







Assumes: discrete sampling of continuous spatial



Challenge: virtual (screen) is not reality

Advantage: humans are good at interpreting spatial

Advantage: realism



You contro! lighting, contrast, resolution, density, and other data parameters.

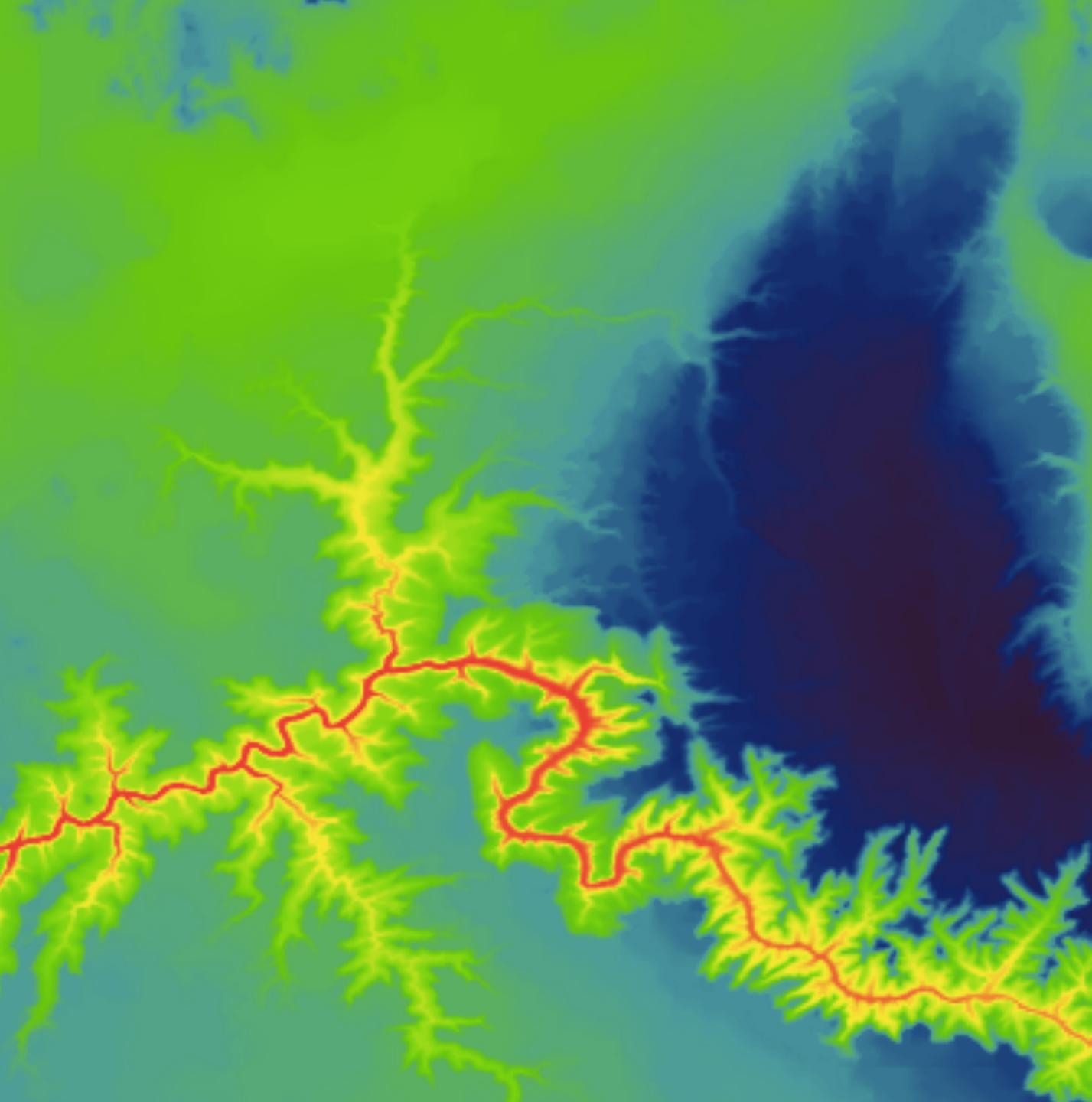
bar, line, heatmap, area

