

Solution to Homework 3

MA502 Linear Algebra

Problem 1.

An $n \times n$ matrix A with entries from field \mathbb{F} is diagonalizable over \mathbb{F} if there exists an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$.

- (a) Prove that A is diagonalizable over field \mathbb{F} if and only if $V = \mathbb{F}^n$ admits a basis each vector of which is an eigenvector for A .

Proof.

(\Rightarrow): Suppose A is diagonalizable, then there exists an invertible P and a diagonal D such that $A = PDP^{-1}$. Write $P = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n]$, where \mathbf{p}_i is i^{th} column vector of P . Meanwhile, we can write $D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$. Then, we have $AP = PD$,

which we may write

$$A [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n] = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}.$$

Extracting the i^{th} column of both sides of this equation, we find $A\mathbf{p}_i = \lambda_i\mathbf{p}_i$ (where λ_i could equal λ_j for $i \neq j$.) This means that each \mathbf{p}_i (obviously non-zero since P is invertible) is an eigenvector for A with corresponding eigenvalue λ_i . Meanwhile, since P is invertible, then $\text{rank}(P) = n$. Hence its set of columns $\{\mathbf{p}_i\}_{i=1}^n$ form a basis of eigenvectors for \mathbb{F}^n .

(\Leftarrow): Suppose we have a basis $\mathcal{B} = \{\mathbf{p}_1, \dots, \mathbf{p}_n\}$ for \mathbb{F}^n consisting entirely of eigenvectors for A . Then there exist scalars (eigenvalues) $\lambda_1, \dots, \lambda_n$ in \mathbb{F} such that $A\mathbf{p}_j = \lambda_j\mathbf{p}_j$ for $1 \leq j \leq n$. Stacking the n vectors \mathbf{p}_j together as columns of a square matrix P , we get

$$\begin{aligned} A \begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n \end{bmatrix} &= \begin{bmatrix} \lambda_1\mathbf{p}_1 & \lambda_2\mathbf{p}_2 & \cdots & \lambda_n\mathbf{p}_n \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \end{aligned}$$

Since $\{\mathbf{p}_1, \dots, \mathbf{p}_n\}$ is a basis, the $n \times n$ matrix $P = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_n]$ is invertible. Defining D to be the diagonal matrix with (j, j) -entry λ_j , we have $AP = PD$. Hence, $A = PDP^{-1}$, and A is diagonalizable. \square

- (b) Prove: If A is diagonalizable, then $\text{tr}(A)$ is the sum of all eigenvalues of A , counting multiplicities.

Proof. Since A is diagonalizable, then there exists invertible P and diagonal D such that $A = PDP^{-1}$. We find

$$\text{tr}(A) = \text{tr}(PDP^{-1}) = \text{tr}(P^{-1}PD) = \text{tr}(D)$$

using the fact that $\text{tr}(MN) = \text{tr}(NM)$. Suppose $D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$, where the scalars λ_j are the eigenvalues of A by the construction above, counting multiplicities. Hence, $\text{tr}(A) = \lambda_1 + \lambda_2 + \cdots + \lambda_n$. \square

Problem 2. We compute the spectral decomposition of the matrix $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$.

- (a) Find an orthonormal basis for the eigenspace belonging to eigenvalue $\lambda = 1$.

Proof. When $\lambda = 1$, $A - \lambda I = \begin{bmatrix} -1 & 1 & 1 \\ 1 & -1 & -1 \\ 1 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$. This reduced row echelon form allows us to read off a basis for the eigenspace: $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$.

We apply Gram-Schmidt orthogonalization to find

$$\mathbf{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}.$$

Hence, $\{\mathbf{v}_1, \mathbf{v}_2\}$ is an orthonormal basis for the eigenspace associated to $\lambda = 1$. \square

- (b) Find an orthogonal matrix P and a diagonal matrix D such that $A = PDP^{-1}$.

Proof. Since A has trace zero, our remaining eigenvalue must be -2 , and its eigenvector is easily found to be $[-1 \ 1 \ 1]^\top$. Since A is symmetric, this is already orthogonal to our previously-discovered eigenvectors. So we normalize to obtain

$$\mathbf{v}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Then we have $P = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] = \frac{1}{\sqrt{6}} \begin{bmatrix} \sqrt{3} & 1 & -\sqrt{2} \\ 0 & 2 & \sqrt{2} \\ \sqrt{3} & -1 & \sqrt{2} \end{bmatrix}$, $D = \begin{bmatrix} 1 & & \\ & 1 & \\ & & -2 \end{bmatrix}$, and $A = PDP^{-1}$. \square

- (c) Compute the orthogonal projection matrix E_λ from \mathbb{R}^3 onto the eigenspace V_λ for each eigenvalue λ of A and compute $\sum_\lambda \lambda E_\lambda$. Explain.

