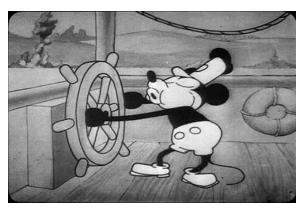
# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

STRESS ANALYSIS ES-2502, D'2020

We will get started soon...



23 April 2020





# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

STRESS ANALYSIS ES-2502, D'2020

We will get started soon...

Lecture 16: Unit 12: Torsion of shafts: circular cross-section: torsion formula

23 April 2020





# General information

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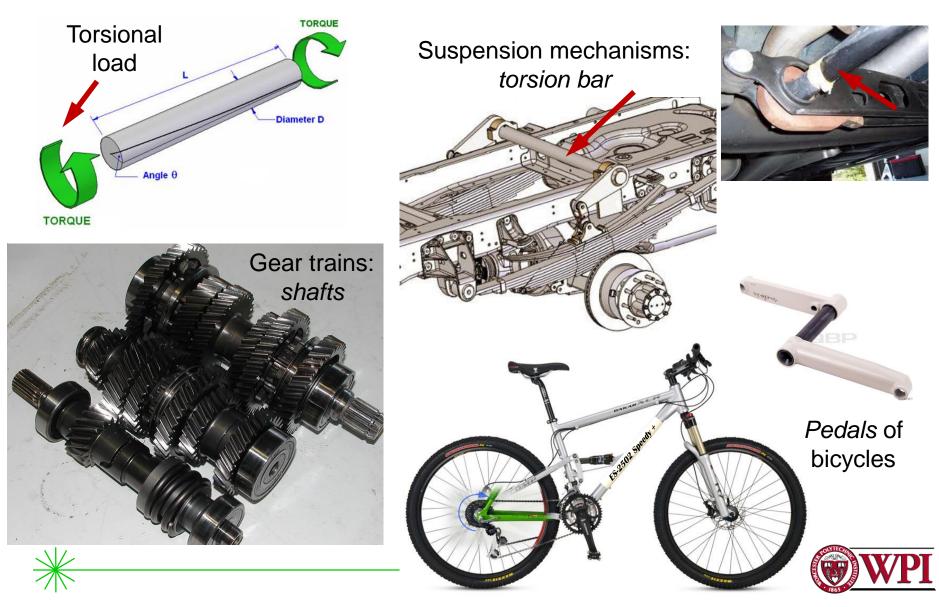
<u>Teaching Assistant</u>: Zachary Zolotarevsky Email: zjzolotarevsky @ wpi.edu





