

# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

## STRESS ANALYSIS ES-2502, D'2020

We will get started soon...



27 March 2020



# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

## STRESS ANALYSIS ES-2502, D'2020

We will get started soon...

Lecture 02: Internal Forces

27 March 2020



# General information

Instructor: Cosme Furlong

HL-152

(508) 831-5126

Email: cfurlong @ wpi.edu

<http://www.wpi.edu/~cfurlong/es2502.html>

Teaching Assistant: Zachary Zolotarevsky

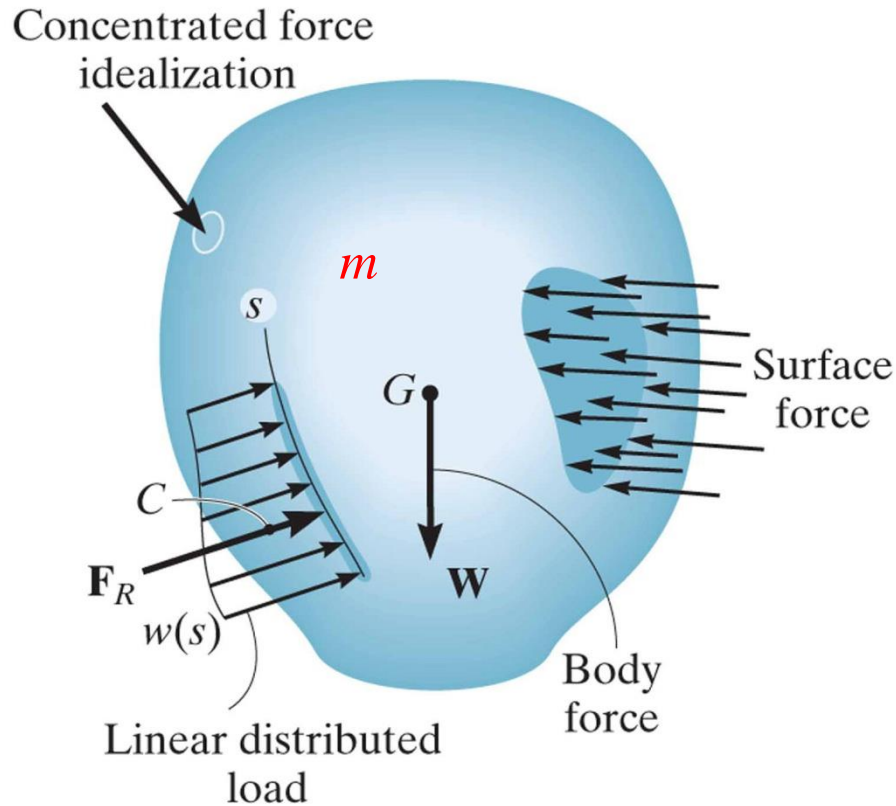
Email: zjzolotarevsky @ wpi.edu



# Force analysis. Free-body diagrams

Static equilibrium: **forces**

Arbitrary component  
under load



Static equilibrium condition  
(vectorial representation) :

$$\sum \mathbf{F} = \mathbf{0}$$



# Force analysis. Free-body diagrams

Static equilibrium: **forces**

Forces acting on a particle or body (**vectorial representation**):

$$\sum \mathbf{F} = \mathbf{0} = \sum F_x \mathbf{i} + \sum F_y \mathbf{j} + \sum F_z \mathbf{k}$$



Null **vector** !!

