

WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

Engineering Experimentation
ME-3901, D'2012

Laboratory #4: Part 1

Vibration measurements with
strain gauges



General information

Office hours

Instructors: **Cosme Furlong**

Office: HL-151

Everyday:

9:00 to 9:50 am

Christopher Scarpino

Office: HL-153

During laboratory

sessions

Teaching Assistants: **During laboratory sessions**



General information

Please refer to laboratory description:
"Laboratory 4: vibration measurements"



Objectives

The objectives of this laboratory are to:

- use different types of motion transducers to measure the natural frequencies, damping characteristics, and elastic modulus of a cantilever

For each motion transducer, vibration data will be analyzed to:

1. Determine the vibration amplitude, velocity, and acceleration in various units of measure;
2. Determine natural frequencies;
3. Measure and express damping characteristics as logarithmic decrement and percentage of critical damping;
4. Compare measurements with analytical and/or computational models of a cantilever;
5. Determine elastic modulus of a cantilever via vibration measurements



Background: cantilevers

Natural frequencies

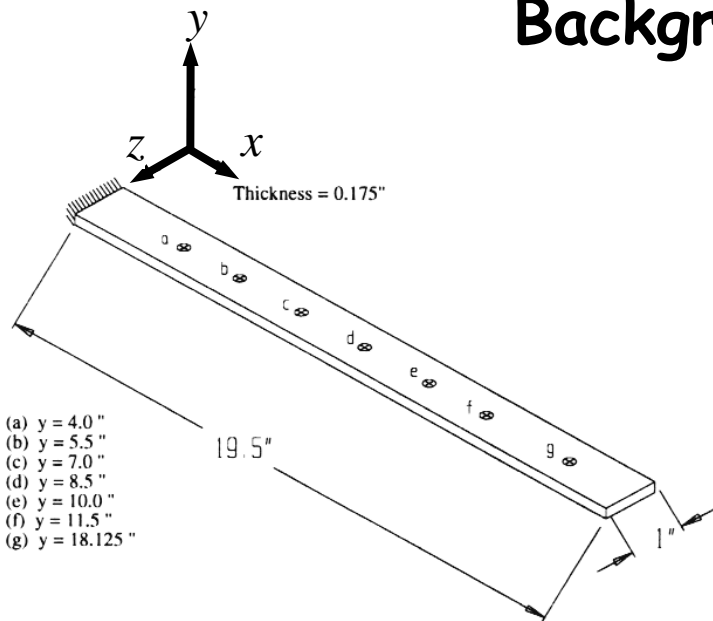


Fig. 3 Low carbon steel beam showing locations of interest

Show demo: modal analysis with FEM

Note: Frequencies can also be expressed as

$$\omega_n = \beta_n \frac{1}{\sqrt{12}} \sqrt{\frac{E}{\rho}} \left(\frac{t}{L^2} \right), \text{ rad/s}$$

$$\text{First: } \omega_n = 3.5160 \sqrt{\frac{EI}{\bar{m}L^4}}, \text{ rad/s} \quad (3)$$

where,

E = Young's modulus = 30×10^6 psi,

I = Moment of inertia of the beam section = 4.46614×10^{-4} in⁴,

\bar{m} = mass per unit of length = 1.26805×10^{-4} lbf·s²/in², and

L = length of the beam = 19.5 in,

$$\text{Second: } \omega_n = 22.0345 \sqrt{\frac{EI}{\bar{m}L^4}}, \quad (4)$$

$$\text{Third: } \omega_n = 61.6972 \sqrt{\frac{EI}{\bar{m}L^4}}, \quad (5)$$

$$\text{Fourth: } \omega_n = 120.0902 \sqrt{\frac{EI}{\bar{m}L^4}}, \quad (6)$$

$$\text{Fifth: } \omega_n = 199.8600 \sqrt{\frac{EI}{\bar{m}L^4}}, \quad (7)$$

$$EI \frac{\partial^4 y}{\partial x^4} + \bar{m} \frac{\partial^2 y}{\partial t^2} = 0. \quad (8)$$

Table 4. Natural Frequencies obtained using Eq. 3 to 7

Natural Frequency	Magnitude, Hz
1	15.1270
2	94.8010
3	265.446
4	516.675
5	859.876



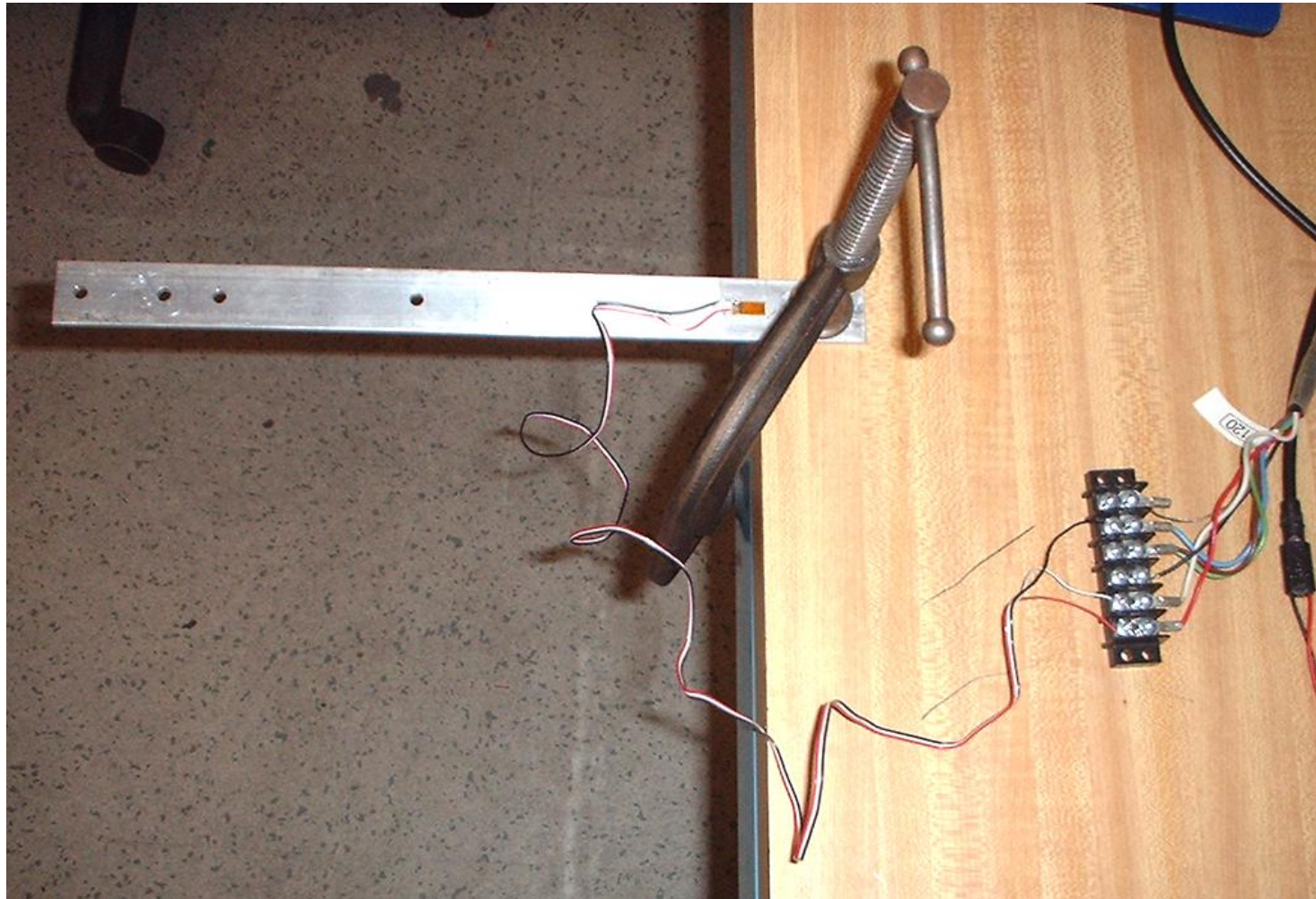
Strain gauges

Tasks

- Derive analytical solutions to determine:
 - a. Stresses and strains of a cantilever subjected to a concentrated load;
 - b. Fundamental natural frequencies and damping factors of a cantilever;
- Using a C-clamp, mount cantilever to the edge of a bench. Attach one strain gauge on the cantilever -- make sure to attach gauge at a location subjected to as much strain level as possible; check your analytical solutions;
- Calculate the necessary output gain for the gauge; use a 10 V bridge excitation; **recommended** filter level is 100; setup an analog input channel to the range of [-2,2] Volts;
- To determine an appropriate output gain consider loading the beam under static situation and with a known load;