form the basis for SciVis techniques for abstract

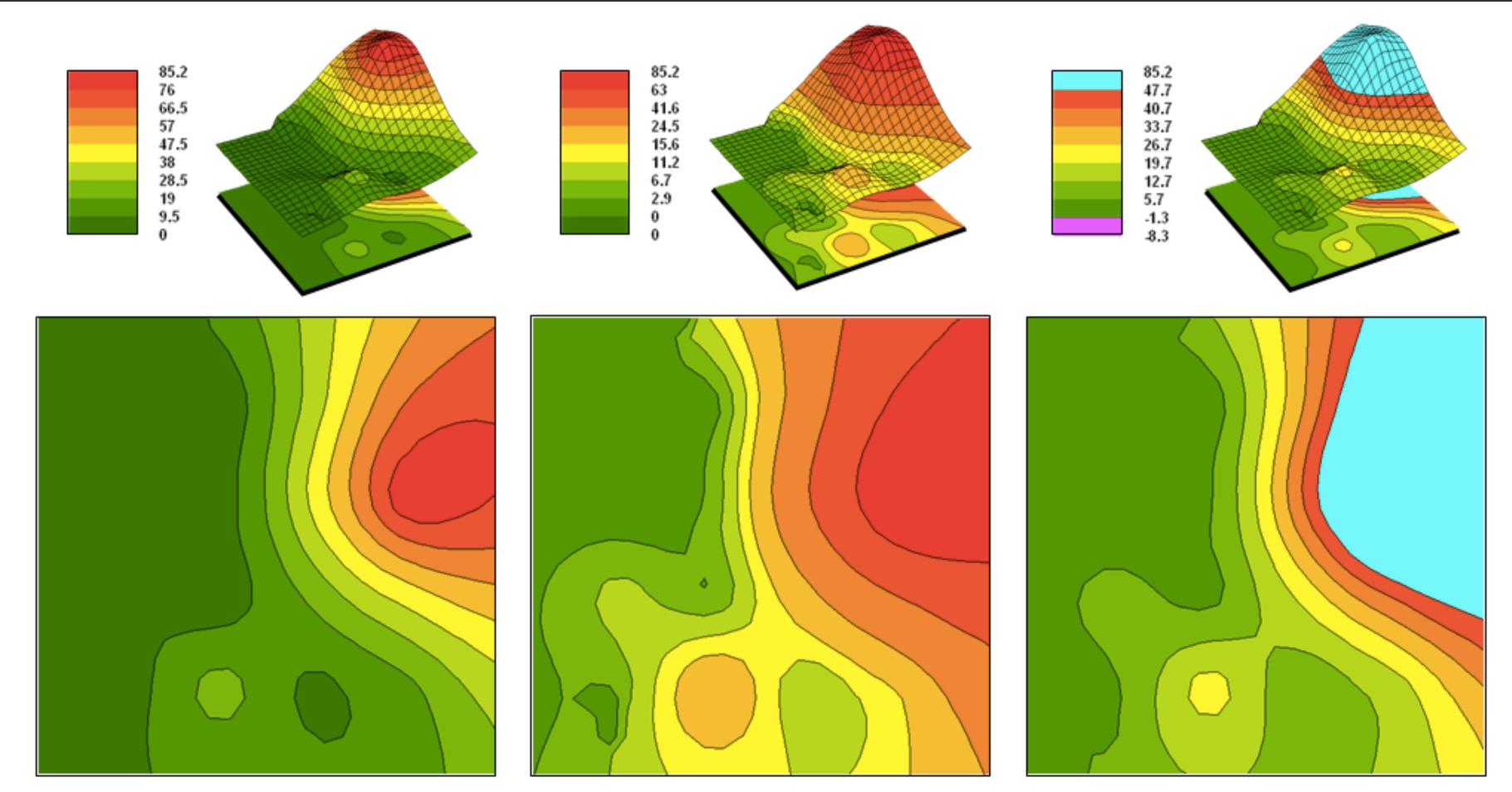
oata







Concept: contours



Equal Ranges

Equal Count

+/-1 Stdev



Continuous

Discrete

Continuous

Discrete

Explicit

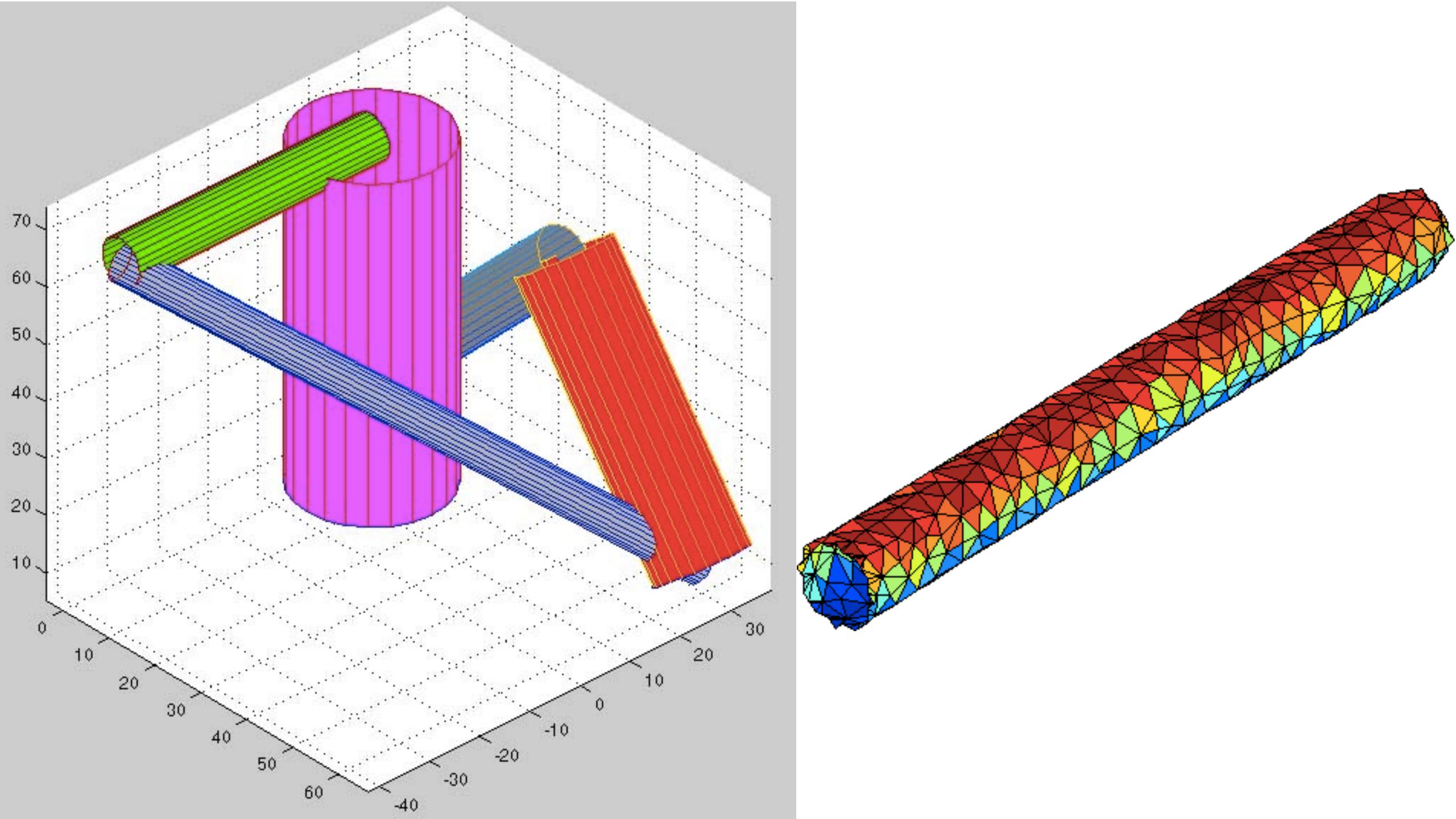


Implicit

Explicit Surfaces