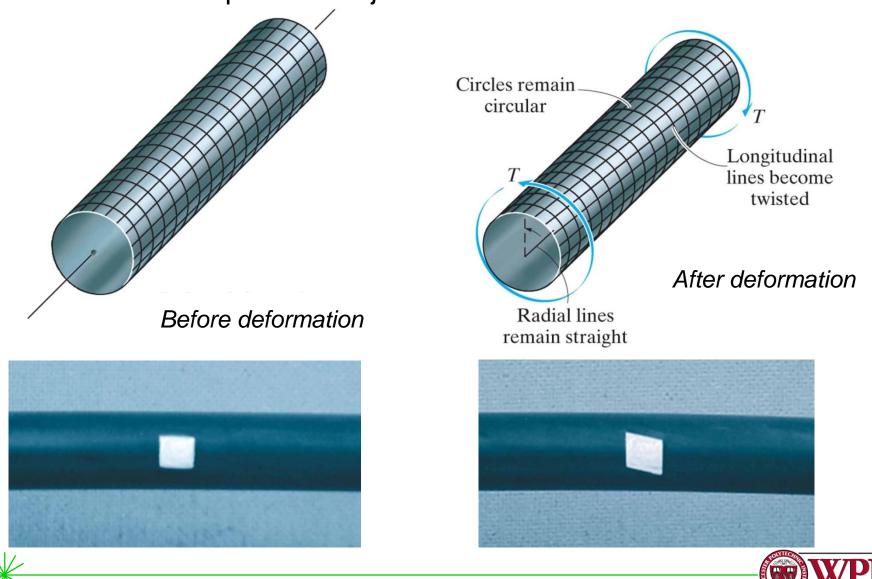
# Torsion

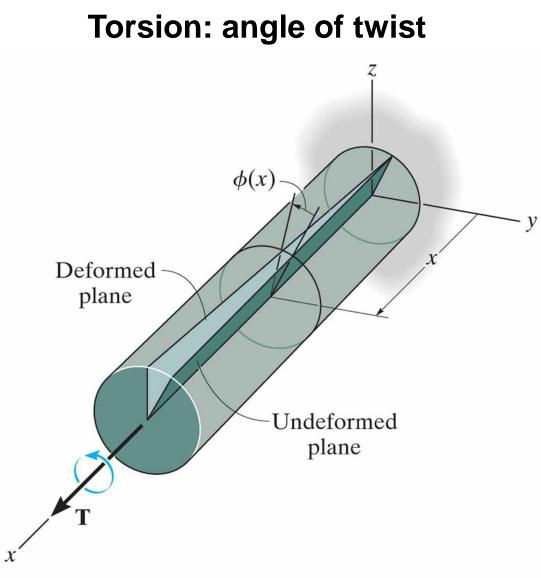
Components subjected to torsional loads: just a few examples



