

**A charged particle of velocity  $\vec{v} \perp \vec{B}$  moves in a circle** in a uniform magnetic field

$$F = qvB = \frac{mv^2}{r} = m\omega^2 r$$

The radius of the circle is

$$r = \frac{mv}{|q|B}$$

The angular speed  $\omega$  is known as the cyclotron frequency

$$\frac{v}{r} = \omega = \frac{|q|B}{m}$$

after the cyclotron, a particle accelerator invented by Lawrence in 1932.

**If the velocity  $\vec{v}$  has a component parallel to the magnetic field the particle will move in a helix, a spiral**

$$\vec{B} = B\hat{z}, \quad \vec{v} = \vec{v}_\perp + \vec{v}_\parallel$$

$$\vec{F} = q\vec{v} \times \vec{B} = qv_\perp B(-\hat{r})$$

The parallel component of the velocity does not contribute to the force, but does give the particle a constant drift speed in a direction parallel to the magnetic field.

**We showed in the previous lecture how Thompson applied the above formula** to infer that cathode rays are speedy electrons, and he measured the ratio of charge to mass of the electron

$$qvB = \frac{mv^2}{r}, \quad \rightarrow \frac{e}{m} = \frac{q}{m} = \frac{v}{rB}$$

By creating a uniform field  $B$ , then accelerating the (as yet unidentified) electrons through a known potential  $V$ , the electron speed could be related by the work-energy theorem  $\Delta U = \Delta K$  to the potential

$$eV = \frac{mv^2}{2}, \quad v^2 = \frac{e}{m} 2V, \quad \rightarrow \left(\frac{e}{m}\right)^2 = \left(\frac{1}{rB}\right)^2 v^2 = \left(\frac{1}{rB}\right)^2 \frac{e}{m} 2V, \quad \rightarrow \frac{e}{m} = \left(\frac{1}{rB}\right)^2 2V$$

Thompson measured the deflection of the electron beam (the radius  $r$ ), and computed  $e/m$ .

**A velocity selector subjects a stream of charged particles to uniform electric and magnetic fields** that are oriented in such a way that the forces exerted by the two fields on a charged particle cancel

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}), \quad F_E = qE, \quad F_B = qvB,$$

$$F_E - F_B = 0, \quad qE - qvB = 0, \quad v = \frac{E}{B}$$

for a particular particle speed  $v$ . If the beam consists of particles of various speeds, only those particles having  $v = E/B$  will move along a straight line and pass through the selector; other particles will be deflected away. The resulting beam will then consist of particles moving at the same speed  $v$ .

For example, for positive charge  $q$ , velocity in the  $+x$  direction, electric field in the  $-y$  direction, the magnetic field must point in the  $-z$  direction

$$\vec{v} = v\hat{x}, \quad \vec{E} = -E\hat{y}, \quad \vec{B} = -B\hat{z}$$

Note: sometimes you will see the unit vectors  $\hat{i}, \hat{j}, \hat{k}$  written as  $\hat{x}, \hat{y}, \hat{z}$ , names that are somewhat more descriptive. Do not let it confuse you, they are still the same old familiar unit vectors!

**Working with a velocity selector, Thompson obtained the ratio of electron charge to mass**

$$v^2 = \frac{2eV}{m} = \left(\frac{E}{B}\right)^2, \quad \frac{e}{m} = \frac{1}{2V} \left(\frac{E}{B}\right)^2$$

**A mass spectrometer accepts a beam of particles having the same speed and separates them by mass** by passing the beam through a region of uniform magnetic field  $B'$ .

In this region particles of mass  $m$  move along semi-circular arcs or radius

$$r = \frac{mv}{qB'} = \frac{m}{qB'} \frac{E}{B}, \quad \leftarrow v = \frac{E}{B}$$

Particles of greater mass move along arcs of greater radius. The particles are intercepted by a particle detector. A range of masses  $m_1$  to  $m_2$  is distributed along a particle detector at distances ranging from  $2r_1$  to  $2r_2$  from the beam entrance, forming a "spectrum"

$$r_1 = \frac{m_1 E}{qB' B}, \quad r_2 = \frac{m_2 E}{qB' B}$$

**A magnetic field exerts a force on a current carrying wire.** Consider a uniform magnetic field  $\vec{B}$  pointing into the page, a straight wire laying in the plane of the page, having cross section  $A$  and carrying current  $I$  consisting of particles of charge  $q$  moving with drift speed  $v_d$  along the wire. The force acting on a charge is perpendicular to both the wire and the field

$$F = qv_d B$$

The total free charge  $Q$  in a segment of wire of length  $L$  is

$$Q = qN = qnAL$$

where  $n$  is the number density of free charges.

The total force acting on the segment of wire (for angle  $\theta = 90^\circ$  between velocity and field)

$$F = Qv_d B = (qnAL)v_d B = ILB, \quad \leftarrow I = JA = nqv_d A$$

The more general formula

$$\vec{F} = I\vec{L} \times \vec{B}, \quad d\vec{F} = I d\vec{L} \times \vec{B}, \quad \vec{F} = \int d\vec{F}$$

applies to any angle  $\theta$  between the velocity and field vectors.

For curvilinear wires the differential form  $d\vec{F}$  may be used to sum the force over a length of wire. It may also be used to approximate the field created by a short segment  $\Delta\vec{L}$  of a curved wire

$$\Delta\vec{F} \cong I \Delta\vec{L} \times \vec{B}$$

**A rectangular current loop that rotates about an axis experiences no net force when placed in a uniform magnetic field, but does experience a torque.** This loop forms the “rotor” of a simple electric motor. In Y&F figure 27.31 page 936, forces on opposite sides of the loop are equal and opposite so that the sum of forces is zero.

When the loop faces a direction at an angle  $\varphi$  from the direction of the magnetic field, the torque is

$$\tau = 2F \frac{b}{2} \sin \varphi, \quad F = IaB$$

At  $\theta = 0$  the torque is zero, and at  $\varphi = \pi/2$  the torque is at a maximum.

The loop will experience an angular acceleration, where  $M$  is the moment of inertia of the loop

$$\alpha = \frac{\tau}{M}$$

which will cause the loop to rotate.

When the loop passes through the  $\varphi = 0$  orientation, the angular acceleration will reverse direction (from clockwise to counter-clockwise, etc), and the loop will experience an angular oscillation.

However, if a mechanism is provided to flip the magnetic field as the loop passes through  $\varphi = 0$ , the acceleration will always act in the same direction (in this case, clockwise).

In this case the loop will accelerate up to a maximum angular speed determined when external forces (such as friction or workload forces) compete with the torque to produce equilibrium.