Proof. Based on the construction above, we have P^\top as orthogonal matrix, which means $P^{-1} = P^\top$.

$$\begin{aligned}
 A &= [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] \begin{bmatrix} 1 & & \\ & 1 & \\ & & -2 \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{v}_3^\top \end{bmatrix} \\
 &= [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] \begin{bmatrix} 1 & & \\ & 1 & \\ & & 0 \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{v}_3^\top \end{bmatrix} + [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] \begin{bmatrix} 0 & & \\ & 0 & \\ & & -2 \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{v}_3^\top \end{bmatrix} \\
 &= [\mathbf{v}_1 \ \mathbf{v}_2 \ 0] \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ 0 \end{bmatrix} + (-2) \cdot [0 \ 0 \ \mathbf{v}_3] \begin{bmatrix} 0 \\ 0 \\ \mathbf{v}_3^\top \end{bmatrix} \\
 &= 1 \cdot (\mathbf{v}_1 \mathbf{v}_1^\top + \mathbf{v}_2 \mathbf{v}_2^\top) + (-2) \cdot \mathbf{v}_3 \mathbf{v}_3^\top
 \end{aligned} \tag{1}$$

Since $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ are orthonormal basis, we have $\mathbf{v}_1 \mathbf{v}_1^\top + \mathbf{v}_2 \mathbf{v}_2^\top$ and $\mathbf{v}_3 \mathbf{v}_3^\top$ are projection matrices. (The second one is obvious, and the first one is due to $\langle \mathbf{v}_1, \mathbf{v}_2 \rangle = 0$.) For $\lambda = 1$ and $\mu = -2$, the projection matrices are

$$P_\lambda = \frac{1}{3} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}, \quad P_\mu = \frac{1}{3} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix}.$$

\square

- (d) Use part (b) to compute A^9 .

Proof. Since $A = PDP^{-1}$, $A^n = PDP^{-1}PDP^{-1} \dots PDP^{-1} = PD^nP^{-1}$. Clearly the diagonal entries of D^9 are 1, 1, and $(-2)^9 = -512$. So

$$A^9 = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] \begin{bmatrix} 1 & & \\ & 1 & \\ & & -2^9 \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{v}_3^\top \end{bmatrix} = \begin{bmatrix} -170 & 171 & 171 \\ 171 & -170 & -171 \\ 171 & -171 & -170 \end{bmatrix}.$$

(Note that we can also obtain this using part (c): since $A = \lambda P_\lambda + \mu P_\mu$ and $P_\lambda P_\mu = 0$, we have $A^9 = 1^9 P_\lambda + (-2)^9 P_\mu$.) \square

Problem 3.

Consider the vector space $V = \mathcal{C}([0, \pi])$ of real-valued continuous functions on the interval $[0, \pi]$. Any bivariate continuous function $A(x, y)$ determines a linear operator $\tau: V \rightarrow V$ given by

$$\tau f(x) = \int_0^{\pi/2} A(x, y) f(y) dy$$

In this exercise, we study $A(x, y) = \cos(x + y)$.

- (a) Find all eigenfunctions $f(x)$ for τ that lie in the two-dimensional subspace

$$S = \{a \sin x + b \cos x \mid a, b \in \mathbb{R}\}.$$

Proof. For some $f(x) = a \sin x + b \cos x$ in S , we need to find a, b and λ such that $\tau f = \lambda f$. We need

$$\int_0^{\pi/2} \cos(x + y)(a \sin y + b \cos y) dy = \lambda(a \sin x + b \cos x).$$

We immediately see that, since

$$\cos(x + y) = \cos x \cos y - \sin x \sin y,$$

we can simplify the left-hand side to

$$\begin{aligned} \int_0^{\pi/2} \cos(x+y)(a \sin y + b \cos y) dy = \\ -\sin x \left[\int_0^{\pi/2} \sin(y)(a \sin y + b \cos y) dy \right] + \cos x \left[\int_0^{\pi/2} \cos(y)(a \sin y + b \cos y) dy \right]. \end{aligned}$$

(This is called a “separable kernel”: $A(x, y)$ is expressible as a sum of products $p(x)q(y)$.) Since

$$\begin{aligned} \int_0^{\pi/2} \sin(y)(a \sin y + b \cos y) dy &= \frac{1}{4}(2b + \pi a) \\ \int_0^{\pi/2} \cos(y)(a \sin y + b \cos y) dy &= \frac{1}{4}(2a + \pi b) \end{aligned}$$

we must solve the system of equations

$$\left\{ \frac{1}{4}(2b + \pi a) = -\mu a, \quad \frac{1}{4}(2a + \pi b) = \mu b \right\}.$$