Characteristics: - topology (vertices, ecces bolygons parametric eqs

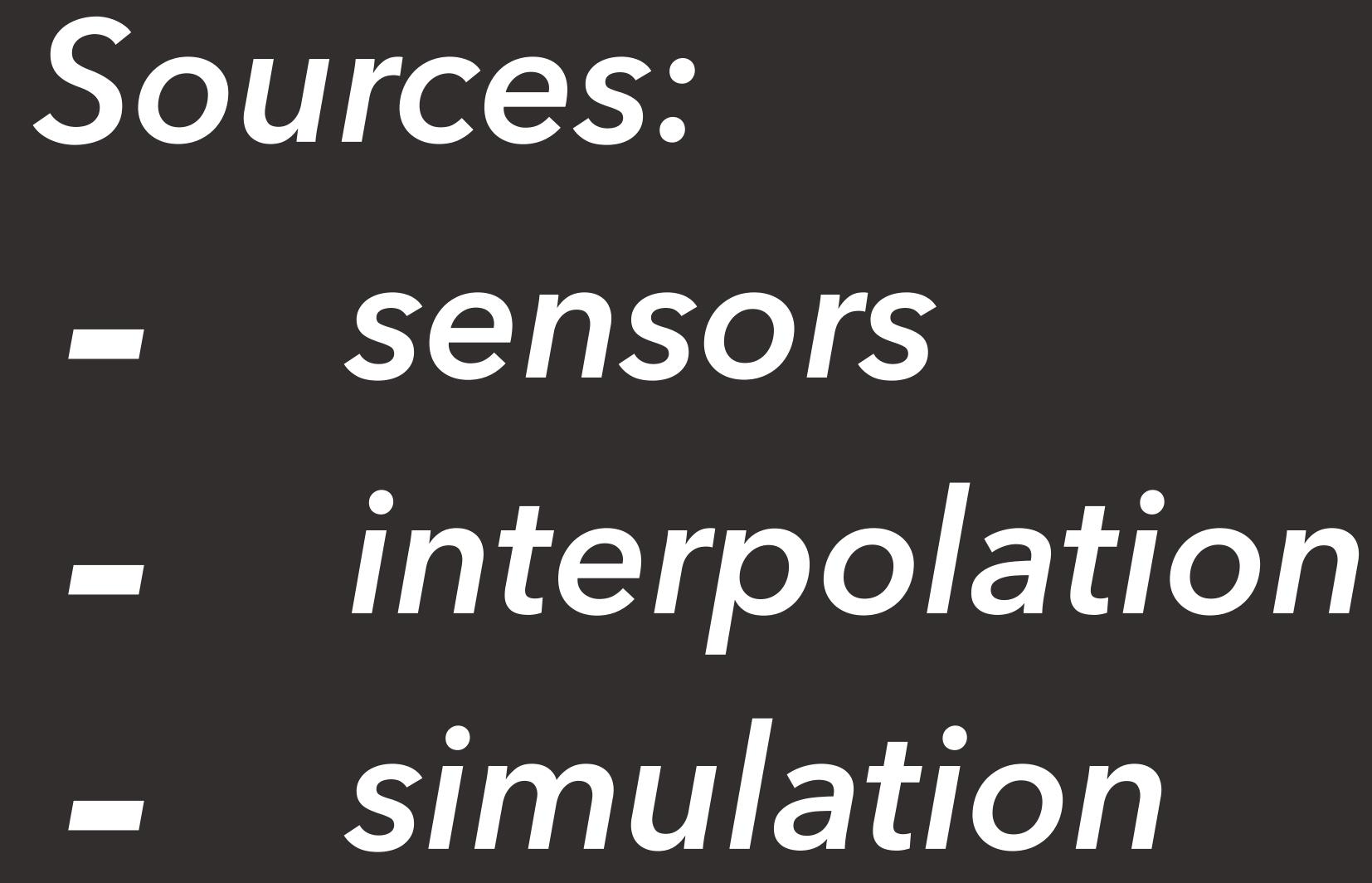




Volume Data

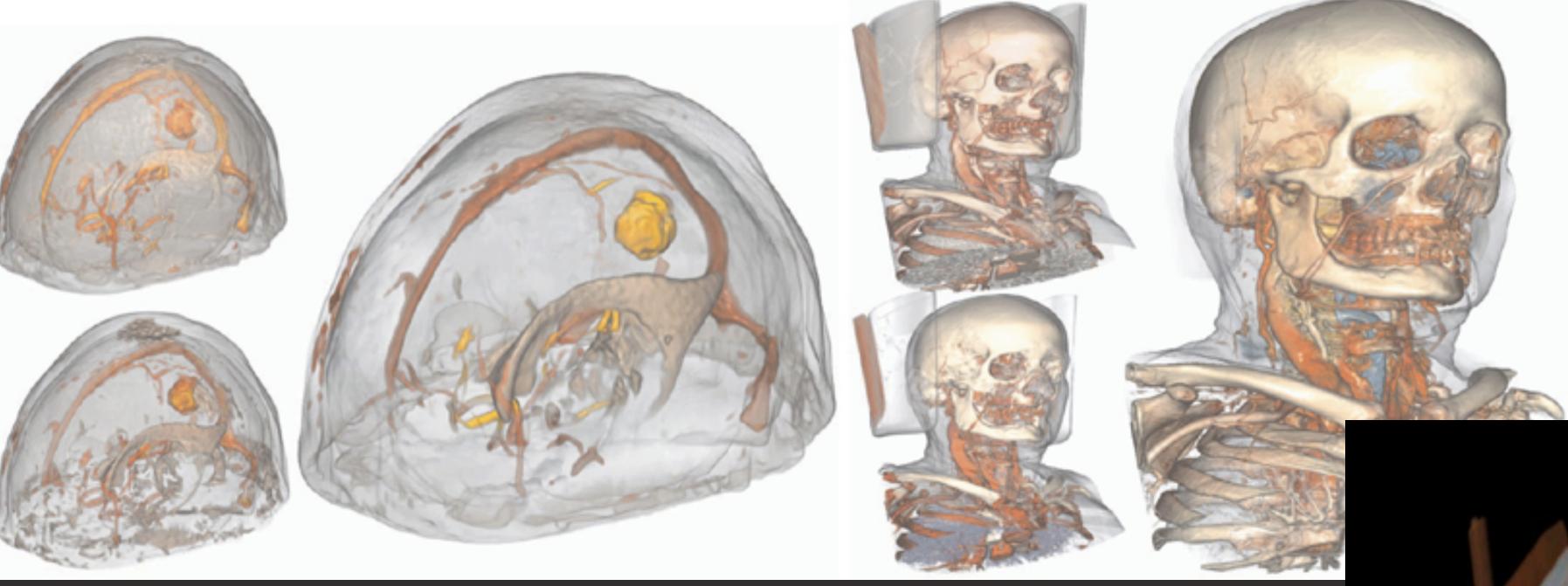
Voxel (3d pixel)

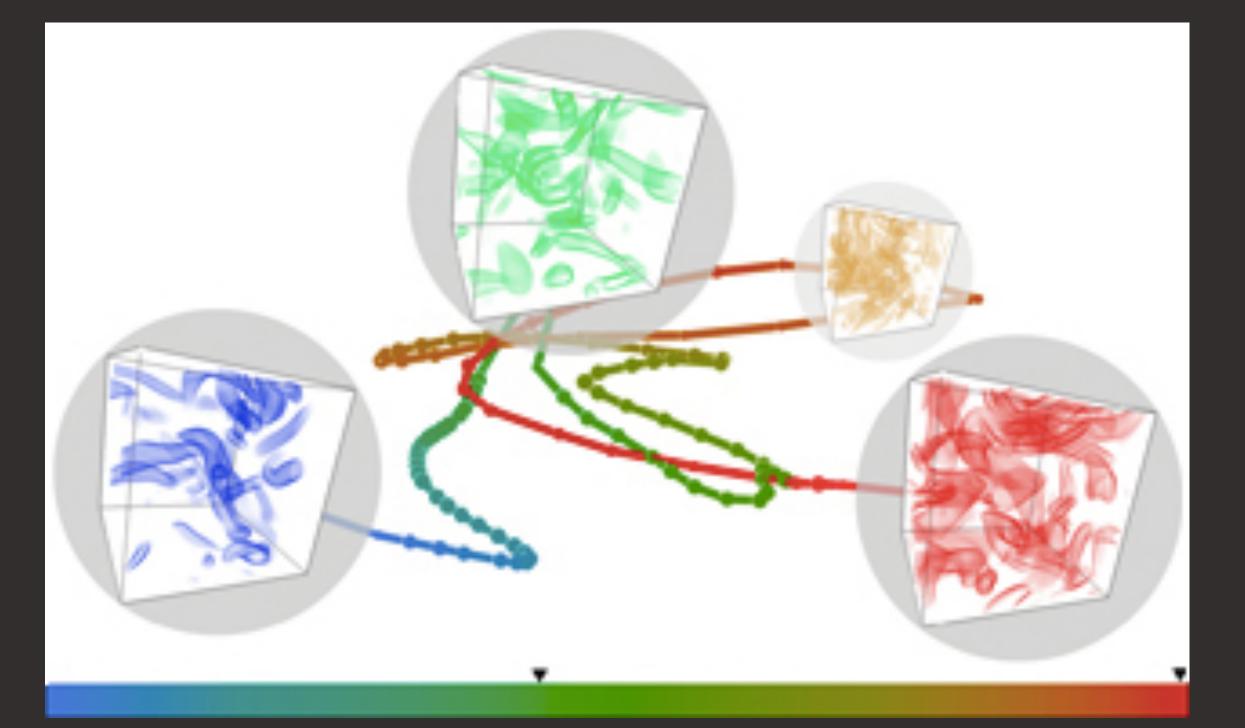




Techniques: - Slicing - Isosurface Direct rendering













Orthogonal

 \mathbf{O}

Arbitrary?

