

Methods for Underdetermined systems

11/22/2006

(11)

Problem: Given $F: \mathbb{R}^{\bar{n}} \rightarrow \mathbb{R}^n$

find $\bar{x}_*$ such that $F(\bar{x}_*) = 0$

Assume $\bar{n} \gg n$

Example: Bratu problem $\left(\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$

$$\Delta u + \lambda e^u = 0 \quad \text{in } D = [0,1] \times [0,1]$$

$$u = 0 \quad \text{on } \partial D$$

$$\lambda \leq 0 \Rightarrow \text{no solution}$$

$$0 < \lambda < \lambda_* \in (6,7) \Rightarrow \text{at least two solutions}$$

$$\lambda = \lambda_* \Rightarrow \text{at least one solution}$$

$$\lambda > \lambda_* \Rightarrow \text{no known solutions}$$

- Discretizing this and treating λ as unknown gives system of n equations ($n = \#$ of grid points) in $n+1$ unknowns (approximate u -values on grid points + λ)
- Might want to trace out whole solution curve with a continuation methods

Another application: Finding periodic solutions

$$\text{suppose have } \begin{cases} y' = \gamma(y) \\ y(0) = x \end{cases} \quad \text{IVP (initial value problem)}$$

- suppose we want periodic solution: $y(x) = x$
- need particular x and t
- denote solution of IVP by $y(t, x)$
- define $F(\bar{x}) = x - y(t, x)$, $\bar{x} = \begin{pmatrix} x \\ t \end{pmatrix}$
- want $\bar{x}_*$ such that $F(\bar{x}_*) = 0$

Back to general problem

Suppose have $\bar{x}$

Reasoning with Newton's method:

want $\bar{s}$ satisfying

$$F(\bar{x}) + F'(\bar{x})\bar{s} = 0$$

If $\bar{u} > u$, this is underdetermined linear system
(assume F' is of full rank u)

$\Rightarrow$ infinitely many solutions (s in range of F')

How to specify $\bar{s}$ uniquely?

- Augmented Jacobian approach
- need $\bar{u} - u$ additional linear conditions
- express these as orthogonality conditions

$$V\bar{s} = 0, \quad V \in \mathbb{R}^{(\bar{u}-u) \times \bar{u}}$$

clearly want $\begin{cases} F'\bar{s} = -F \\ V\bar{s} = 0 \end{cases}$ to have unique solution

i.e. want $\begin{pmatrix} F' \\ V \end{pmatrix} \in \mathbb{R}^{\bar{u} \times \bar{u}}$ nonsingular

Augmented Jacobian method

given $\bar{x}$ and $V \in \mathbb{R}^{(\bar{u}-u) \times \bar{u}}$

until termination, do

$$\text{solve } \begin{pmatrix} F'(\bar{x}) \\ V \end{pmatrix} \bar{s} = \begin{pmatrix} -F(\bar{x}) \\ 0 \end{pmatrix}$$

update $\bar{x} \leftarrow \bar{x} + \bar{s}$

One issue:

want $\begin{pmatrix} F'(x) \\ V \end{pmatrix}$ nonsingular & not ill-conditioned in region of interest

So rows of V should be "sufficiently linearly independent" and scaled to reflect scaling of F' . May be hard to achieve

Another issue:

$$\text{Have } \bar{x}_k = \bar{x}_0 + \sum_{j=0}^{k-1} \bar{s}_j$$

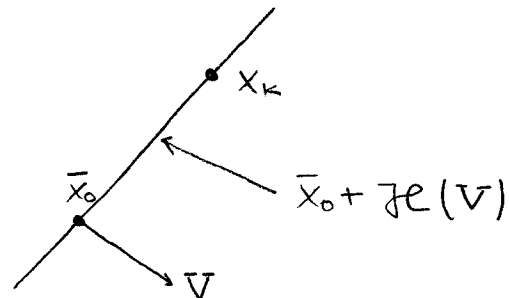
$$\Rightarrow V \bar{x}_k = V \bar{x}_0 + \sum_{j=0}^{k-1} V \bar{s}_j = V \bar{x}_0$$

$$\text{so } \bar{x}_k \in \bar{x}_0 + \mathcal{H}(V) \quad (\text{affine subspace})$$

$$\uparrow \equiv \{ \bar{y} : V \bar{y} = 0 \} \quad (\text{null-space})$$

Team can't possibly find a solution if solution set doesn't intersect $\bar{x}_0 + \mathcal{H}(V)$