For $\mu = \pm \frac{1}{4} \sqrt{\pi^2 - 4}$ (sorry for the typo!), we have eigenvectors (or “eigenfunctions”)

$$f(x) = - \left(\frac{b\mu}{2} \right) \sin x + b \cos x.$$

So we have two distinct eigenvalues and a one-dimensional eigenspace corresponding to each choice of μ . \square

- (b) Consider the subspace W of V spanned by $\{\cos(nx), \sin(nx)\}_{n=1}^{\infty}$. Is W a τ -invariant subspace? Explain.

Proof. We now know, from our trig identity that allowed us to separate $A(x, y)$, that any $f(x)$ which is continuous on $[0, \pi/2]$ gives us $\tau f \in \text{span}\{\sin x, \cos x\}$. So, yes, this space is τ -invariant: for an arbitrary linear combination of basis elements

$$f(x) = \sum_{k=1}^M a_k \sin(n_k x) + b_k \cos(n_k x)$$

we have

$$\tau f(x) = -\sin x \left[\int_0^{\pi/2} \sin(y) f(y) dy \right] + \cos x \left[\int_0^{\pi/2} \cos(y) f(y) dy \right]$$

where the coefficients of $\sin x$ and $\cos x$ are some real constants that we don't care about. So subspace W is τ -invariant (and much more!). \square

Problem 4.

Consider the vector space V spanned by the following complex-valued functions on the interval $[-\pi, \pi]$: $\mathbf{v}_1 = e^z + \cos z$, $\mathbf{v}_2 = e^z + \sin z$, $\mathbf{v}_3 = \sin z$. This space V is invariant under the differential operator $\tau \in \mathcal{L}(V)$ given by $\tau f = \frac{df}{dz}$.

- (a) Compute the matrix $[\tau]_{\mathcal{B}}$ of τ with respect to basis $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

Proof. Since

$$\begin{aligned} \tau \mathbf{v}_1 &= e^z - \sin z = \mathbf{v}_2 - 2\mathbf{v}_3 \\ \tau \mathbf{v}_2 &= e^z + \cos z = \mathbf{v}_1 \\ \tau \mathbf{v}_3 &= \cos z = \mathbf{v}_1 - \mathbf{v}_2 + \mathbf{v}_3 \end{aligned} \tag{2}$$

we have $A = [\tau]_{\mathcal{B}} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ -2 & 0 & 1 \end{bmatrix}$. \square

- (b) Let us write $A = [\tau]_{\mathcal{B}}$. Using a computer, if necessary, find the eigenvalues of τ and determine a basis of eigenfunctions $\mathcal{C} = \{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$. Write down the matrix $[\tau]_{\mathcal{C}}$.

Proof. Eigenvalues for A are $1, \pm i$.

When $\lambda_1 = 1$, we require $\frac{df}{dz} = f$, and hence we choose $\mathbf{w}_1 = e^z$.

For $\lambda_2 = i$, we seek $\frac{df}{dz} = if$, and hence we take $\mathbf{w}_2 = \cos(z) + i \sin(z)$.

For $\lambda_3 = -i$, we need $\frac{df}{dz} = -if$ so we choose $\mathbf{w}_3 = \cos(z) - i \sin(z)$.

So, for $\mathcal{C} = \{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$, $[\tau]_{\mathcal{C}} = \begin{bmatrix} 1 & & \\ & i & \\ & & -i \end{bmatrix}$. \square

- (c) Can you choose an inner product on space V with respect to which operator τ is self-adjoint? Explain.

Proof. No, we cannot have such an inner product. If τ were self-adjoint, then all eigenvalues of τ would be real. However, in part (b), we already find that its eigenvalues include $\pm i$. \square

Problem 5.

- (a) For which $n \times n$ matrices is the minimal polynomial linear? Explain.

Proof. Claim: A should be in the form of λI ($\lambda \in \mathbb{C}$, $\lambda \neq 0$)

We know the minimal polynomial is a monic polynomial of lowest degree which, when evaluated at A , gives the zero matrix. If $m_A(t) = t - c_0$ is the minimal polynomial for A , then

$$A - c_0I = 0$$

or $A = c_0I$. So A is just a non-zero scalar multiple of the identity matrix. \square

- (b) Find a 3×3 matrix with real entries which is not diagonalizable yet whose minimal polynomial is quadratic.