Vibration measurements with strain gauges



Strain gauges

Tasks

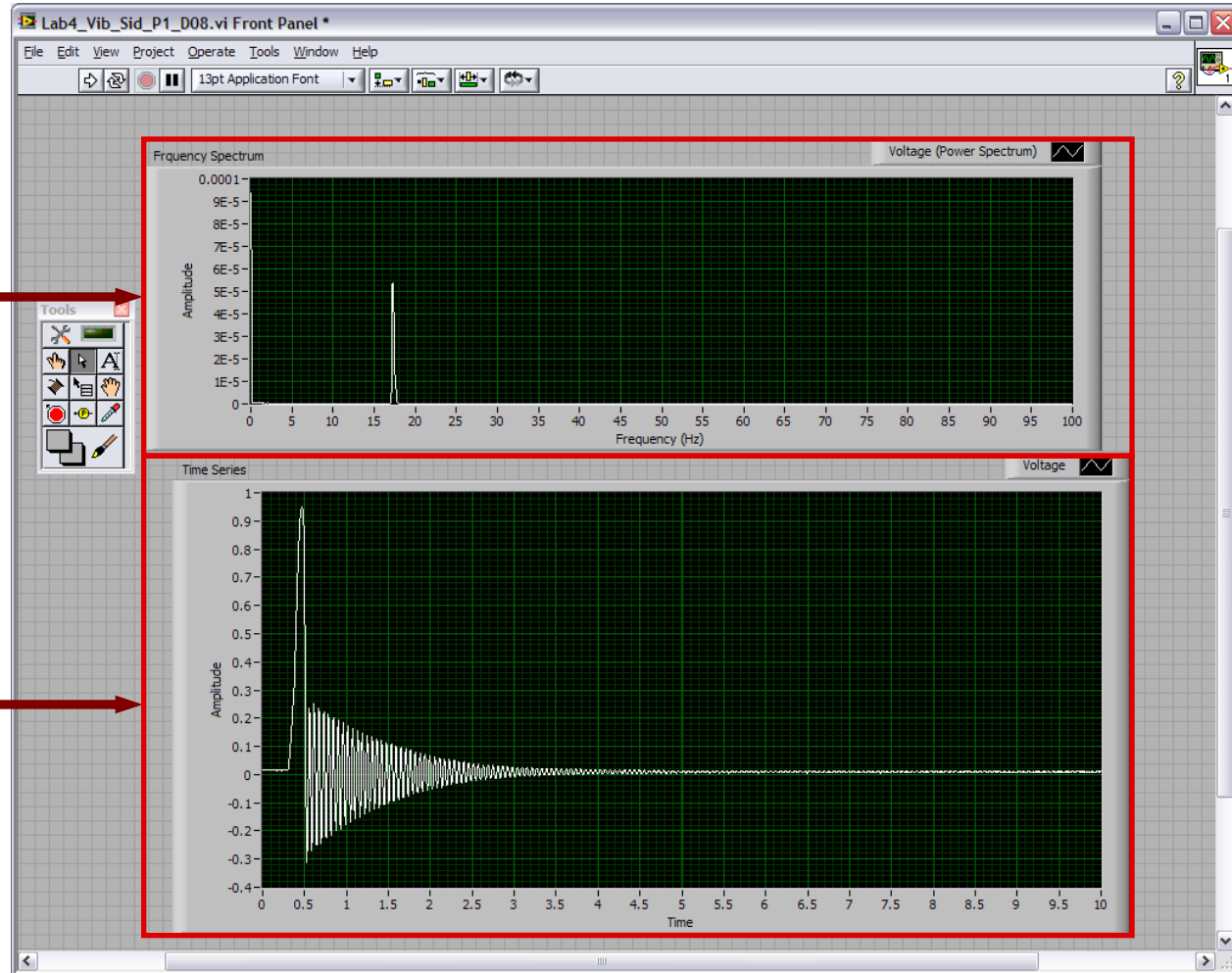
- Use/modify/construct suitable LabView VI(s) to record time & frequency data;
- Pluck the end of the cantilever and record the vibration decay curve;
- Using the recorded data, determine modal parameters (i.e., natural frequencies and damping factors) and elastic modulus of the cantilever;
- Compare your results with analytical/computational models of a cantilever; and
- Do uncertainty analysis on the determined modal parameters and elastic modulus (including % contribution of uncertainties).



Vibration measurements with strain gauges and a VI

Frequency-domain
(Obtained by applying the
"Fast Fourier
Transformation (FFT)" on
the time-domain data)

Time-domain data
(Obtained by
plucking the beam)



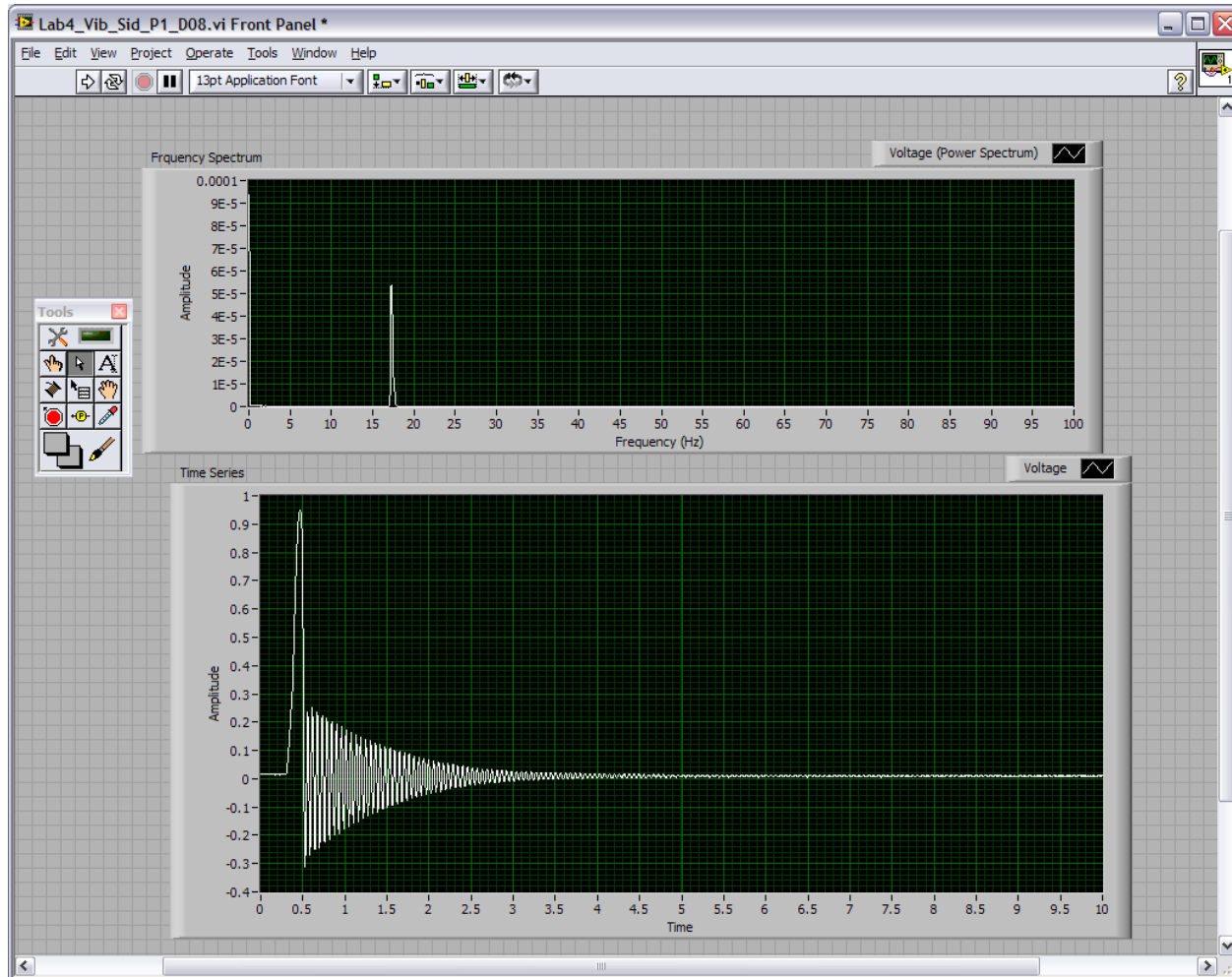
Vibration measurements with strain gauges and a VI

- You can construct a suitable LabView VI (to be shown next); or
- You can use and modify an existing LabView VI (available in our website).