Example:



we missed solution entirely

Normal flow approach

$$\text{choose } \bar{s} = -F'(\bar{x})^+ F(\bar{x})$$

where "+" denotes pseudo-inverse

i.e. $\bar{s}$ = minimal norm solution

Assume $\|\cdot\| = \|\cdot\|_2$ for convenience

characterize $\bar{s}$

projection theorem $\Rightarrow$ can write any $\bar{s}$ as

$$\bar{s} = \bar{u} + \bar{t} \quad \text{where } \bar{u} \in \mathcal{H}(F') \equiv \{ \bar{v} : F' \bar{v} = 0 \} \quad \text{and}$$

$$\bar{t} \in \mathcal{H}(F')^\perp \quad (\text{orthogonal complement of null space})$$

Suppose $F' \bar{s}_1 = -F$ and $F' \bar{s}_2 = -F$

$$\Rightarrow F'(\bar{s}_1 - \bar{s}_2) = 0 \Rightarrow \bar{s}_1 - \bar{s}_2 \in \mathcal{H}(F')$$

So have $\bar{s}_1 = \bar{u}_1 + \bar{t}$ and $\bar{s}_2 = \bar{u}_2 + \bar{t}$ for some $\bar{t} \in \mathcal{H}(F')^\perp$

If $\bar{s} = \bar{u} + \bar{t} \in \mathcal{H}(F')$ then $\|\bar{s} + \bar{t}\|^2$

$$\|\bar{s}\|^2 = \|\bar{u} + \bar{t}\|^2 = \|\bar{u}\|^2 + \|\bar{t}\|^2 > \|\bar{t}\|^2$$

$\Rightarrow \bar{t}$ is the pseudo-inverse solution

See: pseudo-inverse solution is:

denote $J = F'$ $\perp$ non-singular since J is full rank

$$\bar{s} = J^T \underbrace{(JJ^T)^{-1}}_{n \times n} (-F)$$

why?

to verify that, show that it is solution and orthogonal to null-space

$$(1) J\bar{s} = JJ^T(JJ^T)^{-1}(-F) = -F \quad \text{so it is solution}$$

$$(2) \bar{u} \in \mathcal{H}(J) \Rightarrow \bar{u}^T \bar{s} = \underbrace{\bar{u}^T J^T}_{(J\bar{u})^T} (JJ^T)^{-1} (-F) = 0$$

$\Rightarrow$ orthogonal to null-space

Normal flow method

given $\bar{x}$

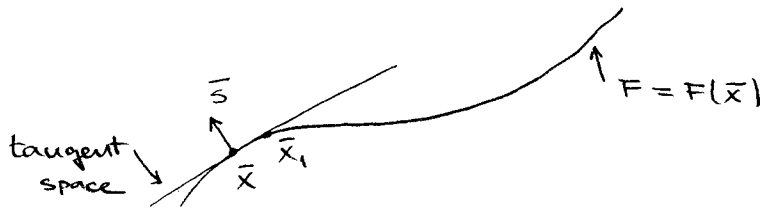
until termination do

compute $\bar{s} = -F'(\bar{x})^\perp F(\bar{x})$

update $\bar{x} \leftarrow \bar{x} + \bar{s}$

See: No "scaling" issue associated with auxiliary orthogonality conditions

- Iterates are not restricted to any affine subspace
- step directions are orthogonal (normal) to surfaces $F = \text{const}$



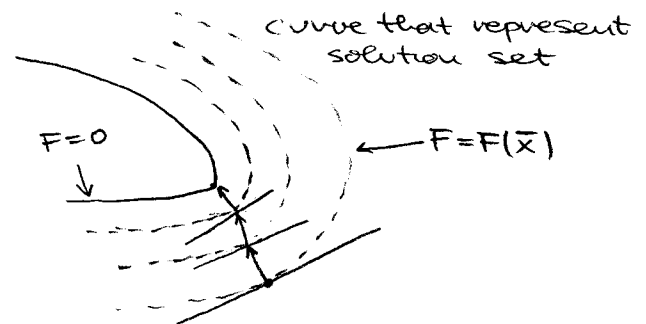
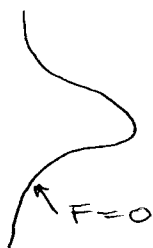
$$\begin{aligned}
 F(\bar{x}_1) &= F(\bar{x}) \\
 &\parallel \\
 F(\bar{x}) + F'(\bar{x})(\bar{x}_1 - \bar{x}) + o(\|\bar{x}_1 - \bar{x}\|) \\
 \Rightarrow F'(\bar{x})(\bar{x}_1 - \bar{x}) &\approx 0
 \end{aligned}$$

see: tangent space of $(\bar{n}-n)$ dimensional surface

$$\begin{aligned}
 \{\bar{y} : F(\bar{y}) = F(\bar{x})\} &\text{ is just } \mathcal{H}(F'(\bar{x})) \\
 &\equiv \{\bar{v} : F'(\bar{x})\bar{v} = 0\}
 \end{aligned}$$