Proof. From our knowledge of generalized eigenspaces, we see that A must have just one eigenvalue, if we ignore multiplicities. Let $A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$. Then, we have

$$A^2 = \begin{bmatrix} 4 & 4 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} = 4A - 4I$$

and A has minimal polynomial $m_A(t) = (t - 2)^2$. \square

Problem 6.

Let S be a subspace of \mathbb{R}^n with basis $\mathcal{B} = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ and let U be the $n \times k$ matrix with j^{th} column \mathbf{v}_j . In class, we showed that, when \mathcal{B} is an orthonormal basis, $P = UU^T$ is the matrix representing orthogonal projection of \mathbb{R}^n onto S with respect to the standard basis.

- (a) No longer assume that \mathcal{B} is orthonormal, but that it is just any basis for S . Prove that the projection operator ρ_{S,S^\perp} is represented by the matrix $P = U(U^T U)^{-1}U^T$.

Proof. By direct computation, it is easy to see that $P^2 = P$. So P is idempotent. We need to prove that $\forall \mathbf{v} \in S$, $P\mathbf{v} = \mathbf{v}$, and $\forall \mathbf{v} \in S^\perp$, $P\mathbf{v} = 0$.

Given $\mathbf{v} \in S$, since $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ is a basis, we can write $\mathbf{v} = \sum_{k=1}^n a_k \mathbf{v}_k = U\mathbf{a}$, where $\mathbf{a} = [a_1 \ \dots \ a_k]^\top$. Then,

$$\begin{aligned} P\mathbf{v} &= U(U^\top U)^{-1}U^\top \mathbf{v} \\ &= U(U^\top U)^{-1}U^\top U\mathbf{a} \\ &= U\mathbf{a} = \mathbf{v} \end{aligned} \tag{3}$$

On the other hand, for $\mathbf{w} \in S^\perp$, we have $\mathbf{v}_i^\top \mathbf{w} = 0$ for $1 \leq j \leq k$ so $U^\top \mathbf{w} = 0$. Then

$$P\mathbf{w} = U(U^\top U)^{-1}U^\top \mathbf{w} = 0$$

This proves that P is projection operator ρ_{S,S^\perp} . □

[NOTE: We just assumed that $U^\top U$ is invertible. If not, then there would be a nonzero vector \mathbf{a} with $(U^\top U)\mathbf{a} = 0$. But, as we've just seen $U\mathbf{a}$ is a vector in subspace S and the only vector \mathbf{s} in S which can be orthogonal to every vector in a basis is the zero vector: $U^\top \mathbf{s} = 0$ implies $\mathbf{s} = 0$.]

- (b) Does the matrix $P = UU^\top$ represent $\rho_{S,T}$ for some T ? Explain.

Proof. We show that P is a projection matrix if and only if $U^\top U = I_k$. Indeed, if $\mathbf{s} \in S$, then there is a vector \mathbf{a} of length k with $\mathbf{s} = U\mathbf{a}$. If P is the matrix representing $\rho_{S,T}$, then $P\mathbf{s} = \mathbf{s}$. So $UU^\top U\mathbf{a} = U\mathbf{a}$ for every possible vector \mathbf{a} of length k . We multiply both sides on the left by U^\top to find

$$(U^\top U)(U^\top U)\mathbf{a} = (U^\top U)\mathbf{a}.$$

We just showed that $U^\top U$ is invertible. So we may multiply both sides on the left by its inverse to see that

$$(U^\top U)\mathbf{a} = I\mathbf{a}$$

for every $\mathbf{a} \in \mathbb{R}^k$. Since the two matrices have the same action, they are equal: $U^\top U = I$. □

- (c) Now let V be the real vector space of polynomial functions $c_0 + c_1x + \dots + c_nx_n$ on the interval $[0, 1]$ with inner product $\langle f, g \rangle = \int_0^1 f(x)g(x) dx$ and let S be the space spanned by $\{1, x\}$. Find a simple expression for the orthogonal projection of V onto S with respect to this inner product.

Proof. First, we need to make the basis orthonormal. Hence, by Gram-Schmidt orthogonalization, we have $f_1 = 1$, and

$$\bar{f}_2 = x - \langle 1, x \rangle \cdot 1 = x - \int_0^1 x dx = x - \frac{1}{2}$$

Then normalize \bar{f}_2 to get $f_2 = \sqrt{12}(x - \frac{1}{2})$, and then, for any $g \in V$, our projection is given by

$$P(g) = \langle g, 1 \rangle \cdot 1 + \langle g, f_2 \rangle \cdot f_2$$

□