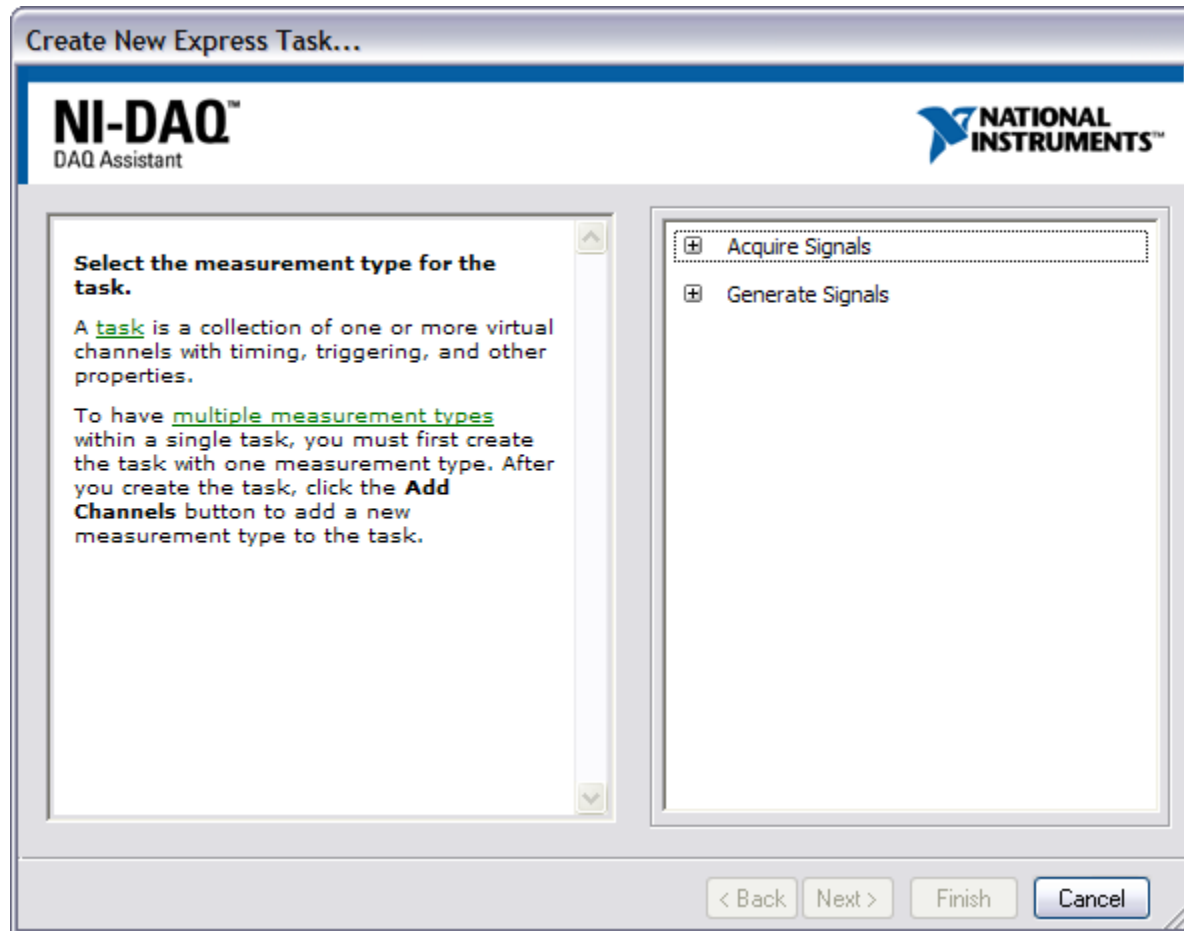
Example time & frequency domains VI

Let's build it !

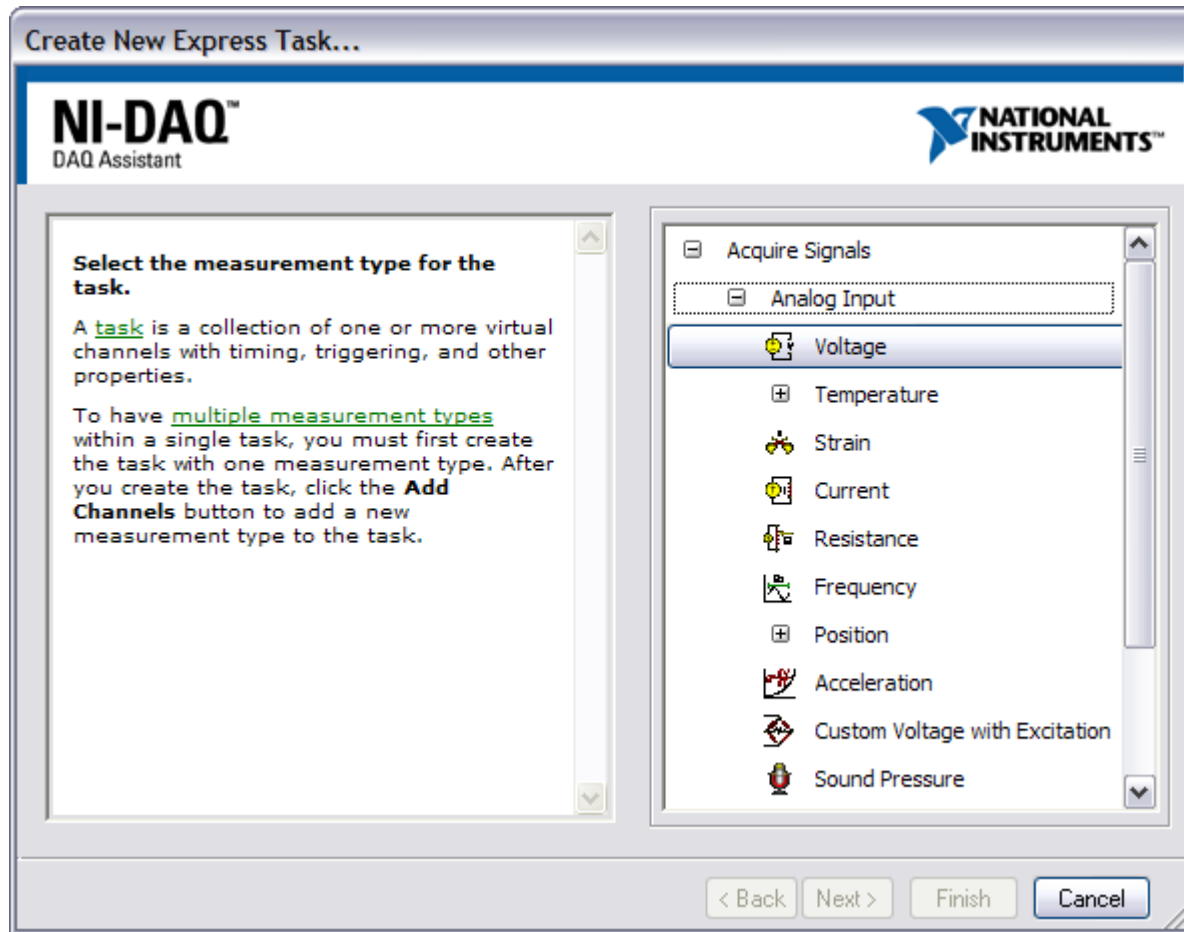


Setting up the DAQ assistant (1)

Open a new VI project & set one AI channel



Setting up the DAQ assistant (2)



Setting up the DAQ assistant (3)

The screenshot displays the DAQ Assistant software window. At the top, there is a toolbar with buttons for Undo, Redo, Run, Add Channels, and Remove Channels. Below the toolbar, there are two tabs: "Express Task" and "Connection Diagram". The main area features a graph with "Amplitude" on the y-axis (ranging from -1 to 1) and a time axis from 0 to 200. The graph is currently empty. Below the graph, there is a "Display Type" dropdown set to "Graph" and an "AutoScale Y-Axis" checkbox that is checked.

The "Configuration" tab is active, showing "Channel Settings" and "Voltage Input Setup". Under "Channel Settings", there is a list with one entry "Voltage" and an "Add Channels" button (+). A note below the list reads: "Click the Add Channels button (+) to add more channels to the task." The "Voltage Input Setup" section has three sub-tabs: "Settings", "Device", and "Calibration". The "Settings" sub-tab is active, showing "Signal Input Range" with "Max" set to 2 and "Min" set to -2. "Scaled Units" is set to "Volts". "Terminal Configuration" is set to "Differential" and "Custom Scaling" is set to "<No Scale>".