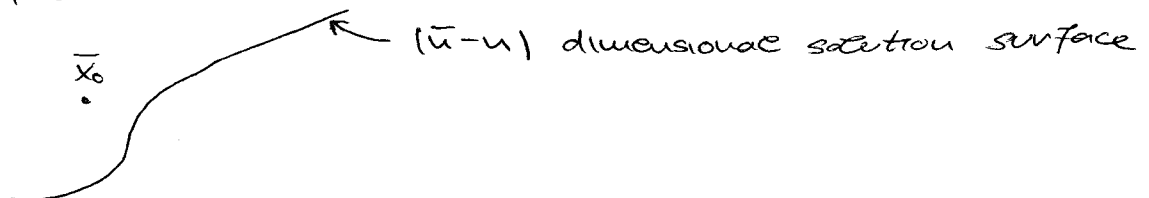
so $\bar{s} = -F'(\bar{x})^+ F(\bar{x})$ is orthogonal to this tangent space

Advantage:



Local convergence analysis

expect



In general solutions are not isolated, so can't predict in advance any solution $\bar{x}_*$ such that $\bar{x}_k \rightarrow \bar{x}_*$

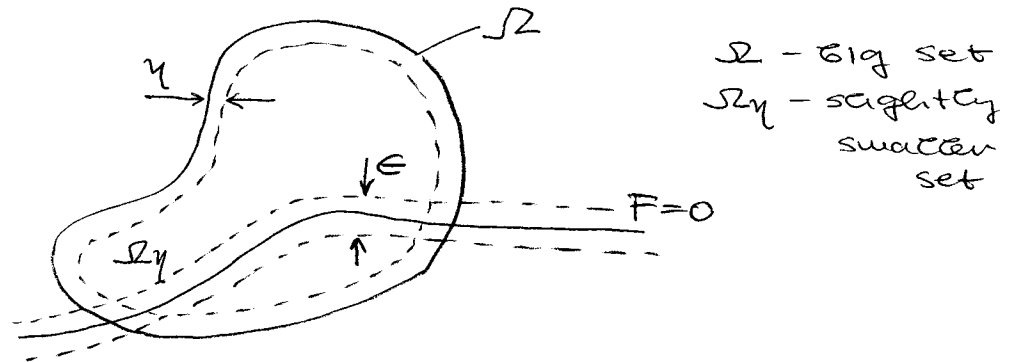
Need Kantorovich - type analysis

Will assume $\|F(x_0)\|$ small, $\|F'(\bar{x})\|$ bounded nearby and F' is Lipschitz nearby

$$\Rightarrow \bar{x}_k = \bar{x}_* \text{ such that } F(\bar{x}_*) = 0$$

From Walter - Watson SIAM 1990

Hypothesis 1



Suppose F is differentiable and rank n in Ω and

$$i) \|F'(\bar{y}) - F'(\bar{x})\| \leq \gamma \|\bar{y} - \bar{x}\| \text{ for } \bar{x}, \bar{y} \in \Omega$$

Lipschitz continuous

$$ii) \|F'(\bar{x})^+\| \leq \mu \text{ for } \bar{x} \in \Omega \text{ (pseudo-inverse is bounded)}$$

For $\eta > 0$ define

$$\Omega_\eta = \{ \bar{x} \in \Omega : \|\bar{y} - \bar{x}\| < \eta \Rightarrow \bar{y} \in \Omega \}$$

Theorem: Suppose Hypothesis 1 holds in Ω and have Ω_η for some $\eta > 0$. Then $\exists \epsilon > 0$ depending only on γ, μ and η such that if $\|F(\bar{x}_0)\| < \epsilon$ then normal flow iterates remain in Ω and converge quadratically to $\bar{x}_* \in \Omega$ such that $F(\bar{x}_*) = 0$

Can apply this to show local convergence of Augmented Jacobian method.