# Torsion

Component subjected to torsional load

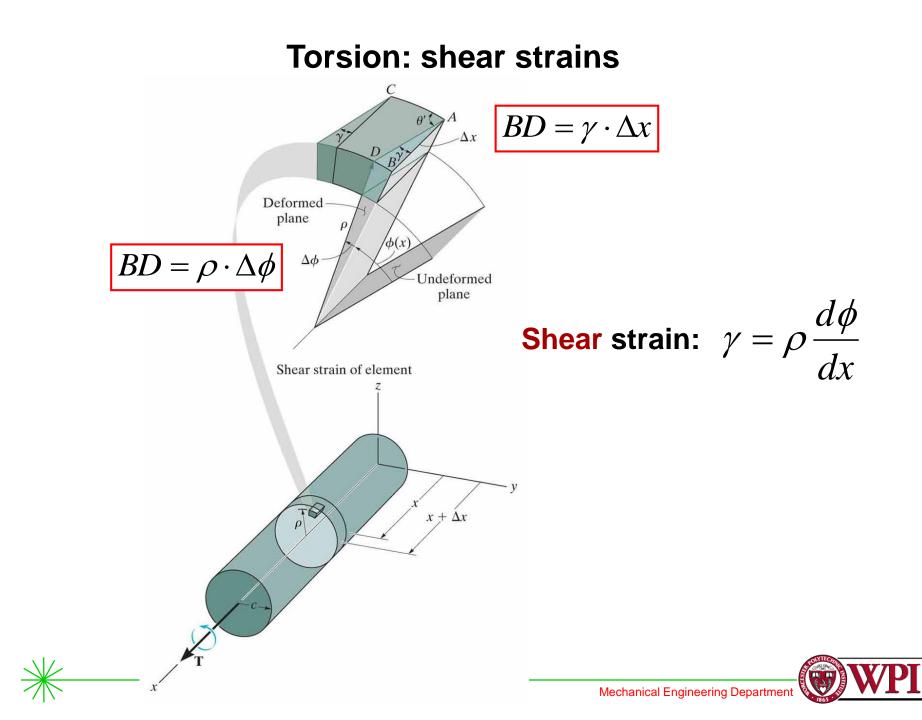




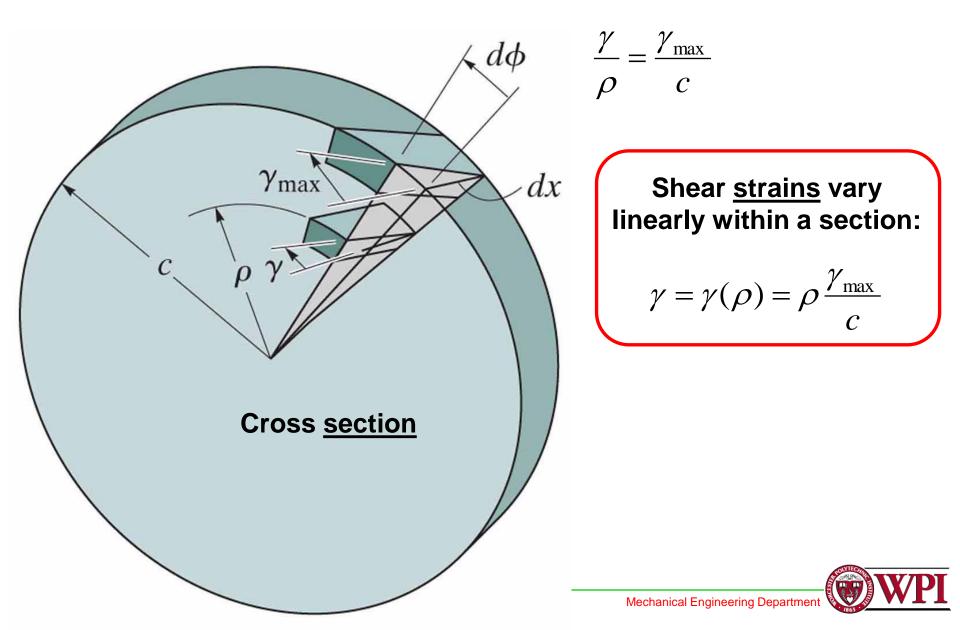
The angle of twist  $\phi(x)$  increases as x increases.







#### **Torsion: shear strains**



### **Torsion formula**

According to Hook's law (linear elasticity):

$$(\tau = G \cdot \gamma)$$

 $au_{\rm max}$ 

T

 $au_{\max}$ 

Shear <u>stresses</u> also vary linearly within a section:

$$\tau = \tau(\rho) = \rho \frac{\tau_{\max}}{c}$$

 $au_{\max}$ 

dA

Differential Force:

 $dF = \tau \cdot dA$ 

Differential Torque:

 $dT = \rho \left(\tau \cdot dA\right)$ 



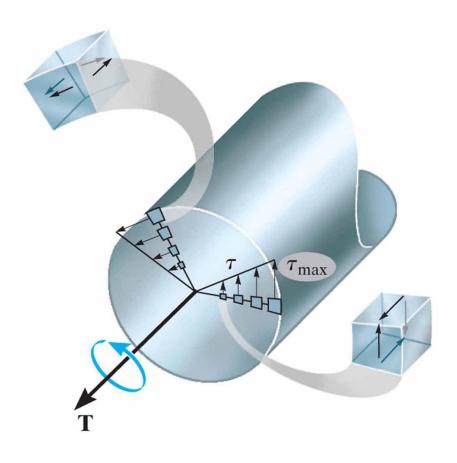
# **Torsion formula**

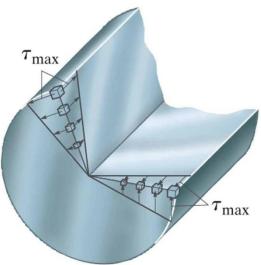
Integrating torque:  $T = \int \rho (\tau \cdot dA) = \int \rho \left( \rho \frac{\tau_{\text{max}}}{c} \right) dA$  $=\frac{\tau_{\max}}{c}\int \rho^2 dA$ Polar area moment of Define:  $J = \int \rho^2 dA$ inertia Torsion formula for stresses: (linear elastic)  $\tau_{\max} = \frac{T c}{I}$  and  $\tau = \tau(\rho) = \frac{T \rho}{J}$ 



# Torsion formula: solid circular bar

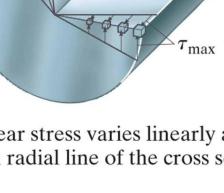
Linear variation of shear stress



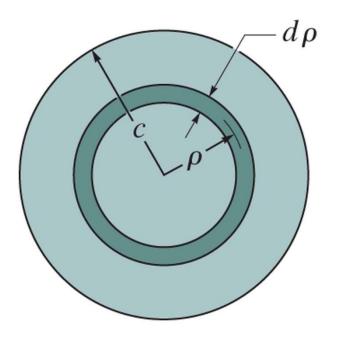


Shear stress varies linearly along each radial line of the cross section.