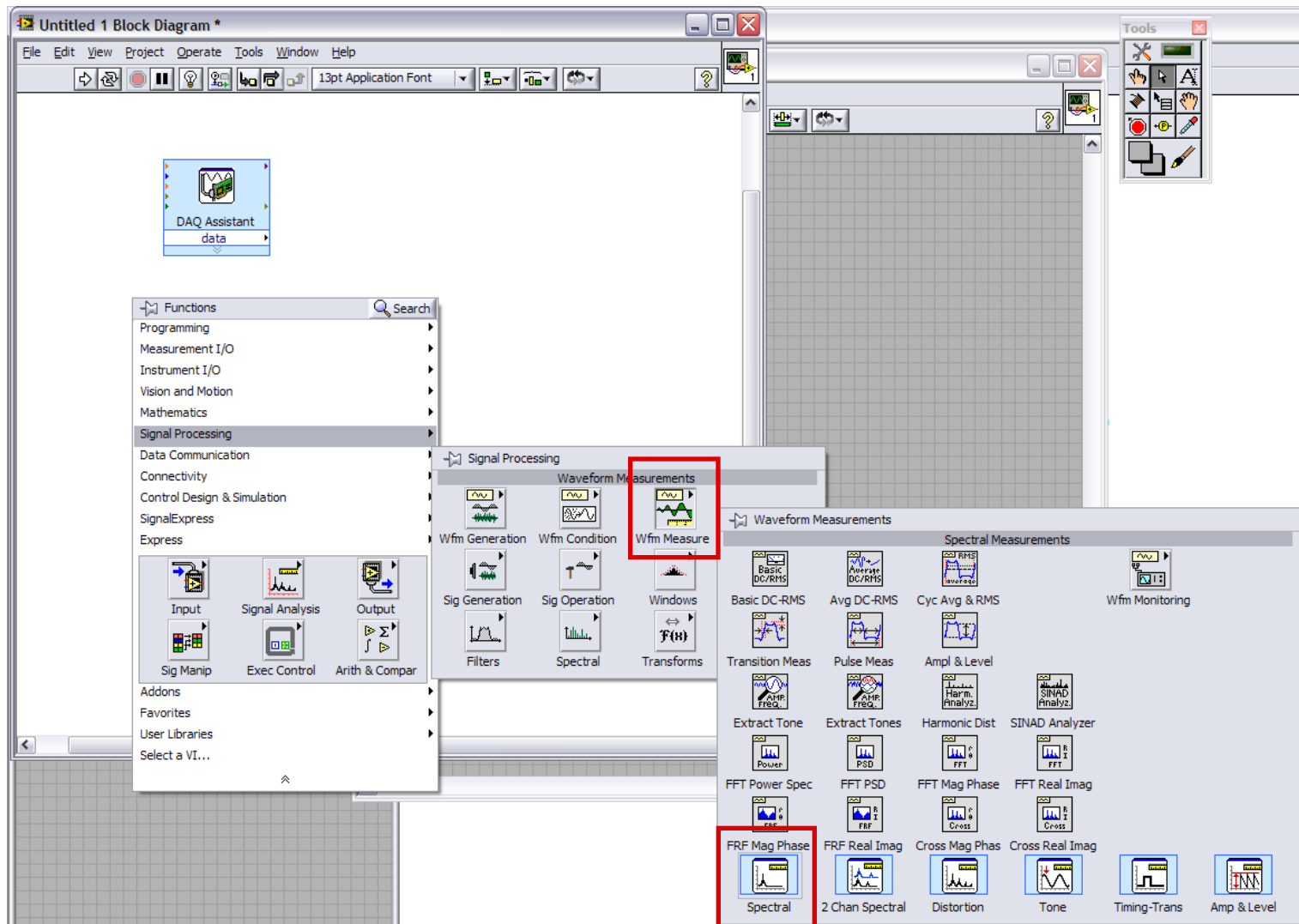
At the bottom of the "Configuration" tab, there are "Timing Settings" with "Acquisition Mode" set to "N Samples", "Samples to Read" set to "2k", and "Rate (Hz)" set to "200".

On the right side of the window, there is a "Measuring Voltage" help panel. It contains text explaining that most measurement devices are designed for measuring voltage, and that DC and AC voltages are common measurements. It also notes that DC voltages are useful for measuring slowly changing phenomena like temperature, pressure, or strain, while AC voltages are used for constantly increasing, decreasing, and reversing waveforms like powerlines.

At the bottom right of the window, there are "OK" and "Cancel" buttons.



Adding spectral measurements tool to block diagram



Settings in the spectral measurements tool

Can be modified later, if necessary

Configure Spectral Measurements

Selected Measurement

- Magnitude (RMS)
- Magnitude (Peak)
- Power spectrum
- Power spectral density

Result

- Linear
- dB

Window

Hanning

Averaging

Mode

- Vector
- RMS
- Peak hold

Weighting

- Linear
- Exponential

Number of Averages

10

Produce Spectrum

- Every iteration
- Only when averaging complete

Phase

- Unwrap phase
- Convert to degree

Windowed Input Signal

Amplitude

Time

Magnitude Result Preview

Magnitude

Frequency

Phase Result Preview

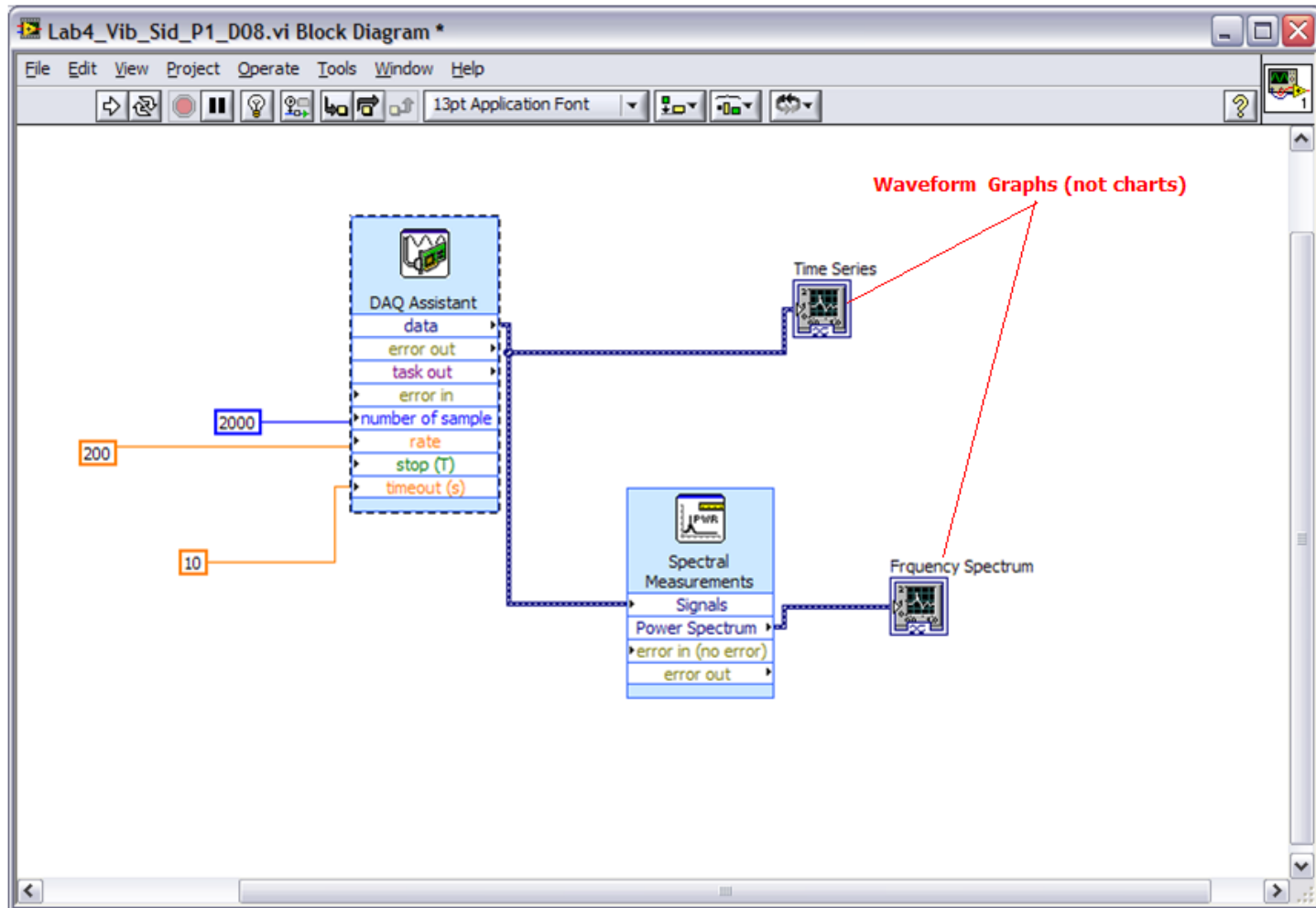
Phase (rad.)