Individual orthogonal components (**scalar representation**):

$$\sum F_x = 0$$



Null - **Scalar** !!

$$\sum F_y = 0$$

$$\sum F_z = 0$$



# Force analysis. Free-body diagrams

Static equilibrium: **moments**

Static equilibrium condition  
(vectorial representation):

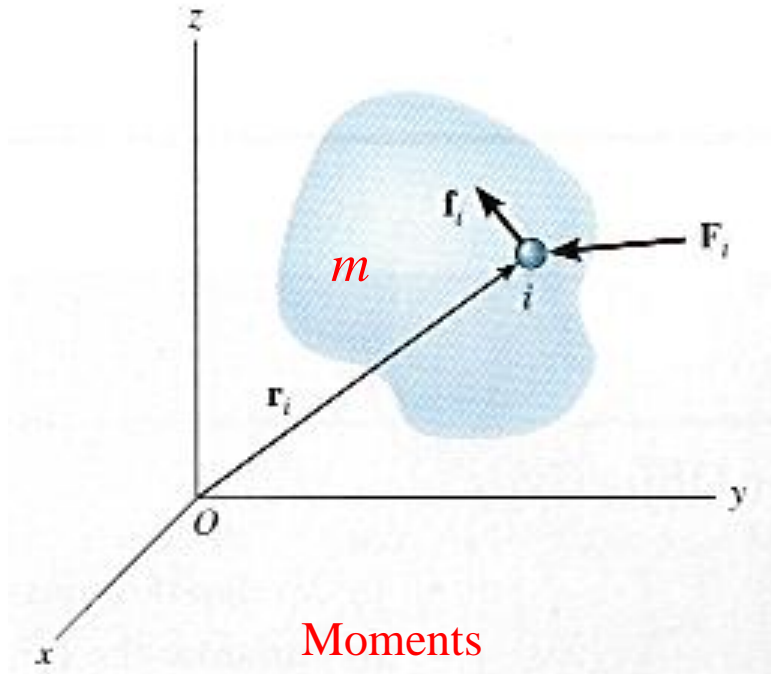
$$\sum \mathbf{M}_O = \mathbf{0}$$

Orthogonal components:

$$\sum M_{x_o} \mathbf{i} + \sum M_{y_o} \mathbf{j} + \sum M_{z_o} \mathbf{k} = 0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k}$$

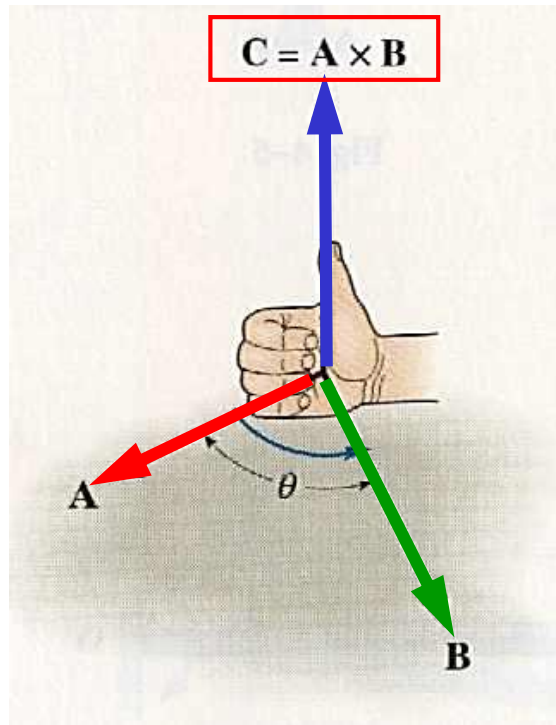
Vectorial evaluation:

$$\sum \mathbf{r}_i \times \mathbf{f}_i + \sum \mathbf{r}_i \times \mathbf{F}_i = \mathbf{0}$$



