

WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

STRESS ANALYSIS ES-2502, D'2020

We will get started soon...



06 April 2020



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We will get started soon...

Lecture 07:
Unit 5: Normal & Shear strain

06 April 2020



General information

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Strain

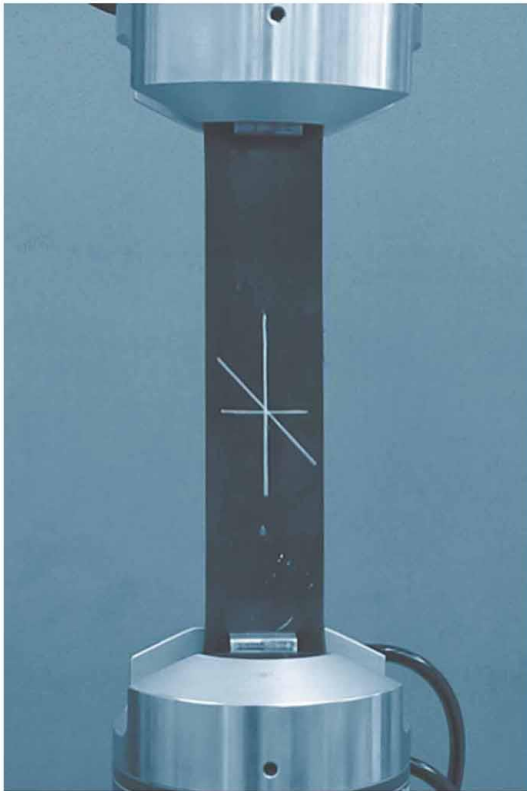


Figure: 02-01-A-UN

Note the before and after positions of three different line segments on this rubber membrane which is subjected to tension. The vertical line is lengthened, the horizontal line is shortened, and the inclined line changes its length and rotates.

Observe what happened to the white line segments in this tensile test experiment

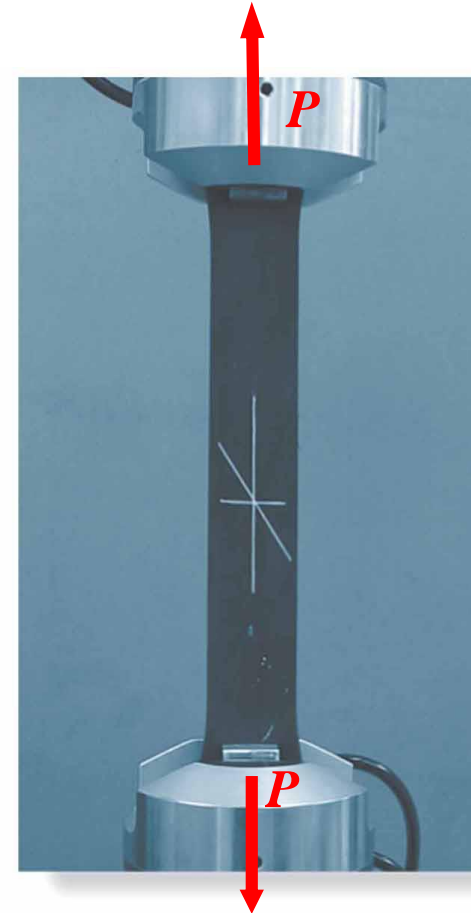


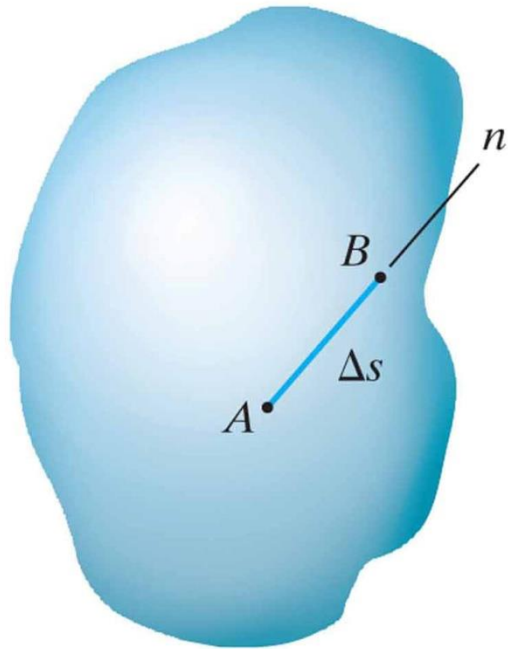
Figure: 02-01-B-UN

Note the before and after positions of three different line segments on this rubber membrane which is subjected to tension. The vertical line is lengthened, the horizontal line is shortened, and the inclined line changes its length and rotates.

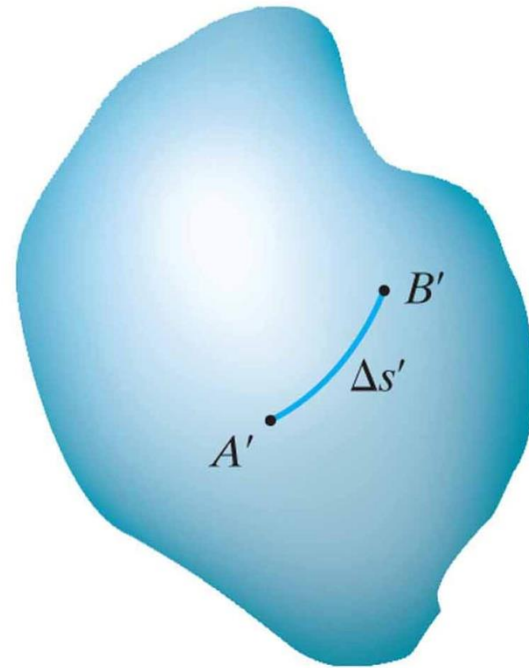


Strain: definition: change in length per unit length

Normal strain



Undeformed body
(a)