Frequency

OK Cancel Help

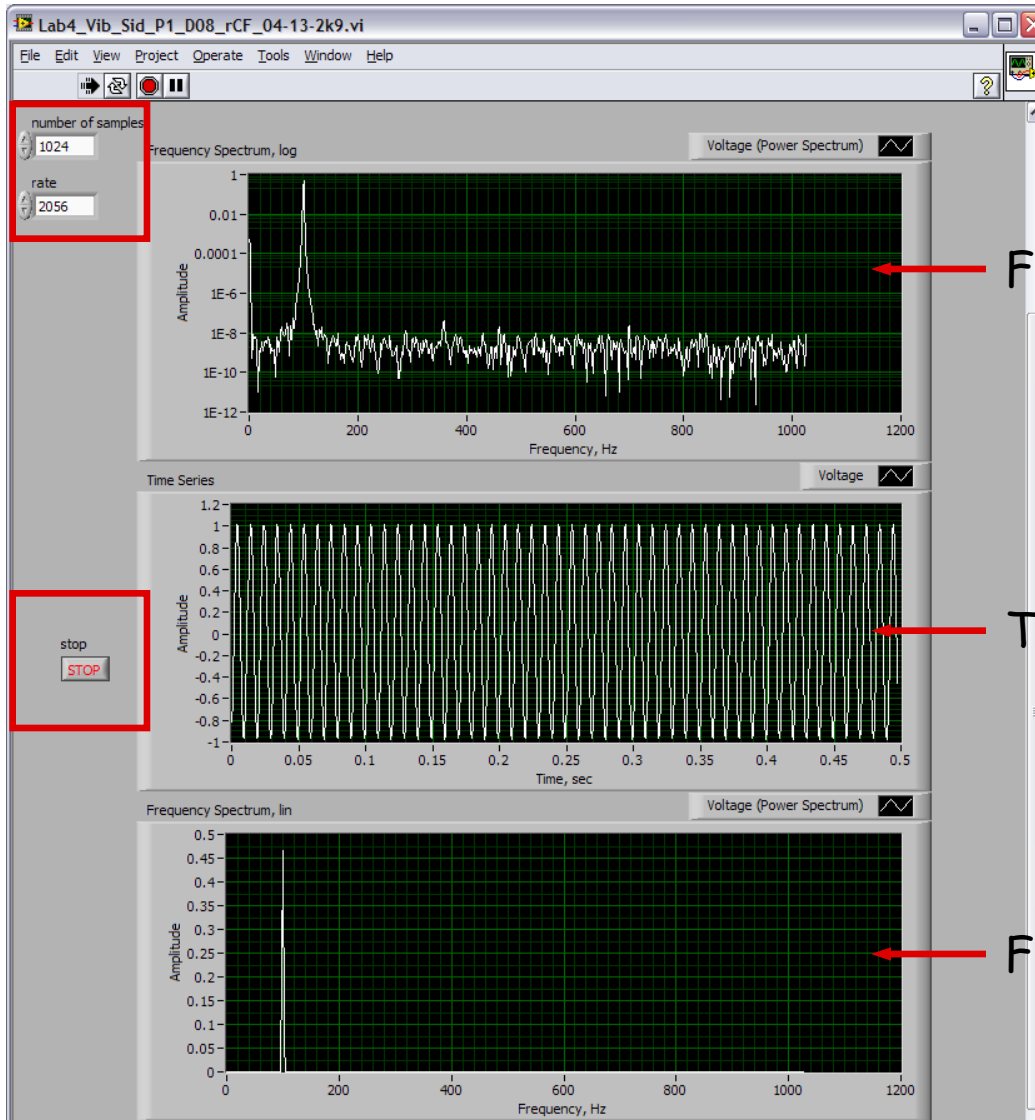


Add controls, graphs, and wire as shown

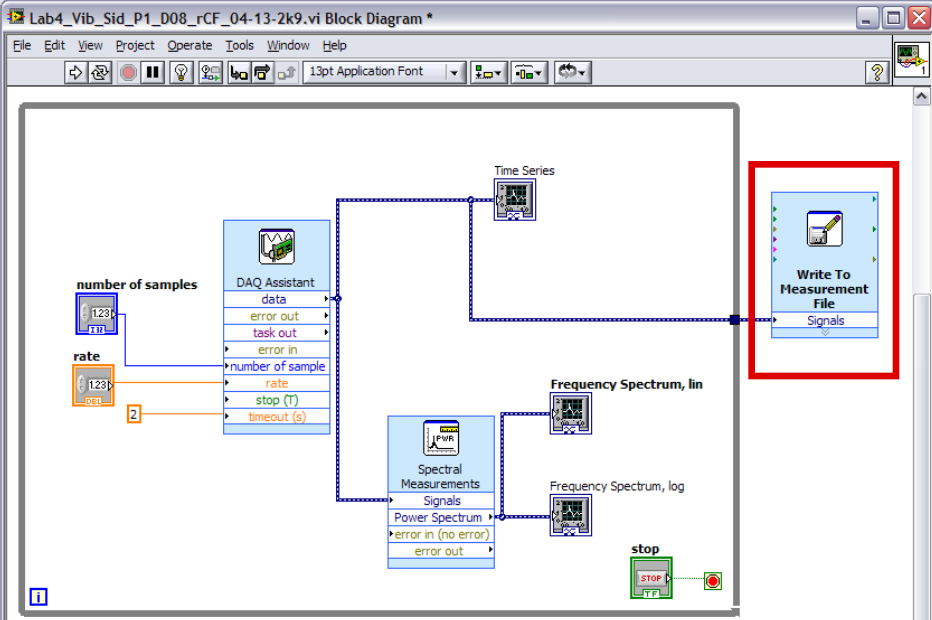
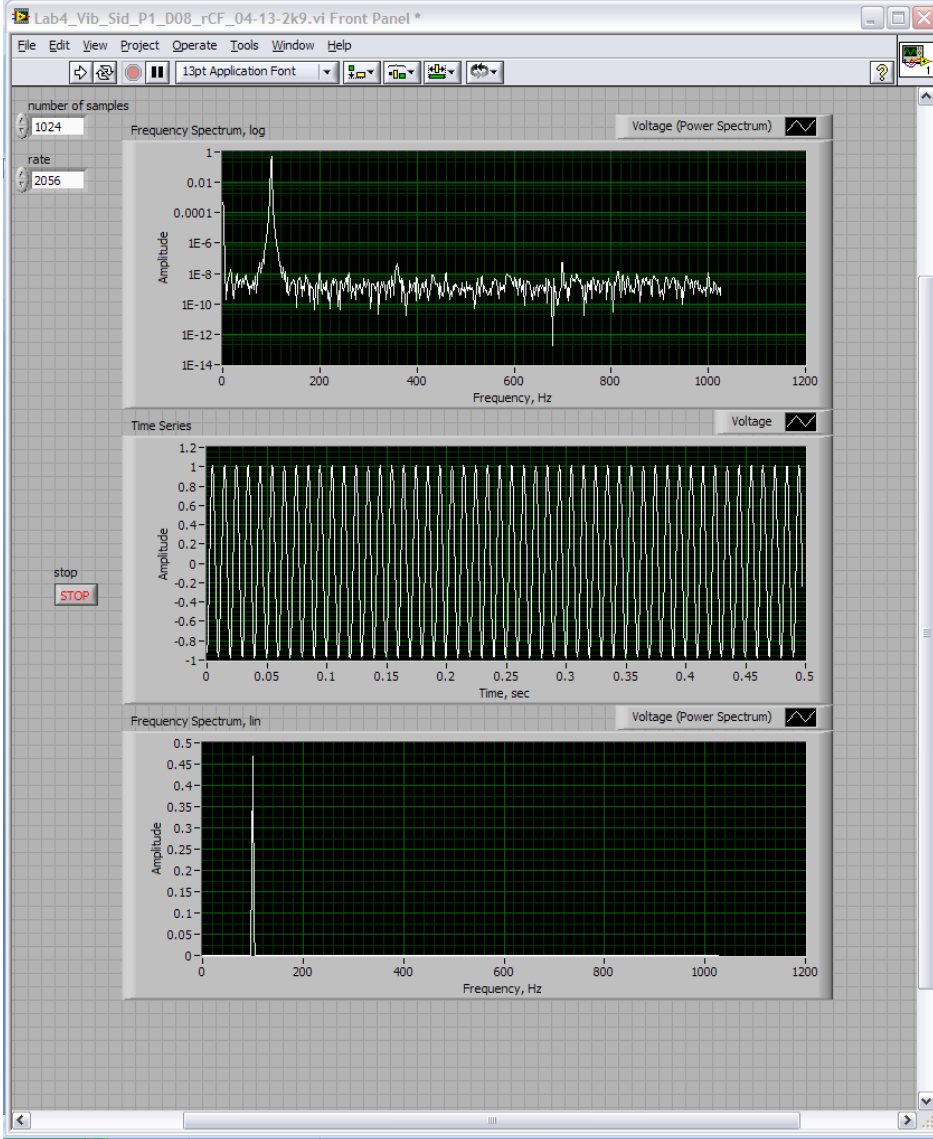