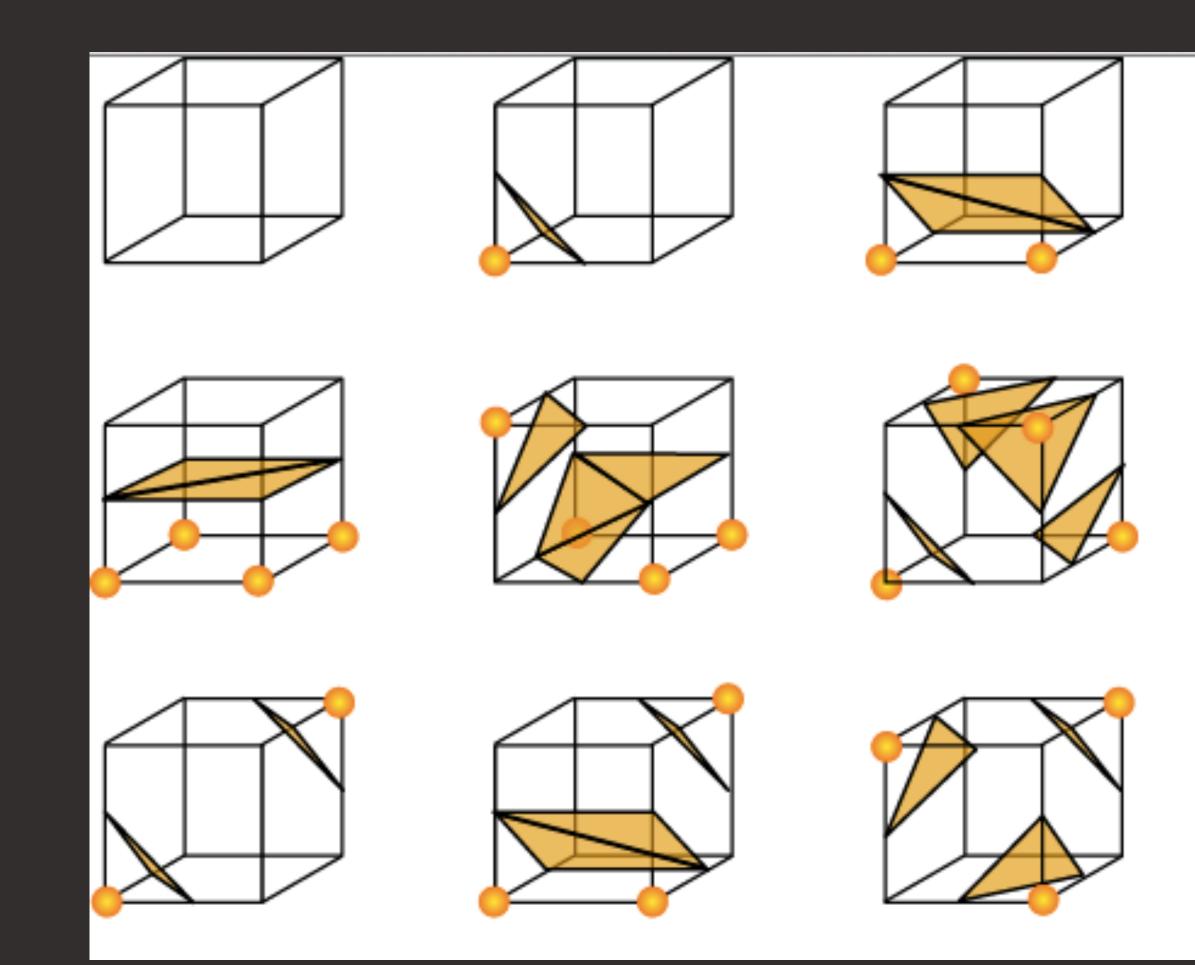


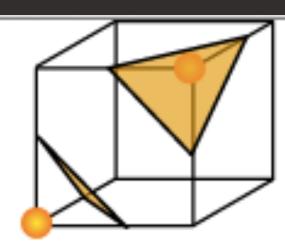


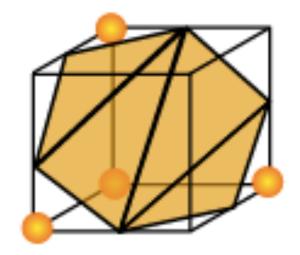
Variations: - non-planar multiple (to remove data)