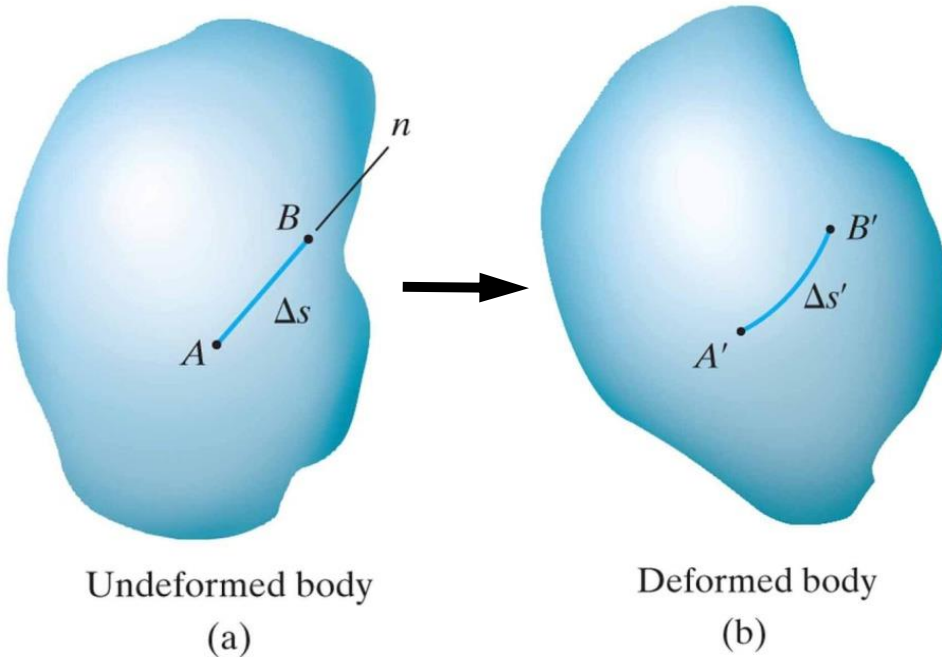


Deformed body
(b)



Strain: definition: change in length per unit length

Normal strain



Average normal strain:

$$\epsilon_{avg} = \frac{\Delta s' - \Delta s}{\Delta s}$$

Normal strain:

$$\epsilon = \lim_{B \rightarrow A \text{ along } n} \frac{\Delta s' - \Delta s}{\Delta s}$$