Modify to add suitable controls, shown here

Multiple
of 2^n

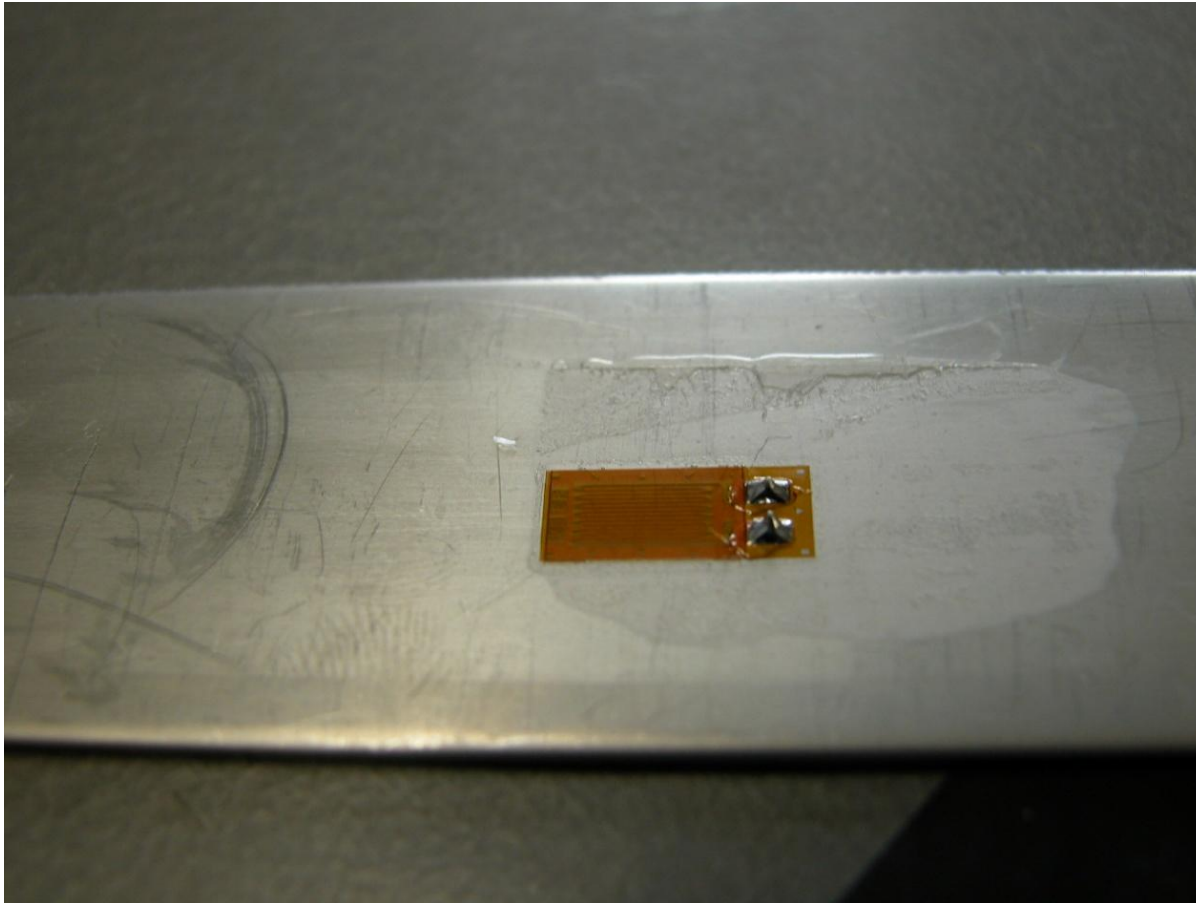


Modify to add suitable functionality, shown here (while loop and write data into file)

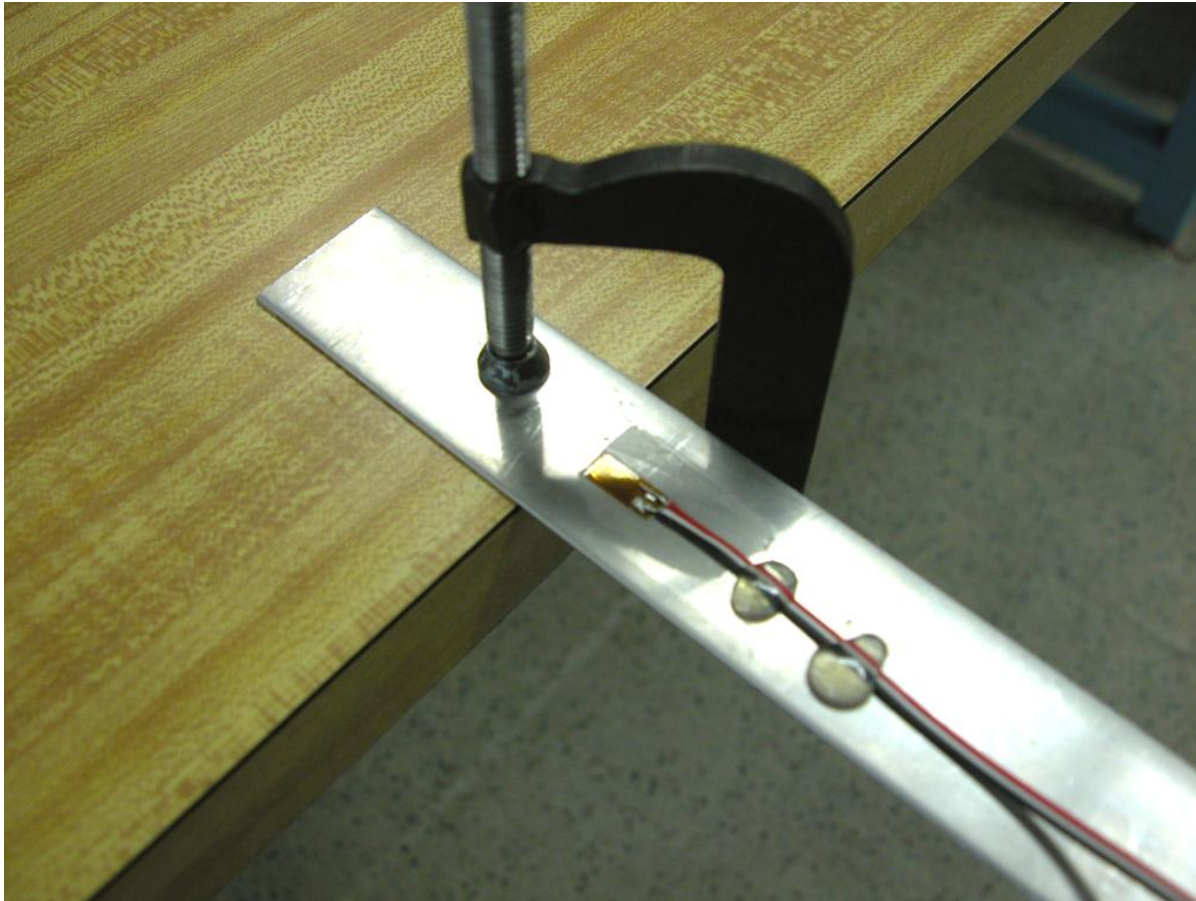


The Functions palette is open, showing the 'File I/O' section. The 'Write To Measurement File' block is highlighted with a red box. Other visible blocks include 'Write Spread...', 'Read Spread...', 'Open/Create...', 'Close File', 'Format Into File', 'Scan From File', 'Write Text File', 'Read Text File', 'Write Binary File', 'Read Binary File', 'Build Path', 'Strip Path', 'File Constants', 'Config File VIs', 'TDM Streaming', 'Storage', 'Zip', and 'Adv File Funcs'.