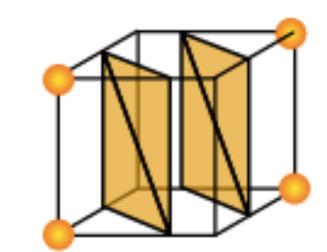
Isosurfaces

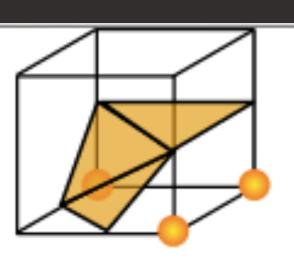


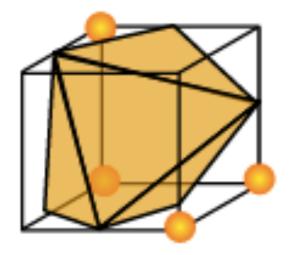


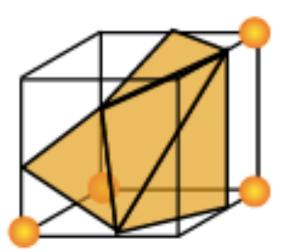












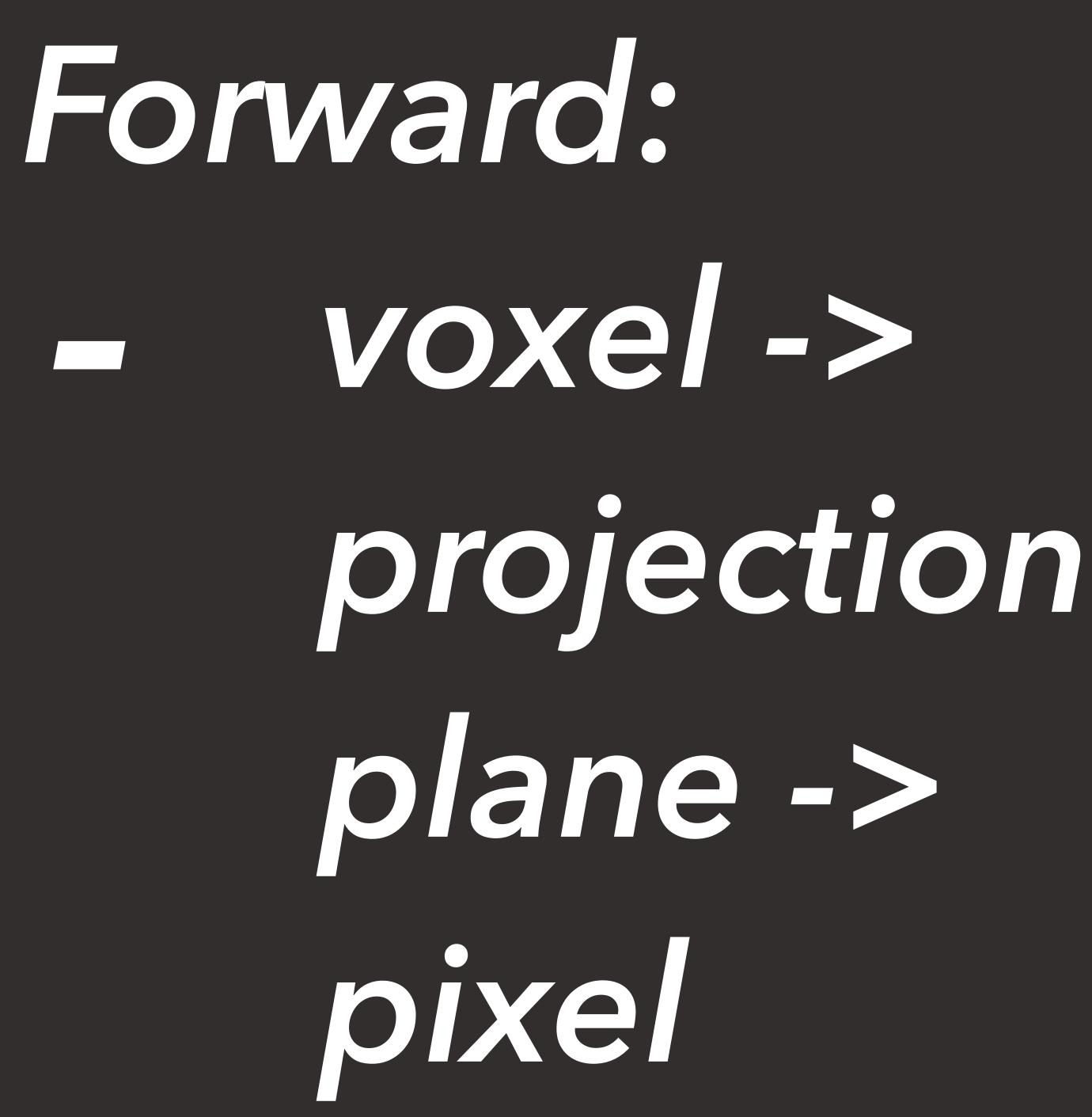
Direct Volume Rendering