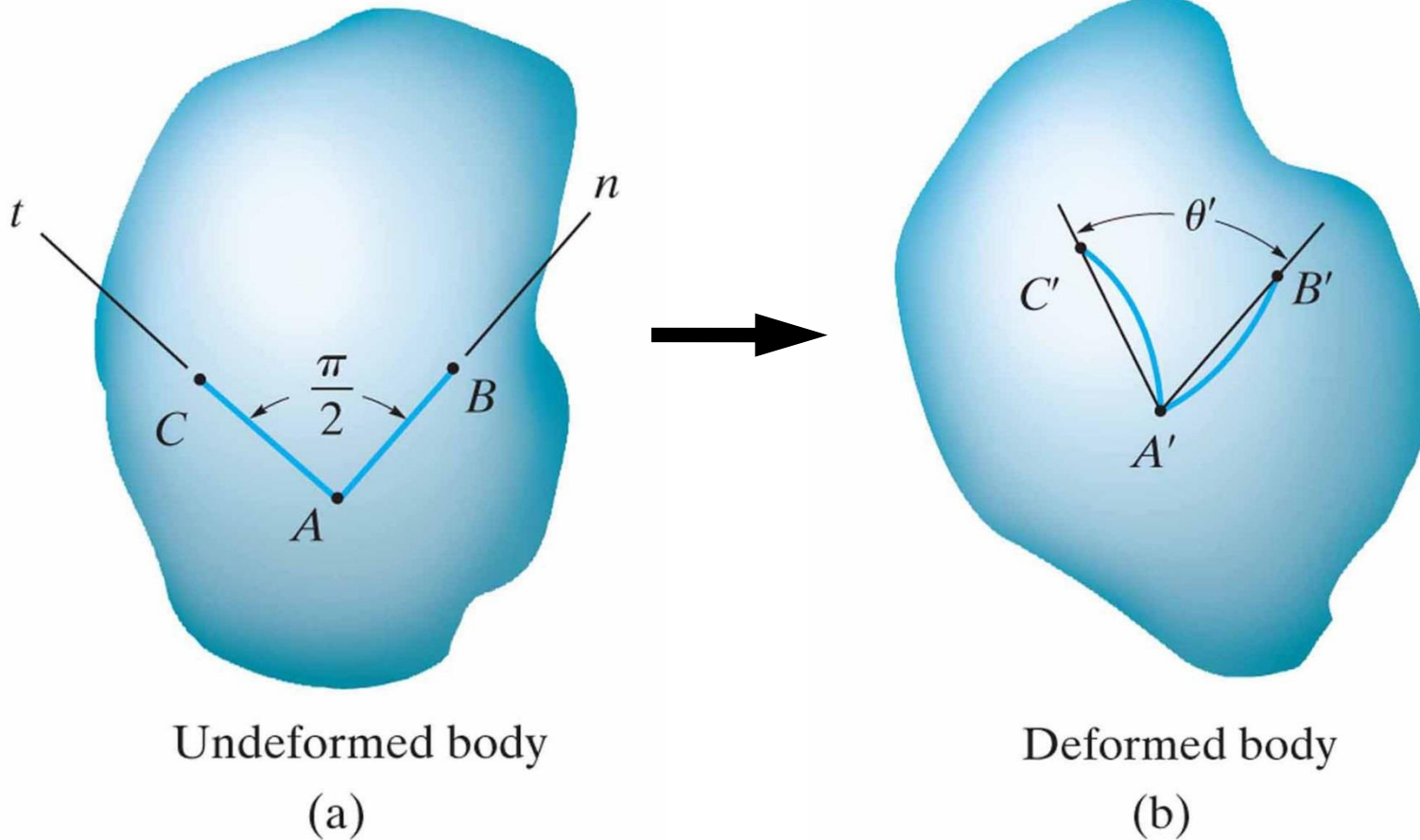
Note that,

$$\epsilon = \frac{d(\Delta s)}{ds}$$



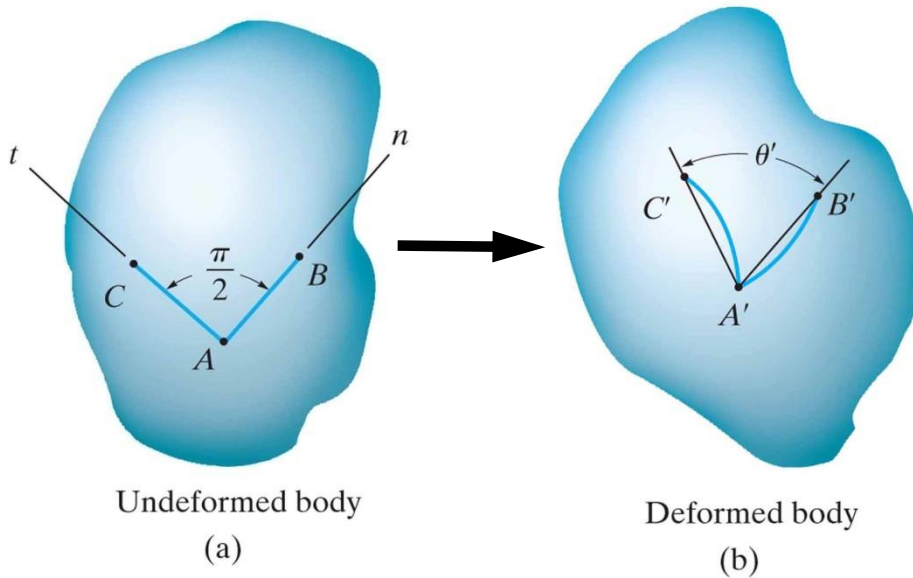
Strain: definition: change in length per unit length

Shear strain



Strain: definition: change in length per unit length

Shear strain



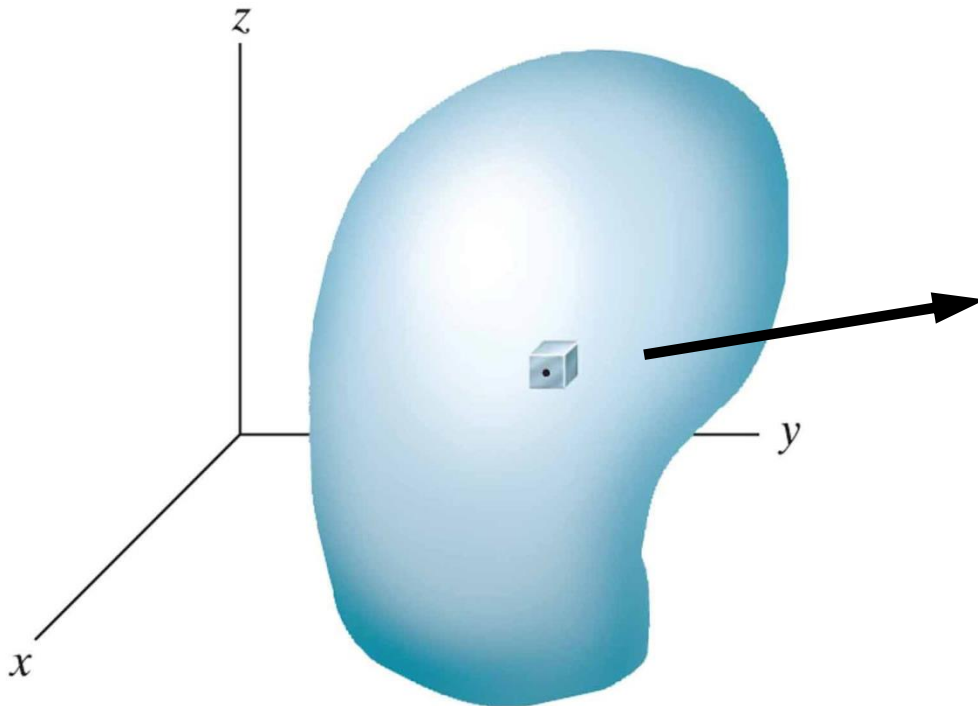
Shear strain:

$$\gamma_{nt} = \frac{\pi}{2} - \lim_{\substack{B \rightarrow A \text{ along } n \\ C \rightarrow A \text{ along } t}} \theta'$$