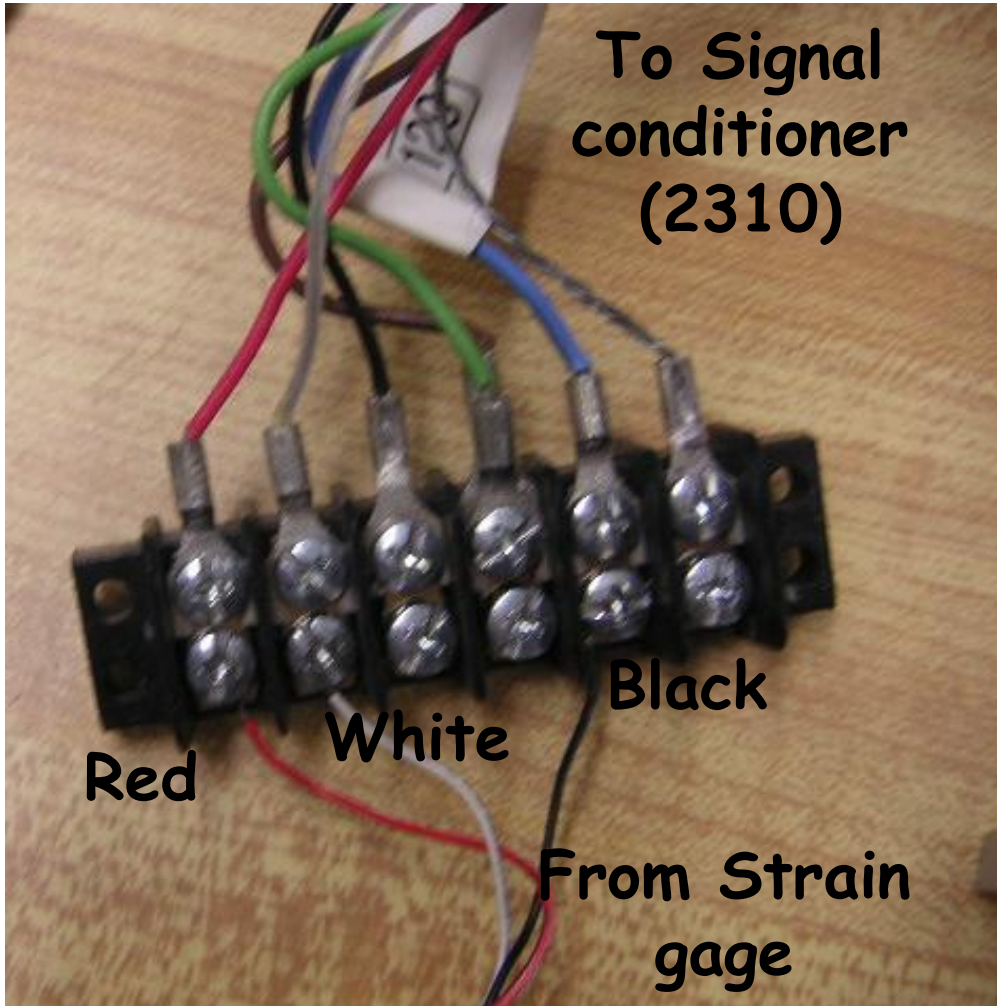
Setting up the hardware (1): attaching strain gauge