# Force analysis. Free-body diagrams

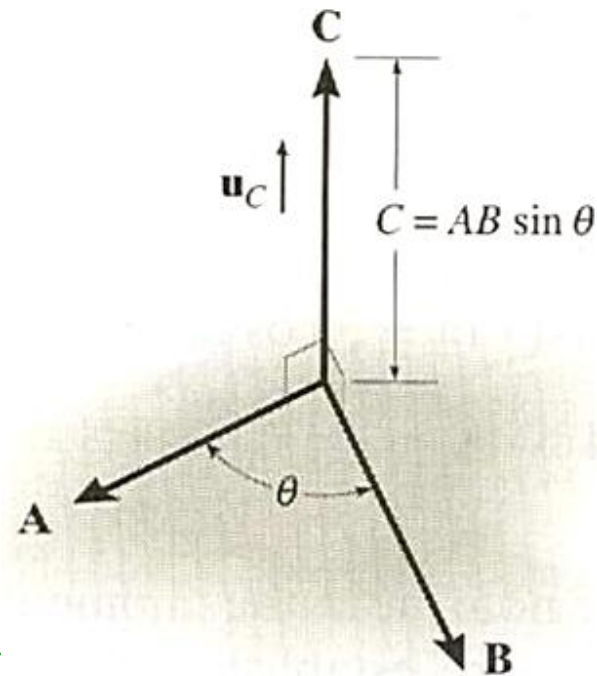
Static equilibrium: **moments**



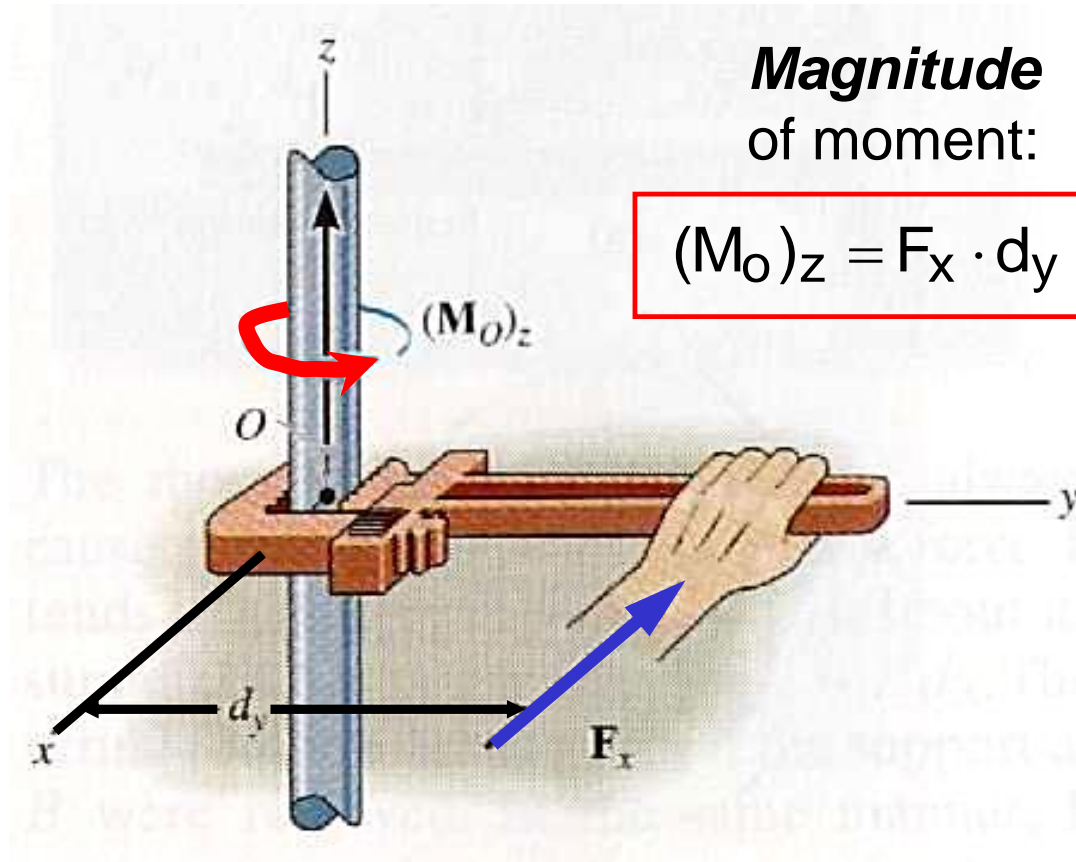
$$\mathbf{C} = \mathbf{A} \times \mathbf{B} = AB \sin(\theta) \mathbf{u}_C$$