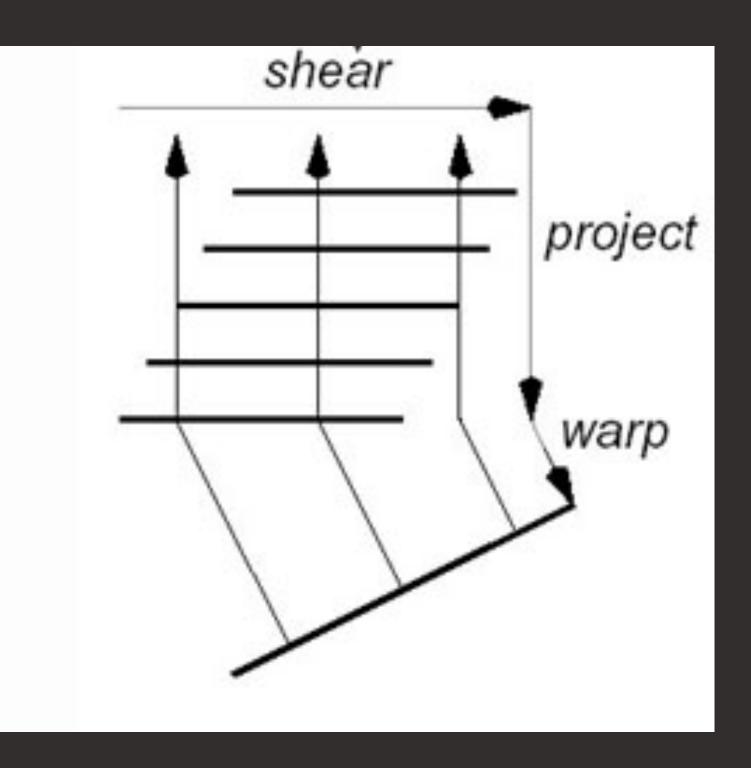
Idea: make views without surfaces

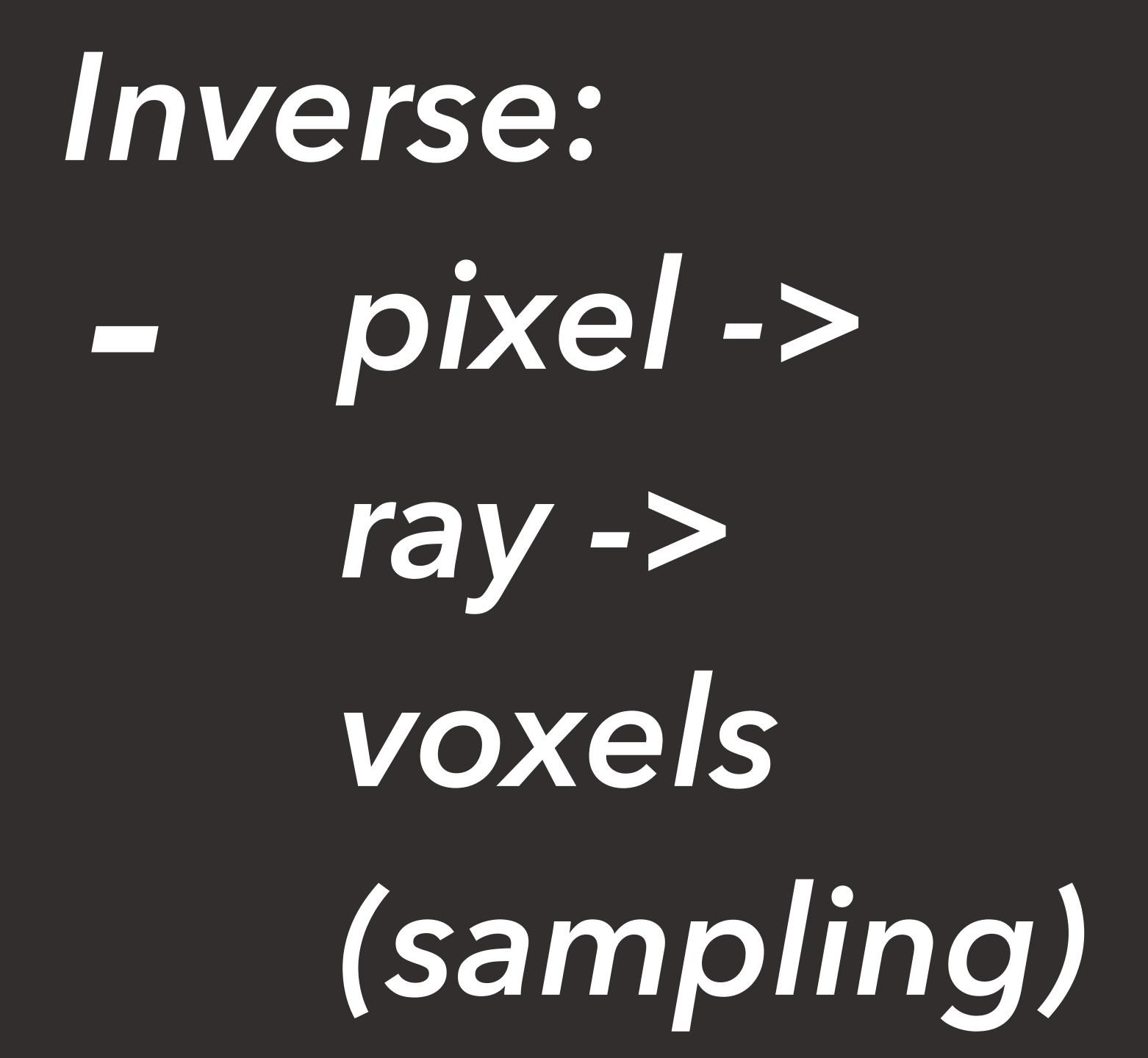
Voxels -> Viewing coordinates

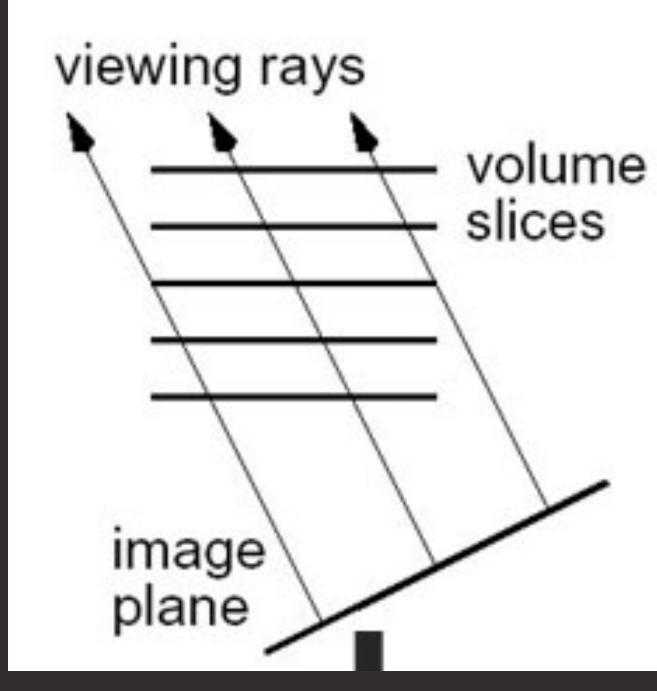


Two approaches: forward mapping inverse mapping





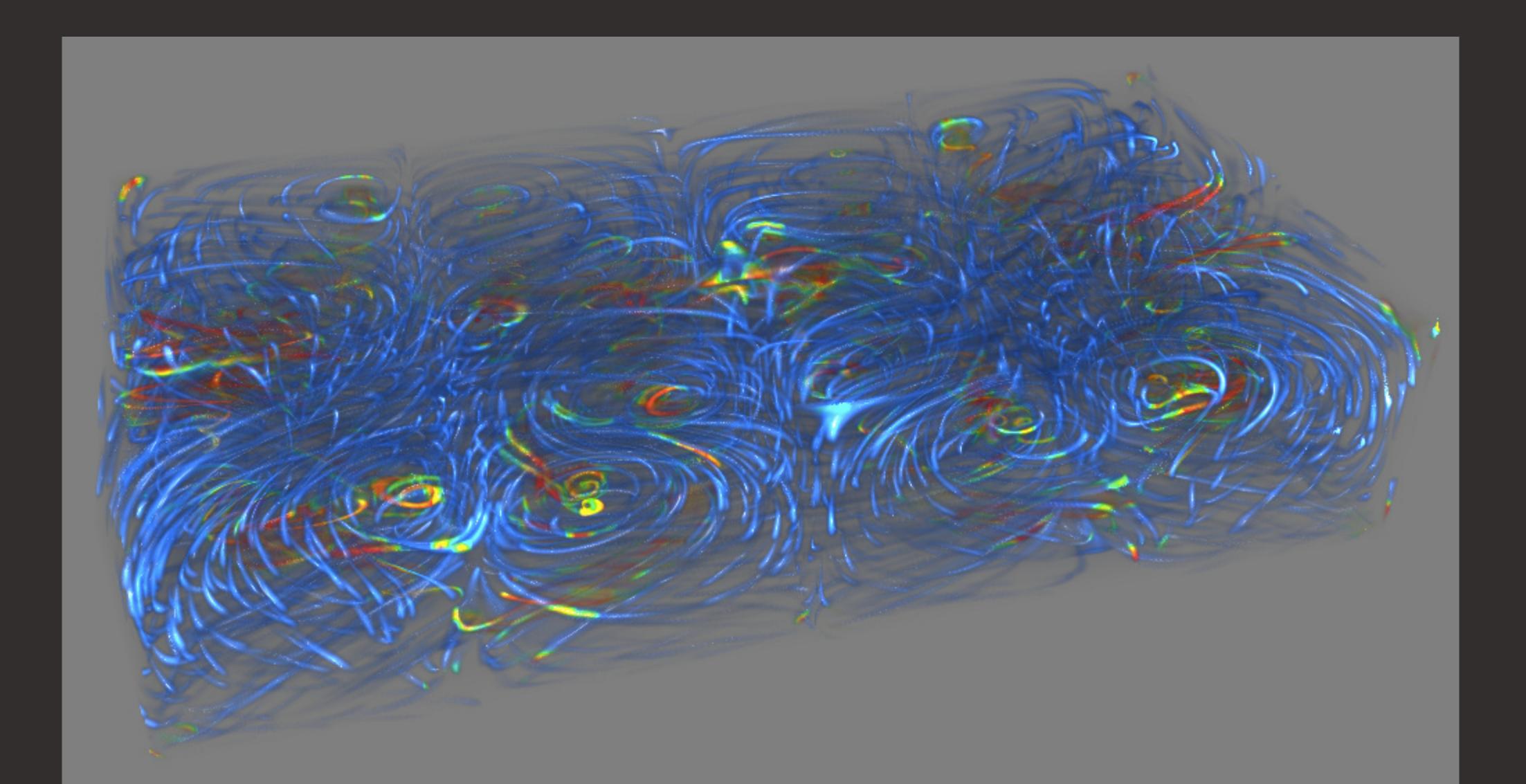