Setting up the hardware (2): clamping



Setting up the hardware (3): bridge completion

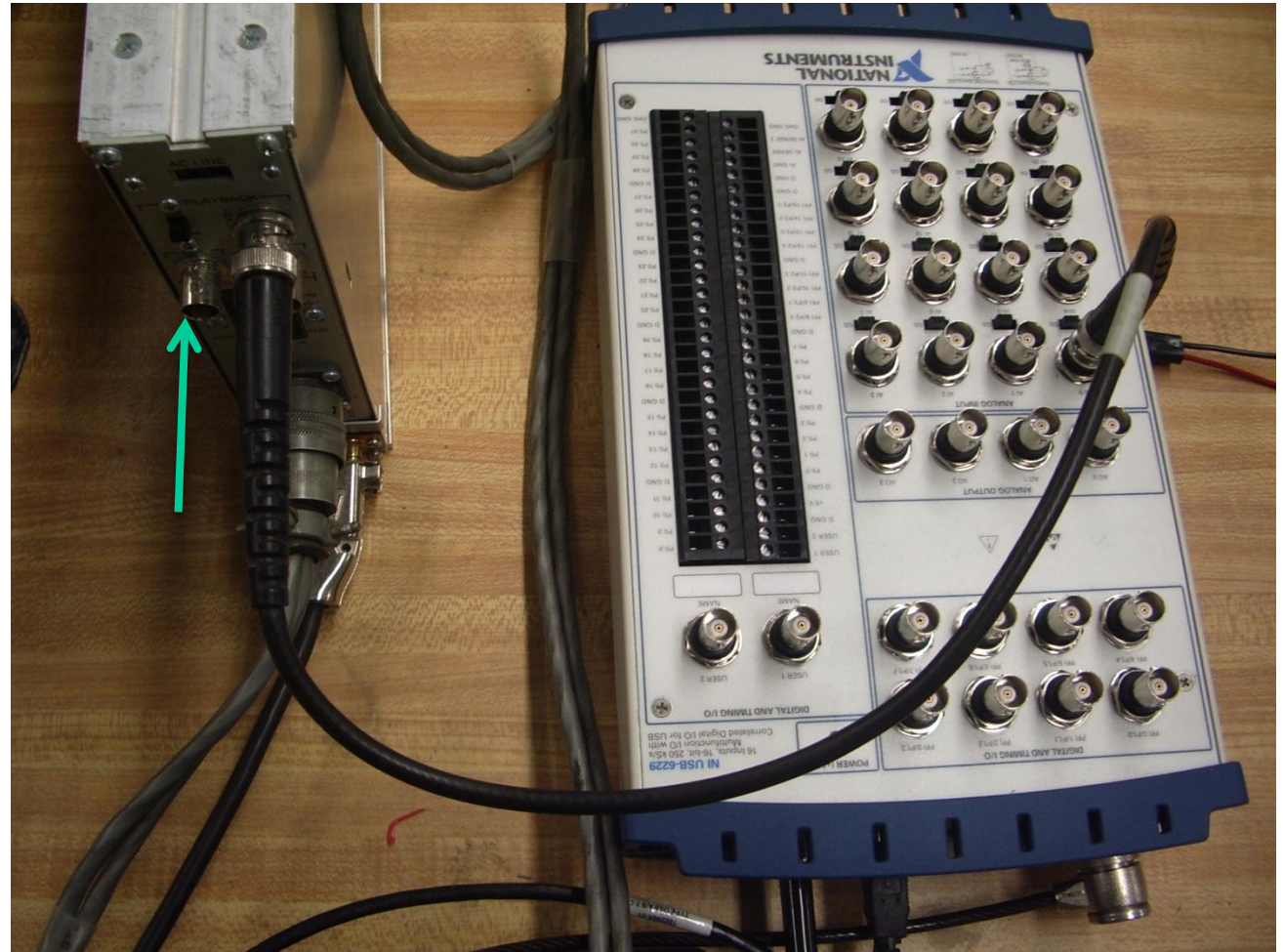


Term.	Strain Gage
Red	Red
White	White
Blue	Black

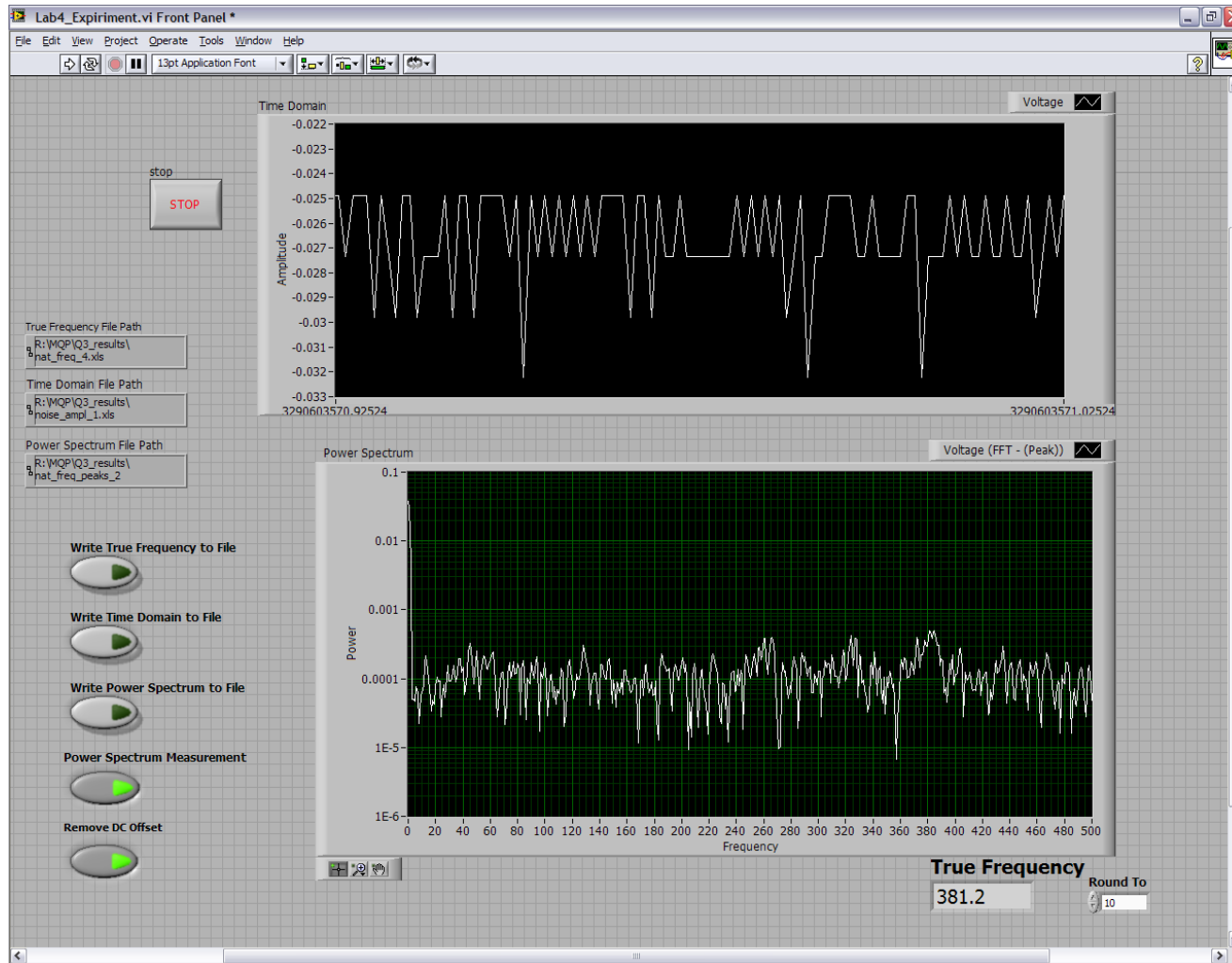


Setting up the hardware (4): read amplified signal

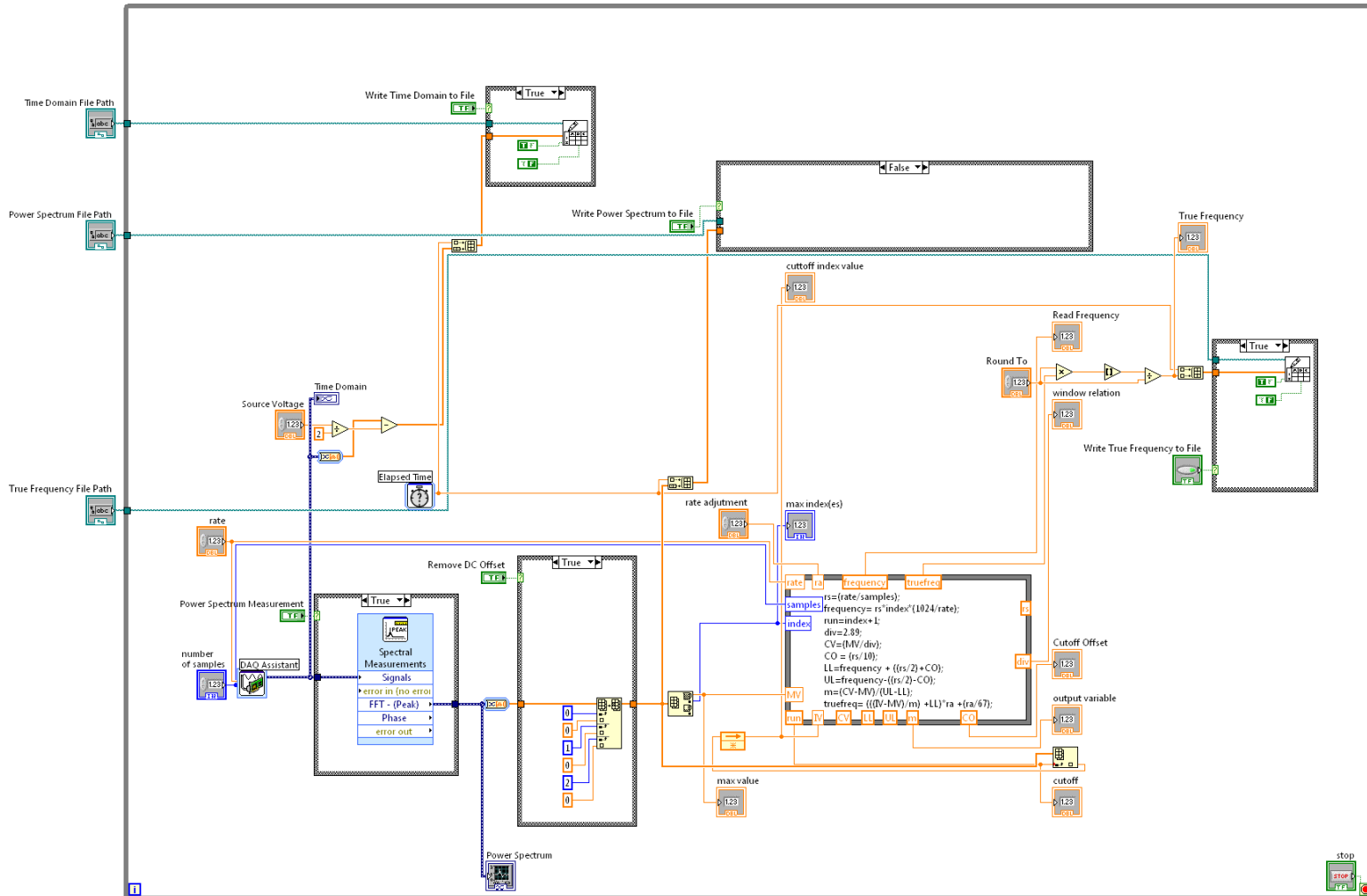
BNC cable from
2310's output
(see ± 10 terminal)



You can try another VI - available in our website
(enabled with writing to file capabilities)



You can try another VI - available in our website (enabled with writing to file capabilities)



Basic principle of accelerometers

- Recall that the RMS value of a function $i(t)$ is calculated as:

$$I_{RMS} = \sqrt{\frac{1}{T} \int_0^T [i(t)]^2 dt}$$

- For a pure sinusoidal function with zero offset:

$$I_{RMS} = \sqrt{\frac{1}{2\pi} \int_0^{2\pi} [I_p \sin(\omega t)]^2 dt} = \sqrt{\frac{I_p^2}{2\pi} \int_0^{2\pi} \sin^2(\omega t) dt}$$

$$I_{RMS} = \frac{I_p}{\sqrt{2}}$$



Basic principle of accelerometers

- Also, recall that for a position function given by:

$$y(t) = A \sin(\omega t + \phi) \quad [\omega, \text{rad/sec}]$$

- Velocity function is:

$$[f = \frac{\omega}{2\pi}, \text{Hz}]$$

$$\dot{y}(t) = \omega A \cdot \cos(\omega t + \phi)$$

- Acceleration function is:

$$\ddot{y}(t) = \underbrace{-\omega^2 A \cdot \sin(\omega t + \phi)}$$



Magnitude of
acceleration