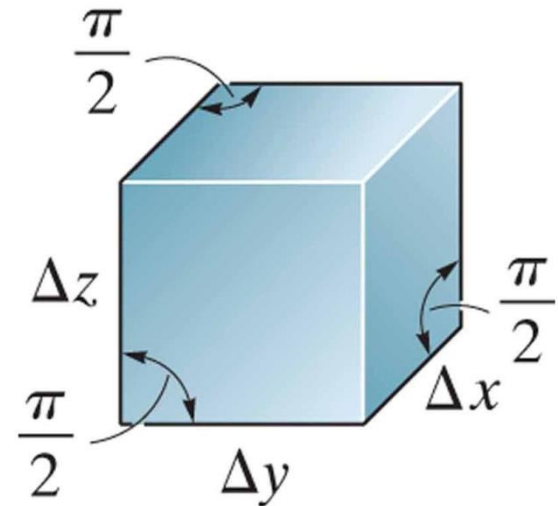
Cartesian strain components

**Before
deformations**



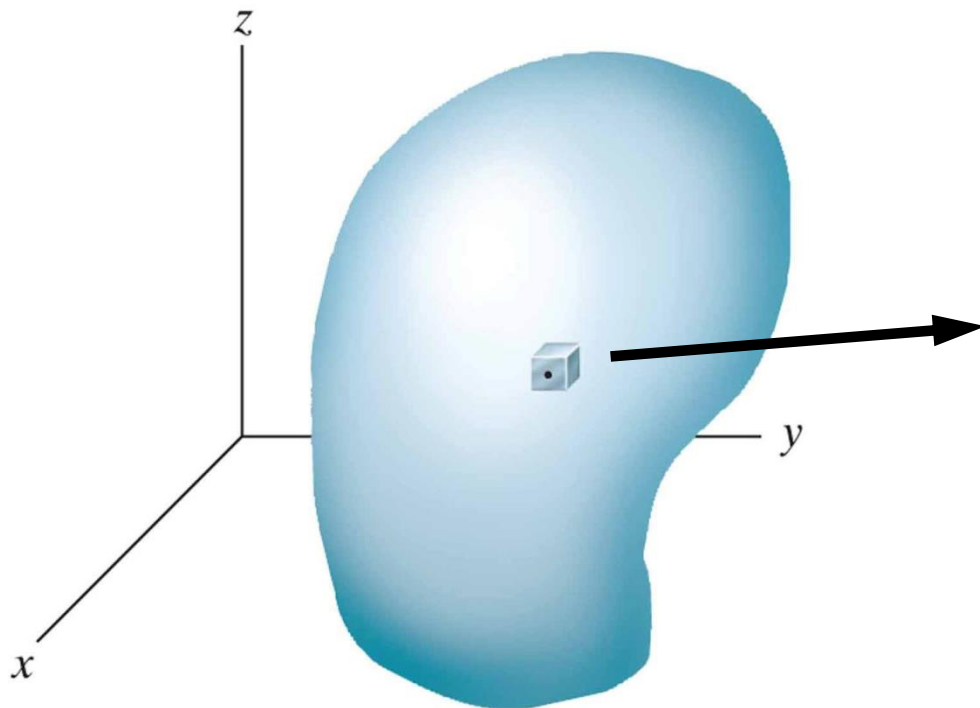
Differential
element or cube
(undeformed)

Dimensions: Δx , Δy , Δz



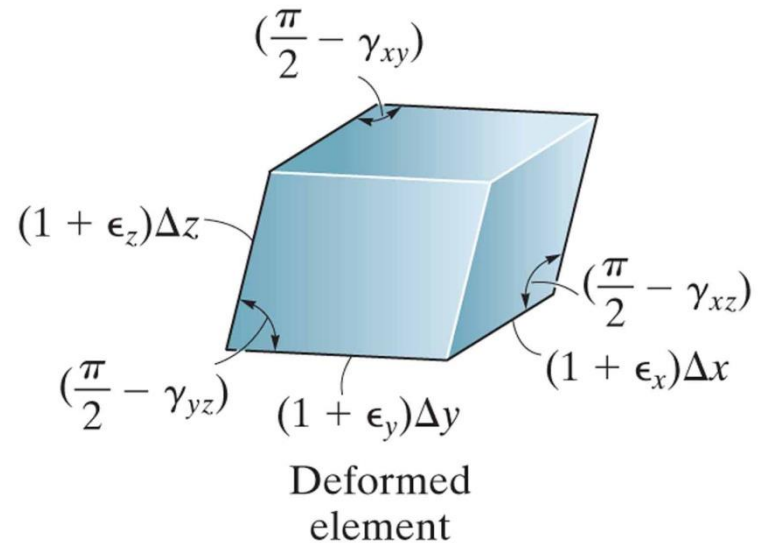
Cartesian strain components

**After
deformations**



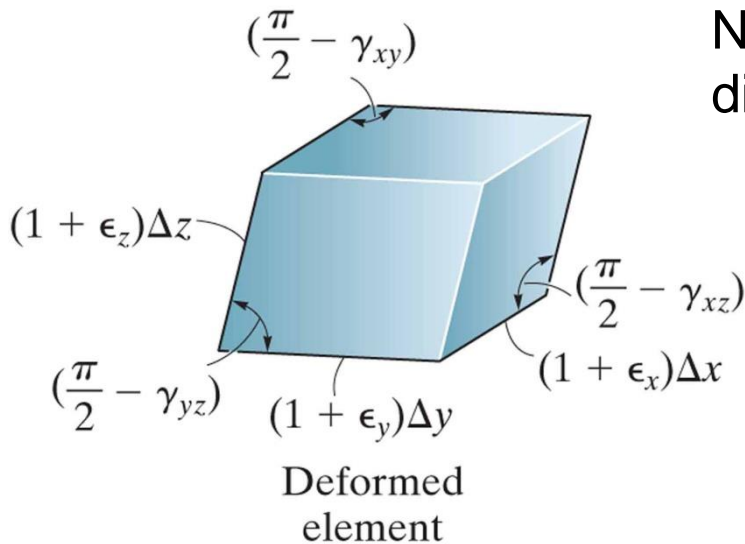
Differential
element or cube
(**deformed**)

New dimensions: $\Delta x + \epsilon_x (\Delta x)$
 $\Delta y + \epsilon_y (\Delta y)$
 $\Delta z + \epsilon_z (\Delta z)$



Cartesian strain components

Differential element or cube
(deformed)



Original dimensions

Elongations

New dimensions:

$$\begin{aligned} \Delta x + \epsilon_x (\Delta x) &= (1 + \epsilon_x) \Delta x \\ \Delta y + \epsilon_y (\Delta y) &= (1 + \epsilon_y) \Delta y \\ \Delta z + \epsilon_z (\Delta z) &= (1 + \epsilon_z) \Delta z \end{aligned}$$