Hypothesis 2: F is differentiable and $\begin{pmatrix} F'(\bar{x}) \\ V \end{pmatrix}$ is nonsingular in Ω and

$$i) \|F'(\bar{y}) - F'(\bar{x})\| \leq \gamma \|\bar{y} - \bar{x}\| \text{ for } \bar{x}, \bar{y} \text{ in } \Omega$$

$$ii) \left\| \begin{pmatrix} F'(\bar{x}) \\ V \end{pmatrix} \right\| \leq \bar{\mu}$$

Theorem: Suppose Hypothesis 2 holds and have Ω_η for some $\eta > 0$. Then $\exists \epsilon > 0$ depending only on $\gamma, \bar{\mu}$ and η . Such that if $\bar{x}_0 \in \Omega_\eta$ and $\|F(\bar{x}_0)\| < \epsilon$. Then augmented Jacobian iterates converge quadratically to $\bar{x}_* \in \Omega$ such that $F(\bar{x}_*) = 0$

proof idea: Define $\bar{F}(\bar{x}) = \begin{pmatrix} F(\bar{x}) \\ V(\bar{x} - \bar{x}_0) \end{pmatrix}$

$$\text{then } \bar{F}'(\bar{x}) = \begin{pmatrix} F'(\bar{x}) \\ V \end{pmatrix}$$

and Augmented Jacobian iterates are just the Newton iterates for $\bar{F}$, which are the normal flow iterates for $\bar{F}$.

Applying previous theorem

$$\text{if } \bar{s} = J^T (J^T J)^{-1} (-F) \text{ and } \bar{u} = u \text{ then}$$

$$\bar{s} = J^T (J^T J)^{-1} J^{-1} (-F) = -J^{-1} F$$

Apply normal flow to find periodic solution of

$$\left. \begin{array}{l} \text{clamped} \\ \text{reed model} \\ \text{(and Rayleigh)} \end{array} \right\} \begin{cases} x'' = ax' + b(x')^3 - kx \\ a=5 \\ b=4 \\ k=5 \end{cases}$$

rewrite as $y' = \varphi(y)$

$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$y_1 = x$$

$$y_2 = x'$$

$$\varphi(y) = \begin{pmatrix} y_2 \\ ay_2 - by_2^3 - ky_1 \end{pmatrix}$$

MATLAB: `periodic (@realfun, (2;2), 3)`
`(3;3), 4`

- How to set up periodic-solution problem as $F(\bar{x}) = 0$ & apply normal flow method.

Denote solution by $y(t, x)$

$$\text{set } F(\bar{x}) = x - y(t, x), \quad \bar{x} = \begin{pmatrix} x \\ t \end{pmatrix} \quad \bar{u} = u+1$$

$$\text{have } F'(\bar{x}) = [F_x, F_t]$$

$$\text{see } F_t = \frac{\partial}{\partial t} (x - y(t, x)) = -\frac{\partial}{\partial t} y(t, x) = -\varphi(y(t, x))$$

$$F_x = I - y_x(t, x), \quad \text{where } y_x = \frac{\partial}{\partial x} y(t, x)$$

$$\text{have } y'(t, x) = \varphi(y(t, x))$$

$$y(0, x) = x$$

$$\Rightarrow \left. \begin{aligned} y'_x(t, x) &= \varphi'(y(t, x)) y_x \\ y_x(0, x) &= I \end{aligned} \right\} \text{ IVP for } y_x$$

So can find $y_x(t, x)$ by integrating this along with IVP for y

$\neq$

$$y' = \varphi(y) \quad \dots \quad n \text{ equations}$$

$$y'_x = \varphi'(y) \cdot y_x \quad \dots \quad n^2 \text{ equations}$$

system gets big very quickly

$\neq$

General remarks on computing $\bar{s} = -F'(\bar{x})^+ F(\bar{x})$

(note: $J = F'(\bar{x})$)

prof Wacker's favourite way (OK if $\bar{u}, u$ not too large)

$$\begin{array}{ccccc} J^T & = & Q & R \\ / & & | & \backslash \\ \bar{u} \times u & & \bar{u} \times u & & u \times u \end{array}$$

want $J\bar{s} = -F$

$$R^T Q^T \bar{s} = -F$$

1) solve $R^T y = -F$

2) set $\bar{s} = Q \cdot y$

Then verify that:

(1) is solution

$$J\bar{s} = R^T \underbrace{Q^T Q}_{I_n} \cdot y = R^T y = -F$$

(2) verify that is min. norm solution $\Leftrightarrow$ orthogonal to null-space of J

$$\bar{\eta} = \mathcal{H}(J) \text{ i.e. } J\bar{u} = 0$$

$$\Rightarrow \bar{u}^T \bar{s} = \bar{u}^T Q \cdot y = (Q^T \bar{u})^T y = \underbrace{(R^T Q^T \bar{u})}_{J \cdot \bar{u}}^T R^{-1} y = 0$$