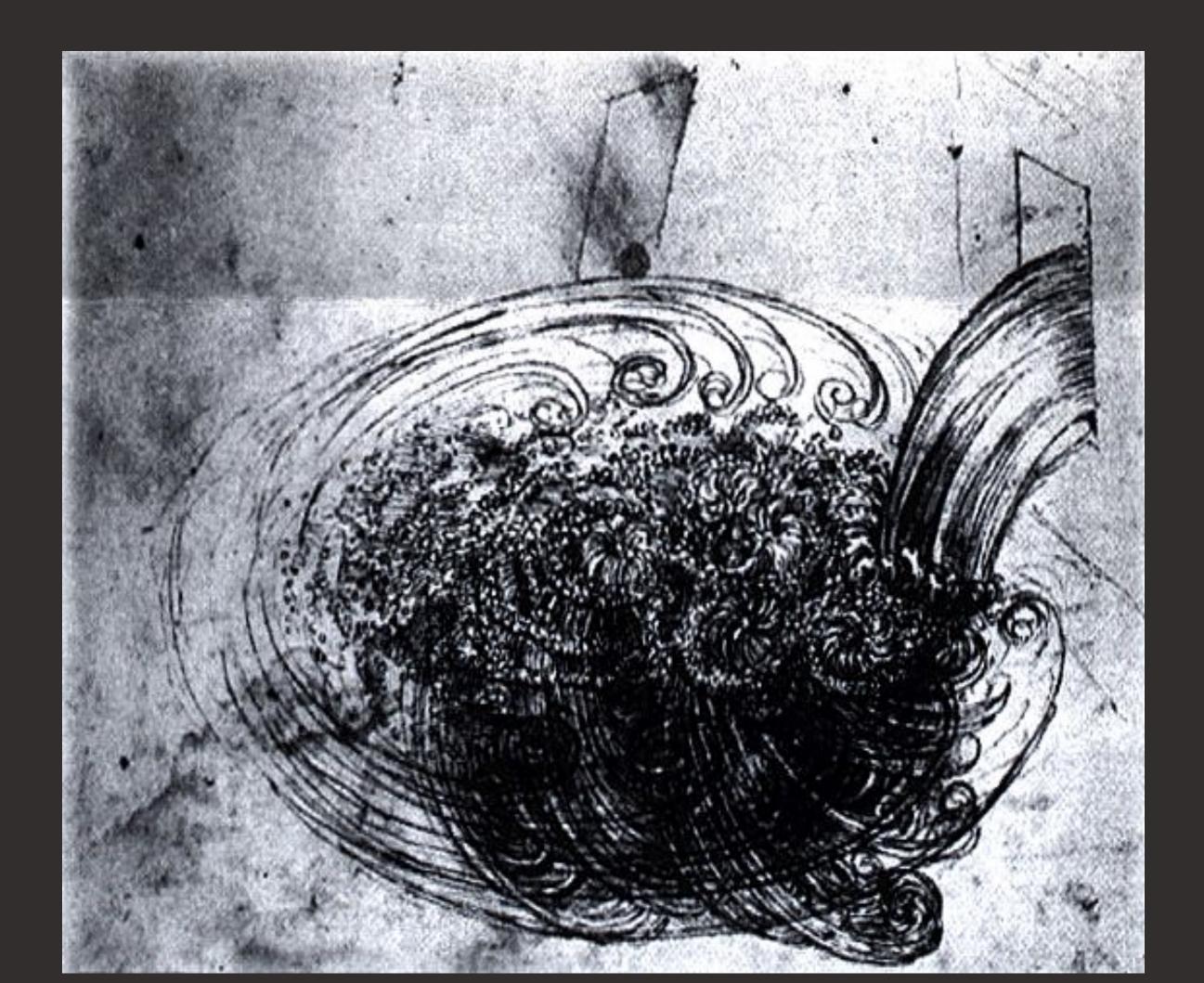




"Flow" vis



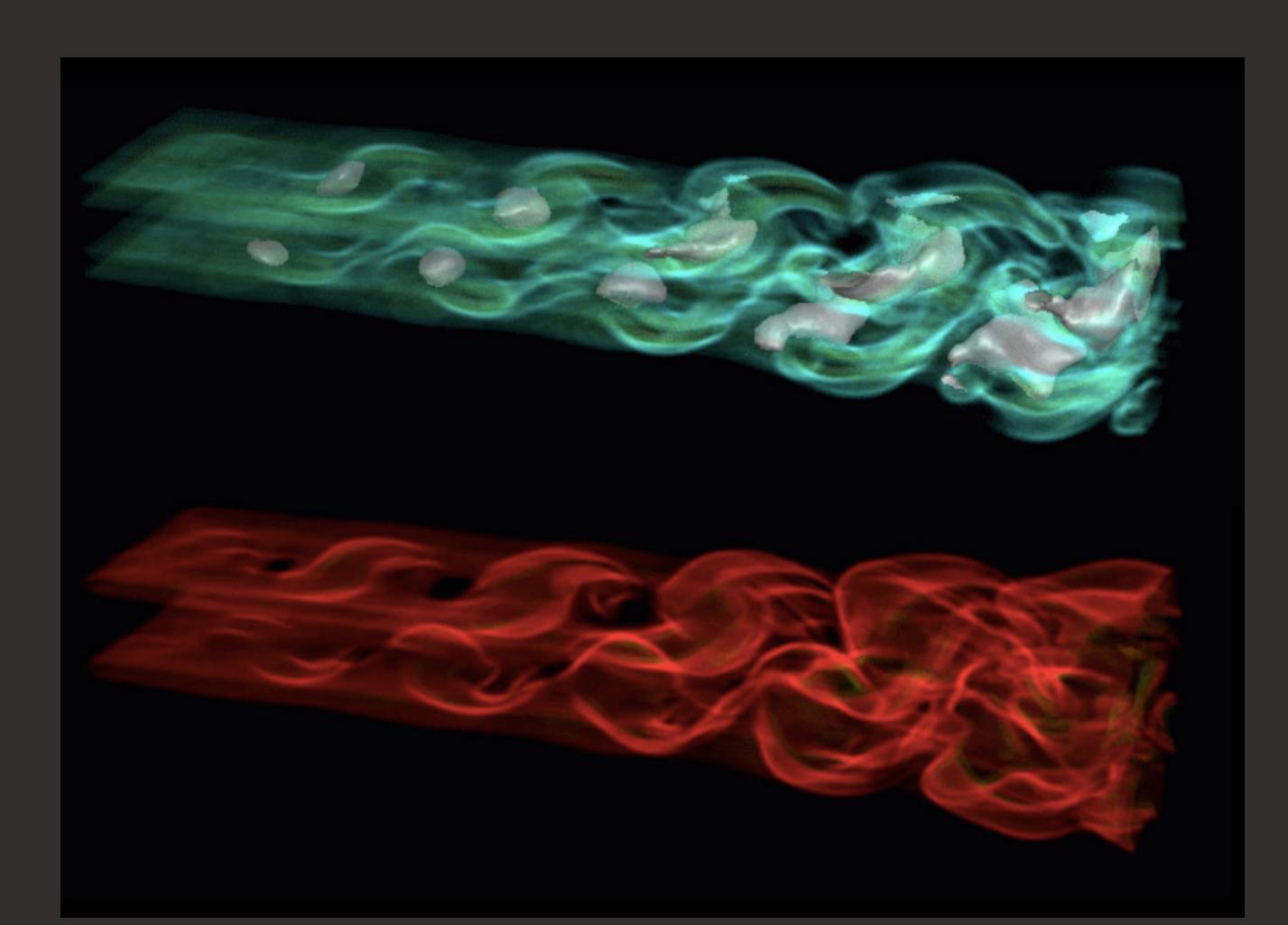
Leonardo da Vinci



Structure: 2d or 3d grid of velocity vectors

Common goals: analyze saddle points, turbulence, vortices

3d + time