#### Torsion formula: polar area moment of inertia Solid bar



$$J = \int_{A}^{c} \rho^{2} dA$$
$$= \int_{0}^{c} \rho^{2} (2\pi \rho d\rho)$$

$$=2\pi\int_0^c\rho^3\,d\rho=2\pi\left(\frac{\rho^4}{4}\right)_0^c$$

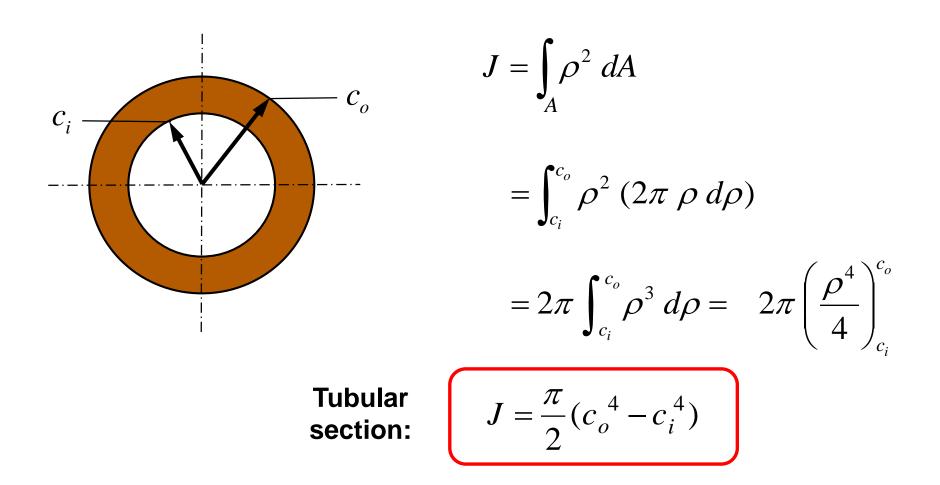
Solid, circular, section:

$$J = \frac{\pi}{2}c^4$$





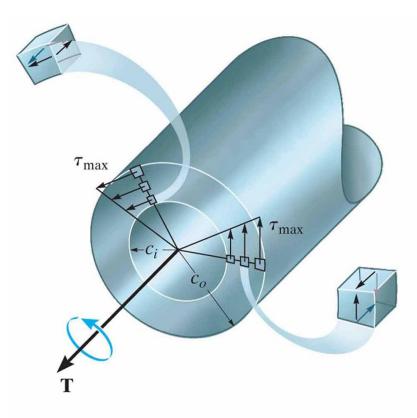
#### Torsion formula: polar area moment of inertia Tubular bar

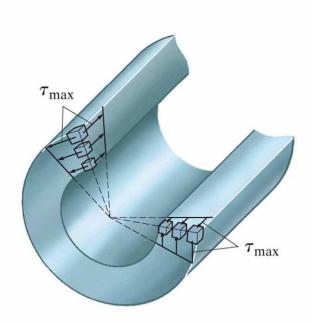




# **Torsion formula: tubular bar**

Linear variation of shear stress





Shear stress varies linearly along each radial line of the cross section.

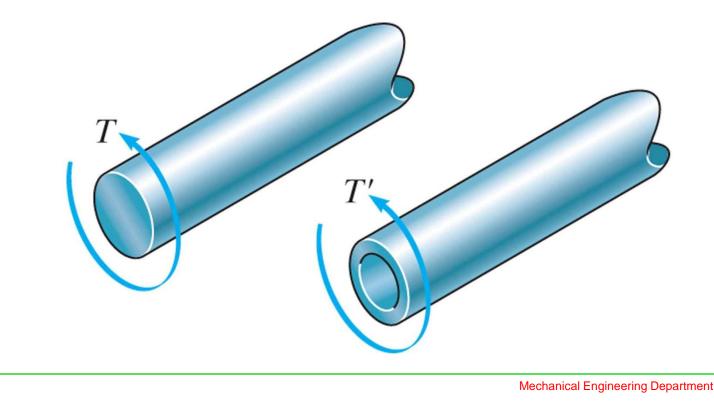




## **Torsion: example A**

A shaft is made of a steel alloy having an allowable shear stress of  $\tau_{\text{allow}} = 12 \text{ ksi}$ . If the diameter of the shaft is 1.5 in., determine the maximum torque *T* that can be transmitted.