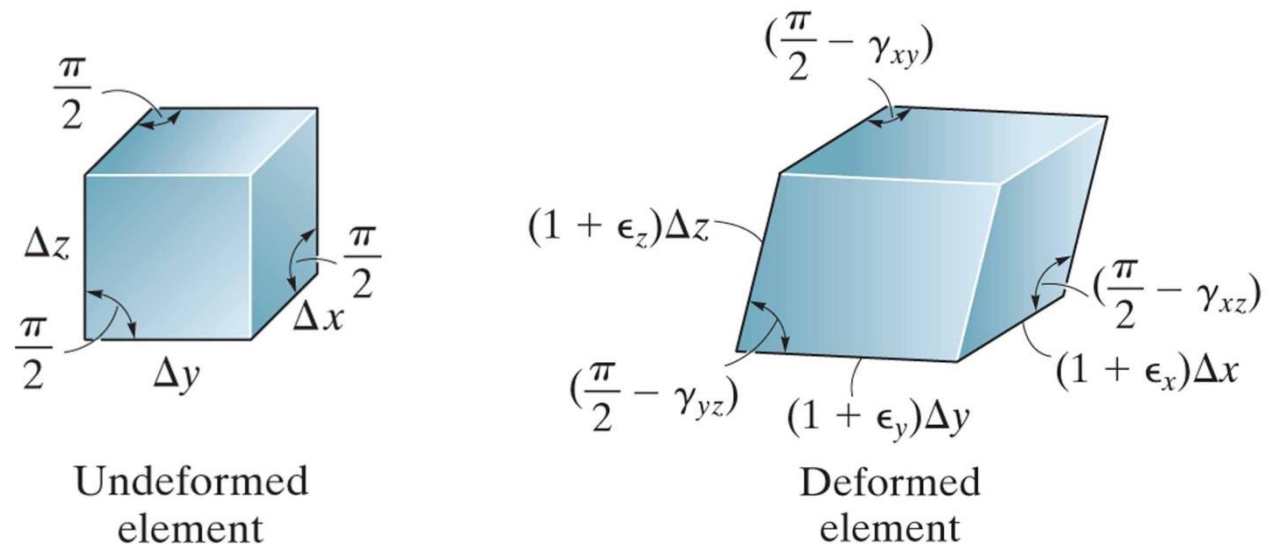
Approximate angles
between sides:

$$\frac{\pi}{2} - \gamma_{xy} , \quad \frac{\pi}{2} - \gamma_{yz} , \quad \frac{\pi}{2} - \gamma_{xz}$$



Cartesian strain components

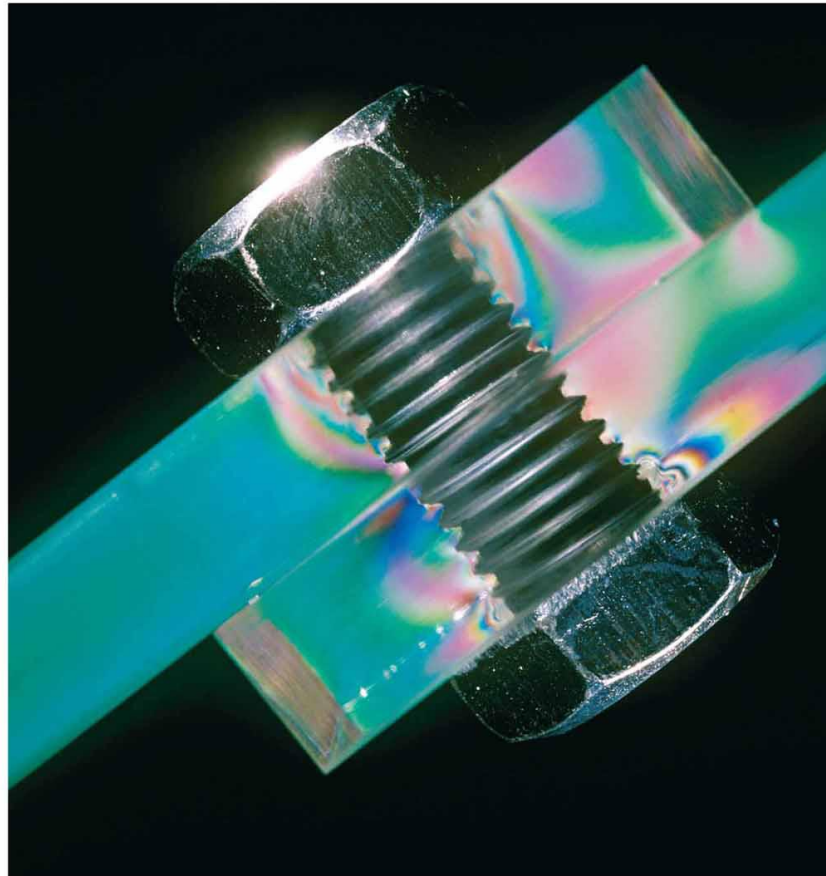
- 1) Normal strains cause a change in volume of the element
- 2) Shear strains cause a change in its shape
- 3) Normal and shear strains occurs simultaneously during deformation
- 4) State of strain at a point on a body requires specifying 6 strain components: ϵ_x , ϵ_y , ϵ_z , and γ_{xy} , γ_{yz} , γ_{xz}