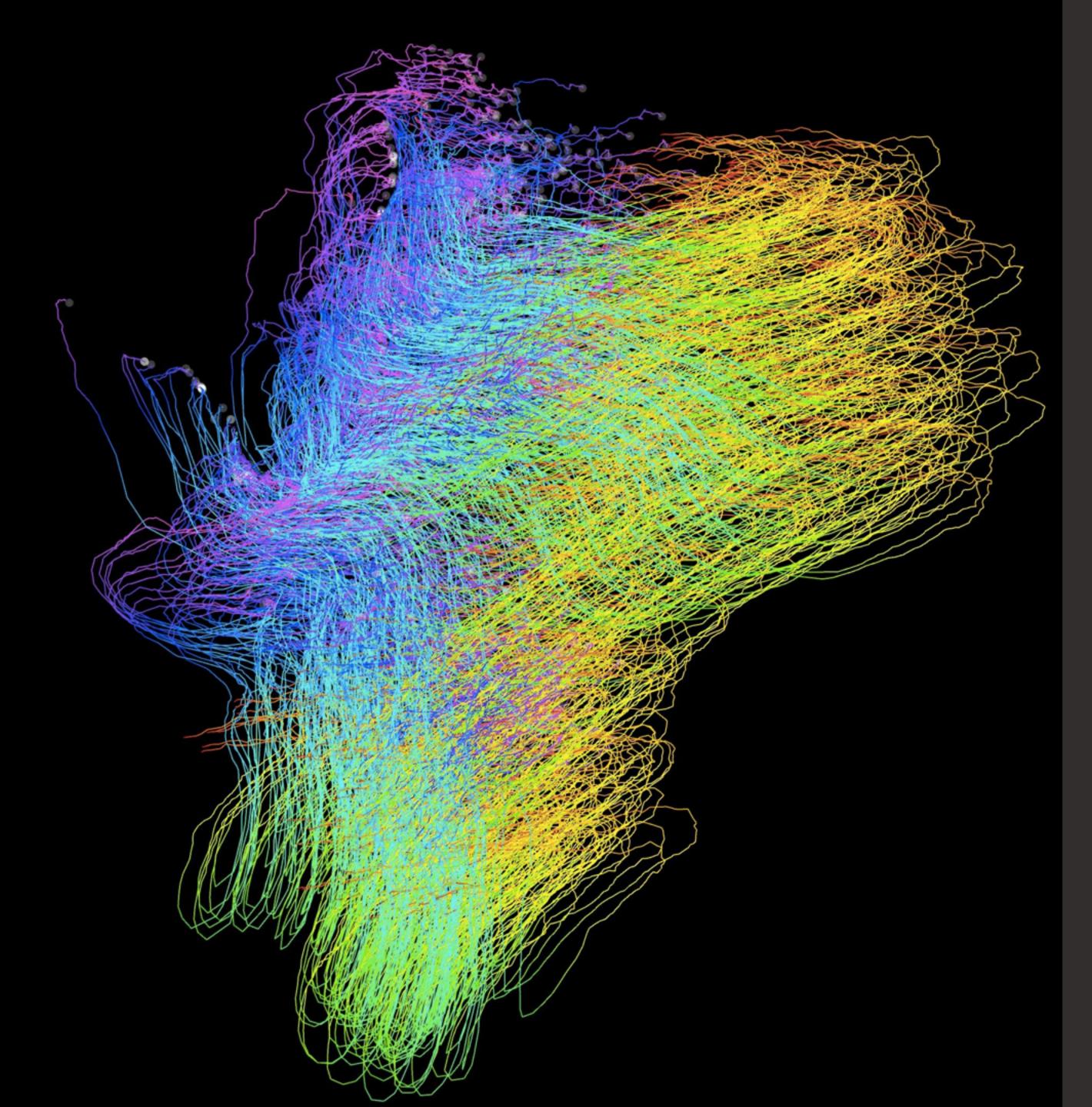


Lines. path-, streak-, stream-,

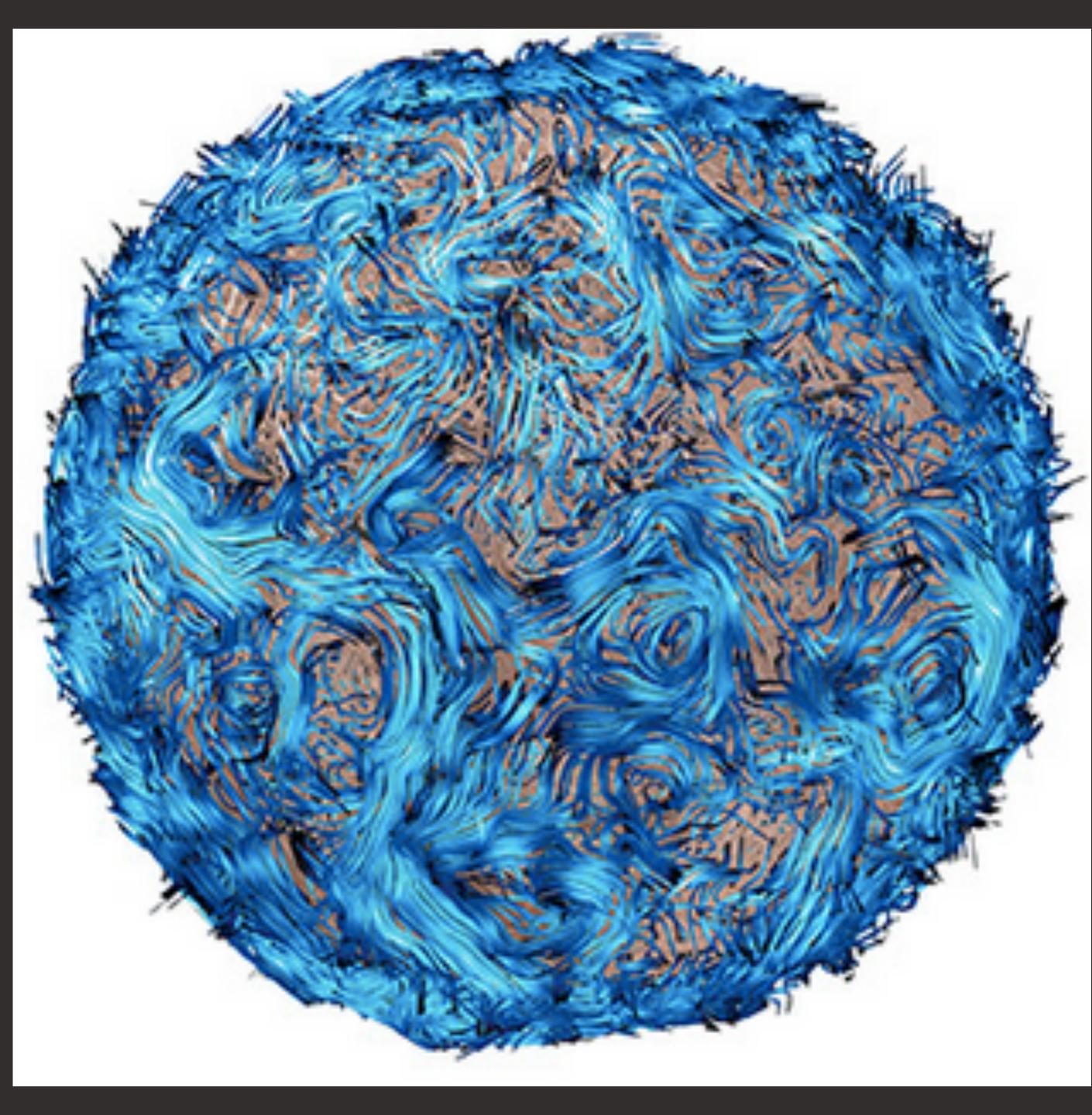




Pathline







Illustrative rendering

dti tracts



time-varying



better than real?



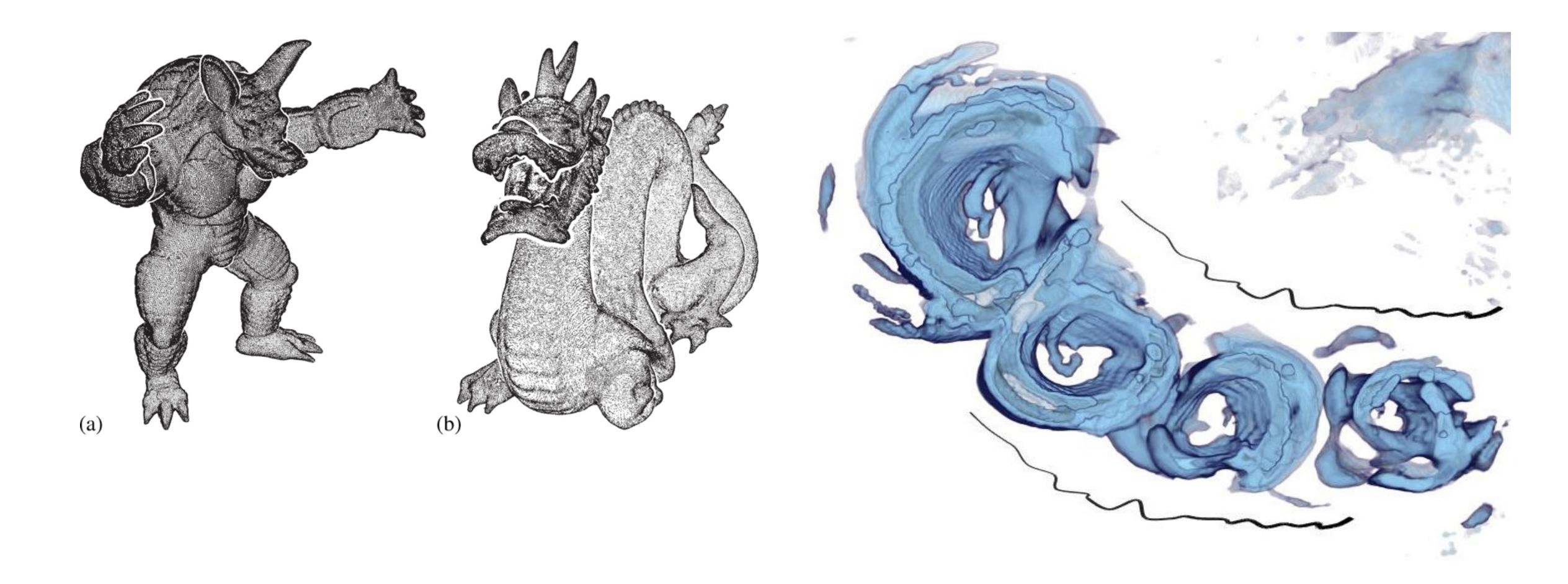


illustration-inspired