$\underbrace{J \cdot \bar{u}}_{=0}$

Path following methods

- Suppose have $F(\bar{x}) : \mathbb{R}^{(n+1)} \rightarrow \mathbb{R}^n$
- want to follow curve of solution $F(\bar{x}) = 0$
- usual $\bar{x} = \begin{pmatrix} x \\ \lambda \end{pmatrix}$

example: $\Delta u + \lambda e^u = 0 \quad \text{in } D$
 $u = 0 \quad \text{on } \partial D$

λ "normal" parameter $\Rightarrow$ continuation methods

Also there are "artificial parameter" - homotopy method

Suppose have $G(x) = 0$; $G: \mathbb{R}^n \rightarrow \mathbb{R}^n$
 $\uparrow$
hard

given x_0 , solving

$$H(x) = G(x) - G(x_0) = 0$$

Homotopy idea:

$$\text{set } F(x, t) = (1-t)H(x) + tG(x)$$

and follow solution curve

$$F(x, t) = 0, \quad 0 \leq t \leq 1$$

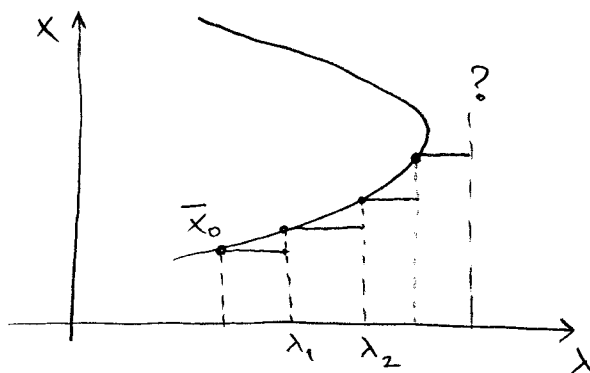
Assume $F'(\bar{x})$ is full-rank u always

First thought: Start with $\bar{x}_0 = \begin{pmatrix} x_0 \\ \lambda_0 \end{pmatrix}$, $F(\bar{x}_0) = 0$

choose $\Delta\lambda$

given $\bar{x}_i$ with $F(\bar{x}_i) = 0$

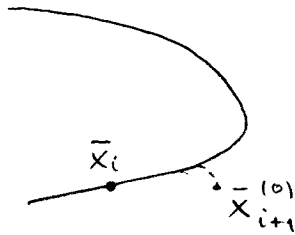
set $\lambda_{i+1} = \lambda_i + \Delta\lambda$ and iterate to solve
 $F(x_{i+1}, \lambda_{i+1}) = 0$



you can't go pass the
turn

Second thought: Given $\bar{x}_i = \begin{pmatrix} x_i \\ \lambda_i \end{pmatrix}$ "predict" $\bar{x}_{i+1}^{(0)}$ and

Iterate to find $\bar{x}_{i+1} \approx$ on curve

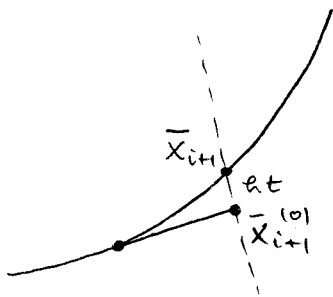


simple predictor/corrector idea

predict $\bar{x}_{i+1} = \bar{x}_i + h \bar{t}_i$

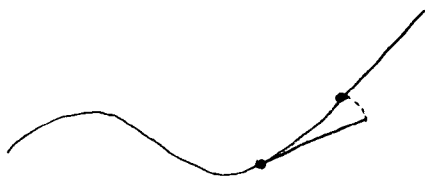
$\bar{t}_i =$ (approximate) tangent

corrector iterations can be either augmented
Jacobian iterations ($\bar{v} = \bar{t}_i^+$) or normal flow iterat.



augmented Jacobian

(at the sharp turn, augmented
Jacobian may not be able to
get to the curve)



normal flow

Note: normal flow may succeed near "turning point"
where augmented Jacobian may fail.

More sophisticated predictor:

Hermit cubic predictor based on $\bar{x}_{i-1}$, $\bar{x}_i$ and
 $\bar{t}_{i-1}$, $\bar{t}_i$

- can either each $\bar{t}_i$ accumulate

or use $\frac{\bar{x}_i - \bar{x}_{i-1}}{\|\bar{x}_i - \bar{x}_{i-1}\|} = \bar{t}_i$