Typical **strain** distributions generated inside a bolted assembly

Polarized light used in experiment shown: bolted assembly

Strains are related to stresses in the materials



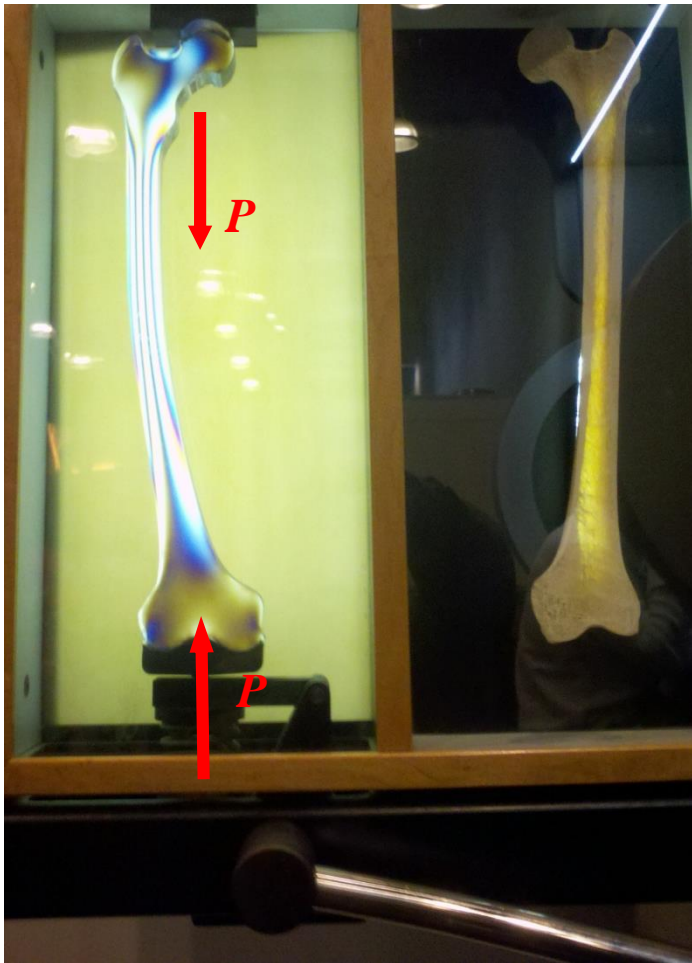
Strains can be measured and stresses estimated from strains



Typical **strain** distributions generated inside a bolted assembly

Polarized light used in experiment shown: component in compression

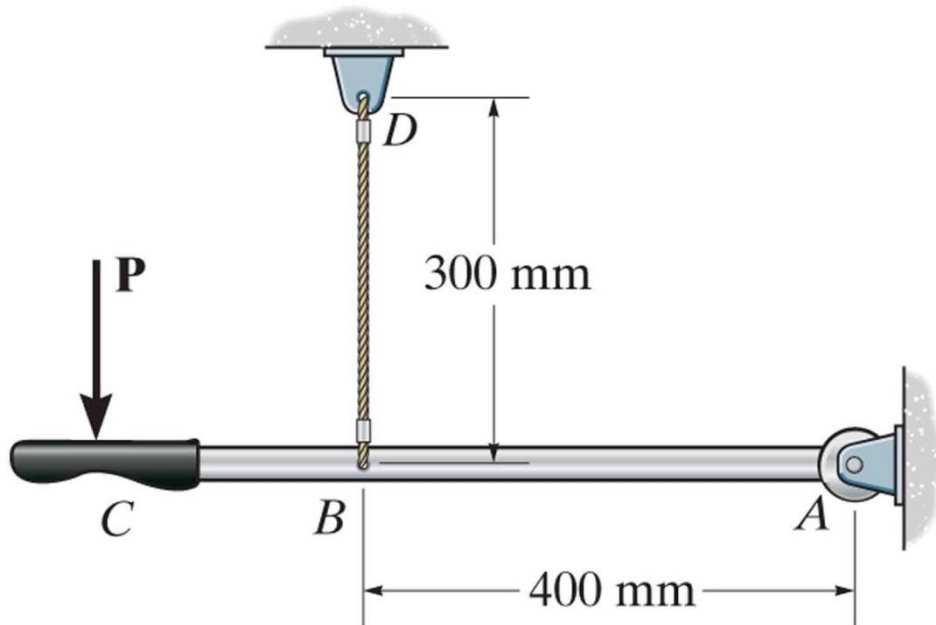
Strains are related to stresses in the materials



Strains can be measured and stresses estimated from strains

Strain: example A

When force \mathbf{P} is applied to the rigid lever arm ABC shown, the arm rotates counterclockwise about pin A through an angle of 0.05° . Determine the normal strain developed in wire BD .



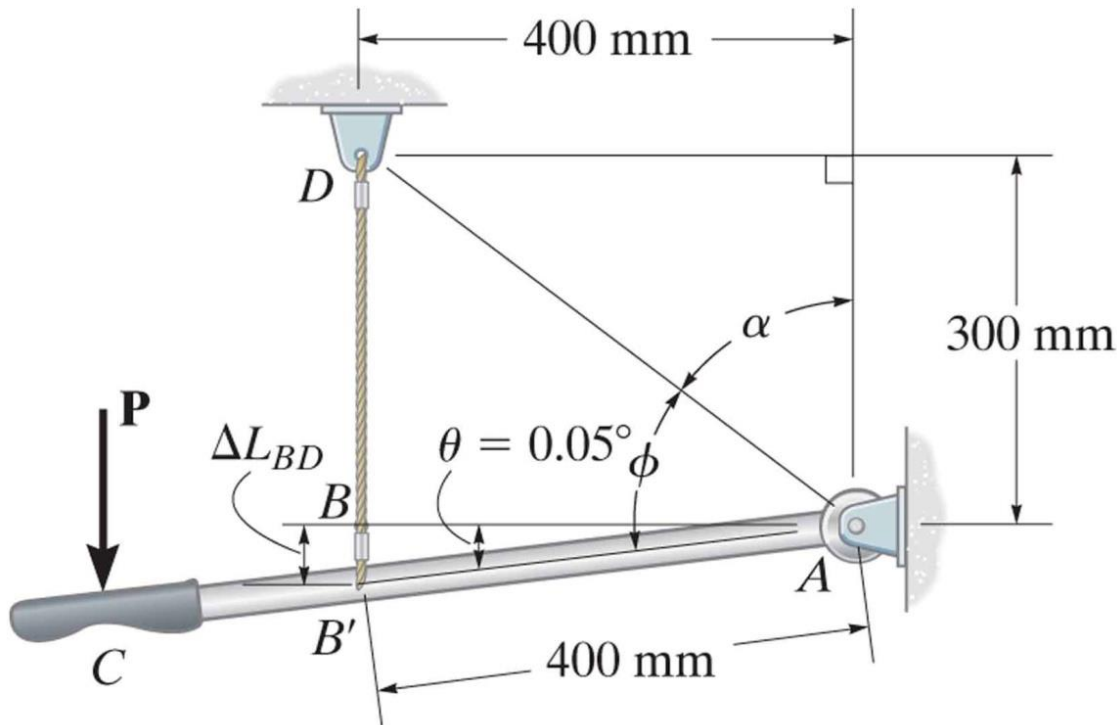
Approach:

- 1) Define geometry
- 2) Determine change in geometry
- 3) Compute required strains



Strain: example A

When force \mathbf{P} is applied to the rigid lever arm ABC shown, the arm rotates counterclockwise about pin A through an angle of 0.05° . Determine the normal strain developed in wire BD .

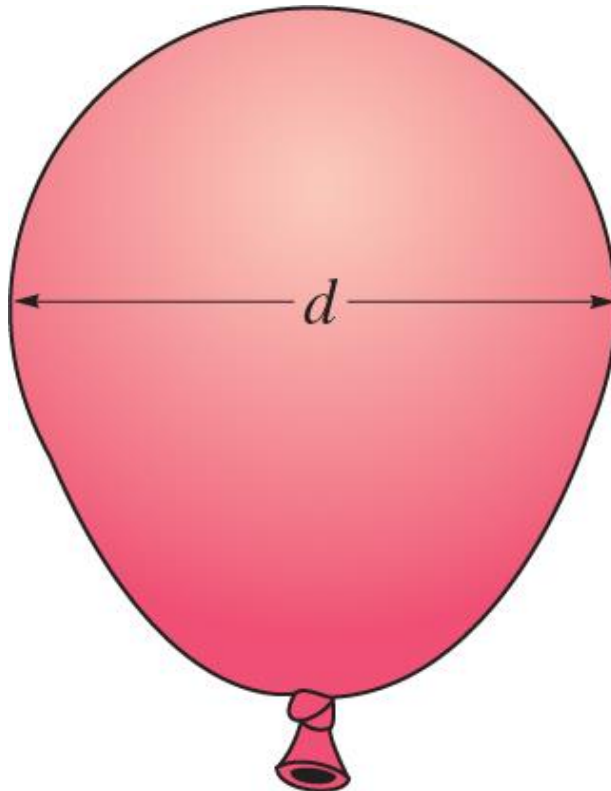


Change in geometry
&
Computation of
normal strain



Strain: example B

An air-filled rubber balloon has a diameter of 6 in. If the air pressure within it is increased until the ball's diameter becomes 7 in, determine the average normal strain in the rubber



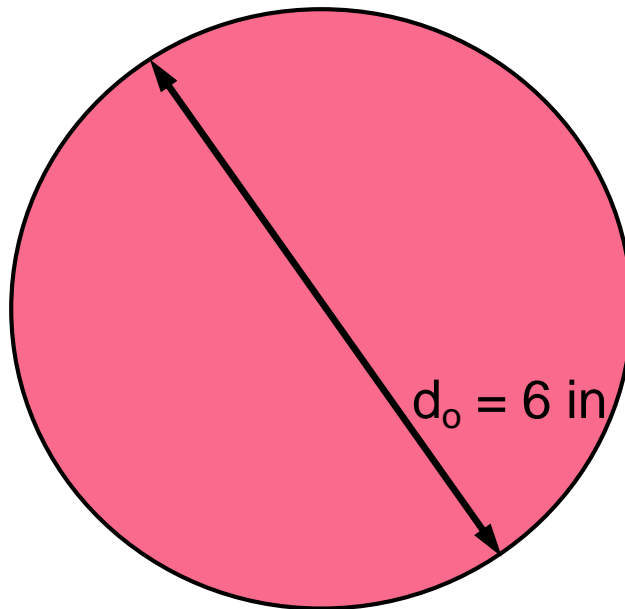
Approach:

- 1) Define geometry
- 2) Determine change in geometry
- 3) Compute required strains



Strain: example B

An air-filled rubber balloon has a diameter of 6 in. If the air pressure within it is increased until the ball's diameter becomes 7 in, determine the average normal strain in the rubber



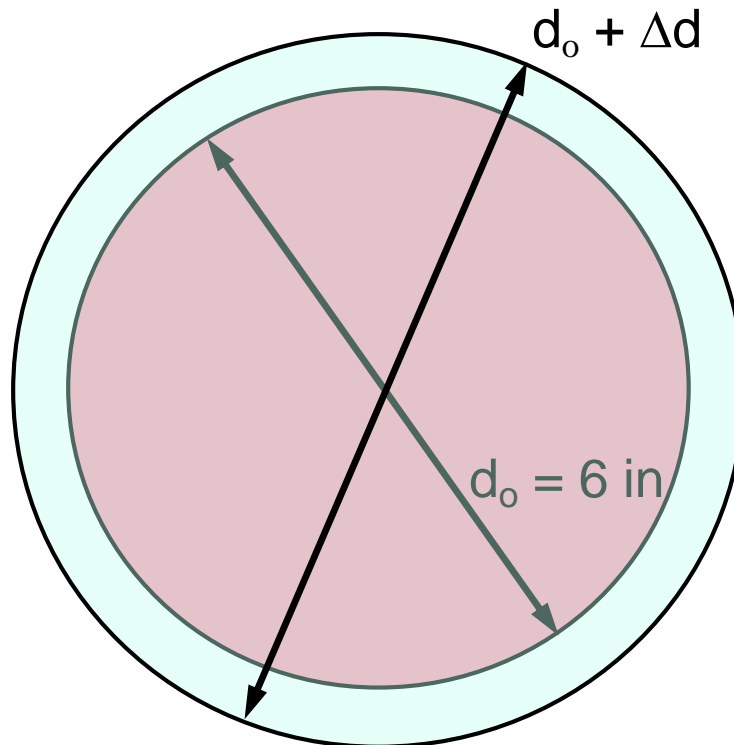
Approach:

- 1) Define geometry
- 2) Determine change in geometry
- 3) Compute required strains



Strain: example B

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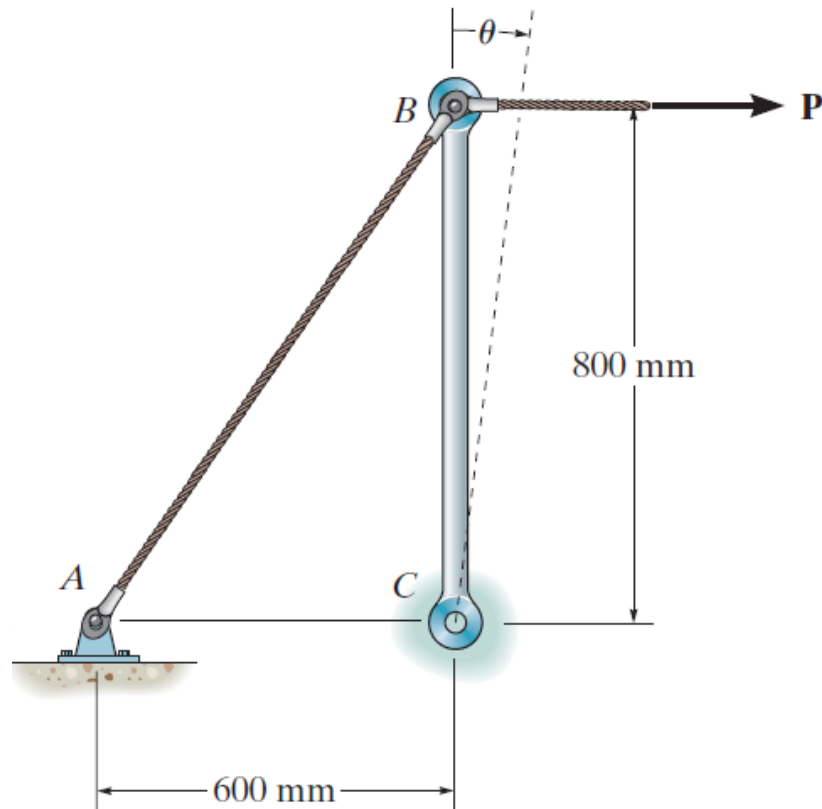
Change in geometry
&
Computation of
normal strain

change in length of
circumference $\rightarrow \epsilon$



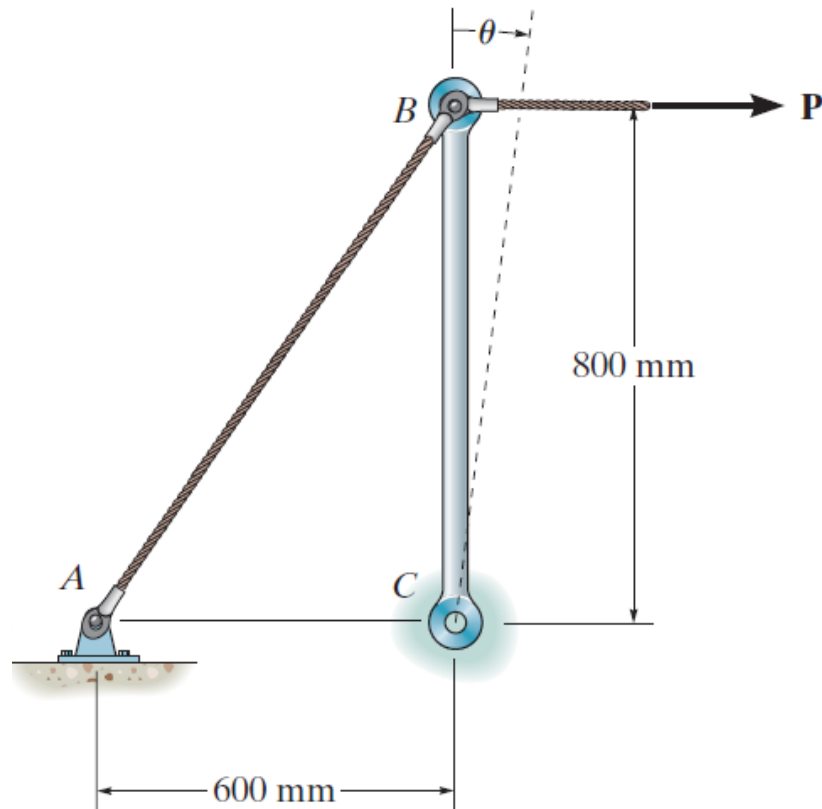
Strain: example C

Part of a control linkage for an airplane consists of a rigid member CB and a flexible cable AB . If a force is applied to the end B of the member and causes it to rotate by $\theta = 0.5^\circ$, determine the normal strain in the cable. Originally the cable is unstretched.



Strain: example D

Part of a control linkage for an airplane consists of a rigid member CB and a flexible cable AB . If a force is applied to the end B of the member and causes a normal strain in the cable of 0.004 mm/mm , determine the displacement of point B . Originally the cable is unstretched.



Reading assignment

- Chapter 2 of textbook
- Review notes and text: ES2001, ES2501



Homework assignment

- As indicated on webpage of our course