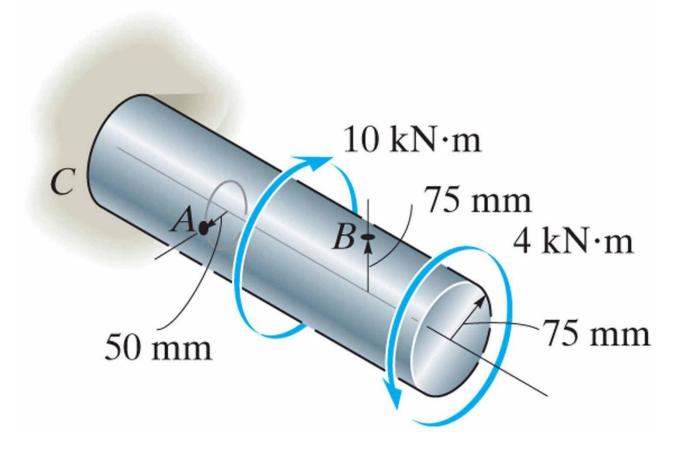
What would be the maximum torque T if a 1-in. diameter hole is bored through the shaft? Sketch the shear-stress distribution *along a radial line* in each case.





# **Torsion: example B**

The solid shaft is fixed to the support at *C* and subjected to the torsional loadings shown. Determine the shear stress at points *A* and *B* and sketch the shear stress on volume (stress) elements located at these points.

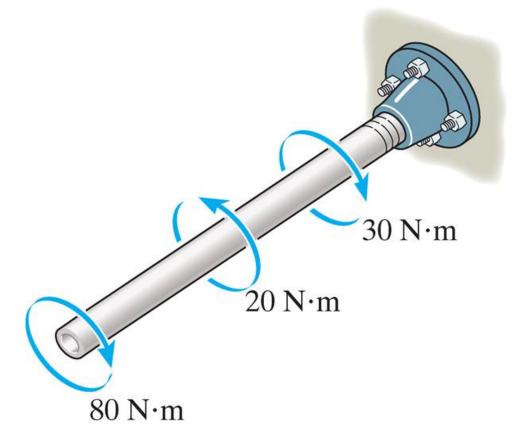






# **Torsion: example C**

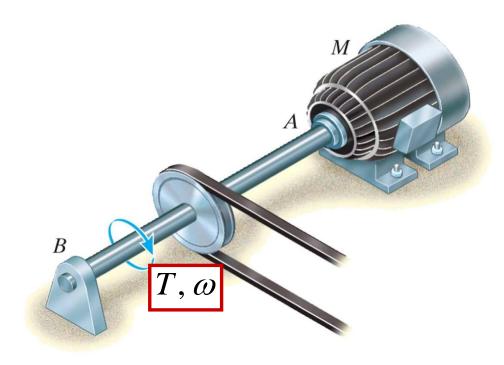
The copper pipe has an outer diameter of 40 mm and an inner diameter of 37 mm. If it is tightly secured to the wall and three torques are applied to it, determine the absolute maximum shear stress developed in the pipe.







### **Power transmission**



$$P = T \omega$$
  
with:  

$$\omega = 2\pi \cdot f$$

$$\omega \begin{bmatrix} rad \\ sec \end{bmatrix}$$

$$f [Hz]$$

WPI



# **Reading assignment**

- Chapter 5 of textbook
- Review notes and text: ES2001, ES2501





# Homework assignment

• As indicated on webpage of our course