Labels with arrows pointing to the equation:

- Vector (points to  $\mathbf{C}$ )
- Scalar (points to  $AB \sin(\theta)$ )
- Unit vector (points to  $\mathbf{u}_C$ )

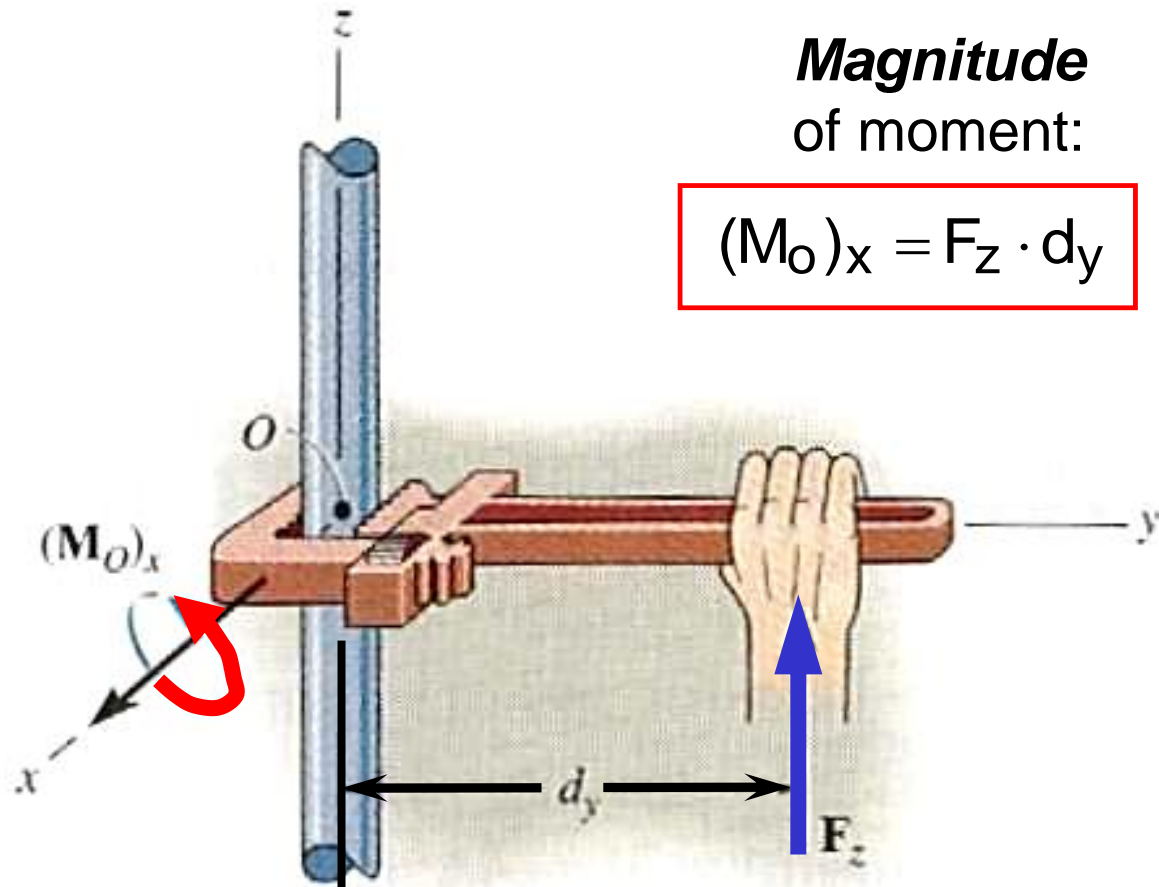


# Moment of a force: about $z$ -axis





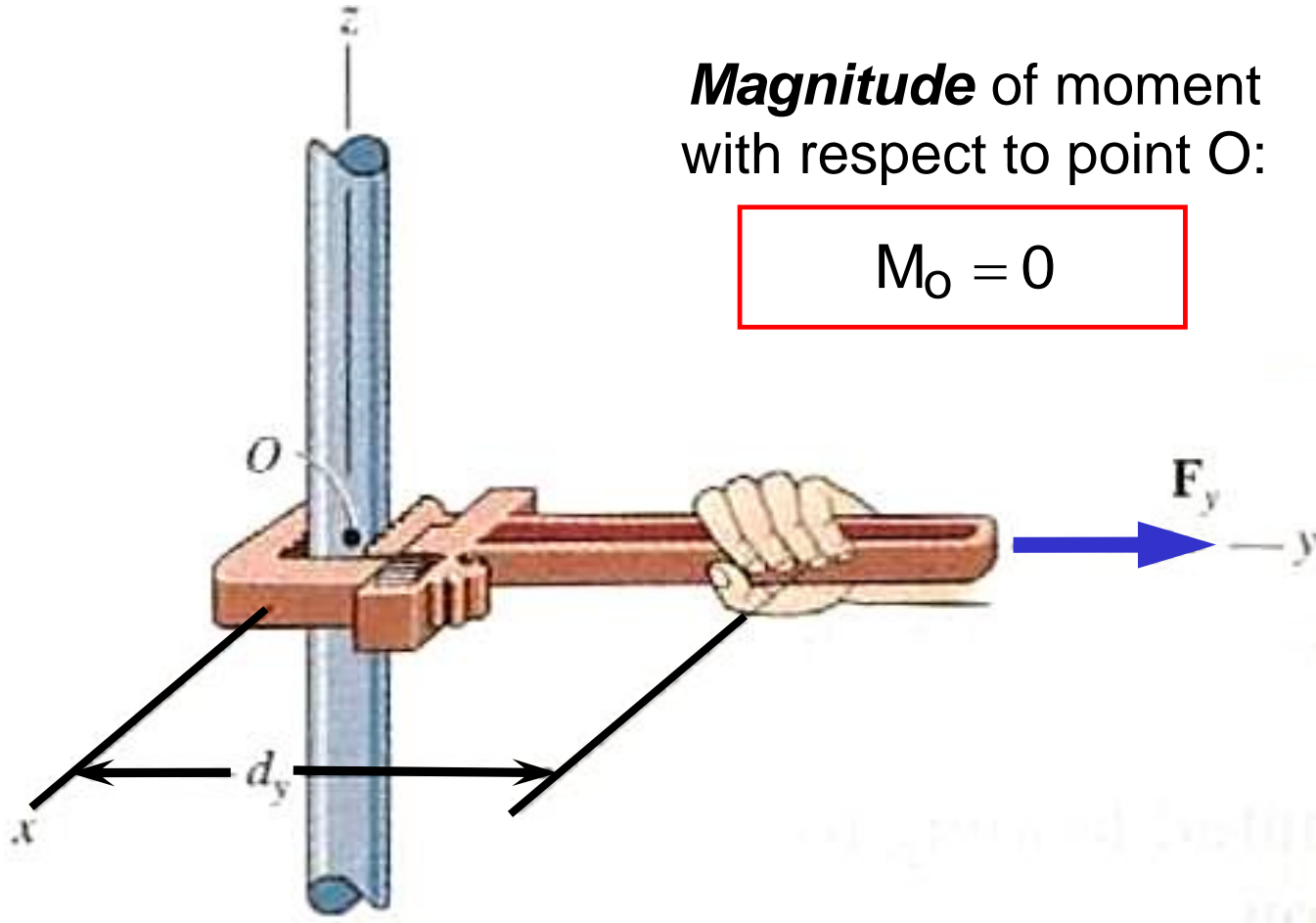
# Moment of a force: about $x$ -axis



# Moment of a force: null effect

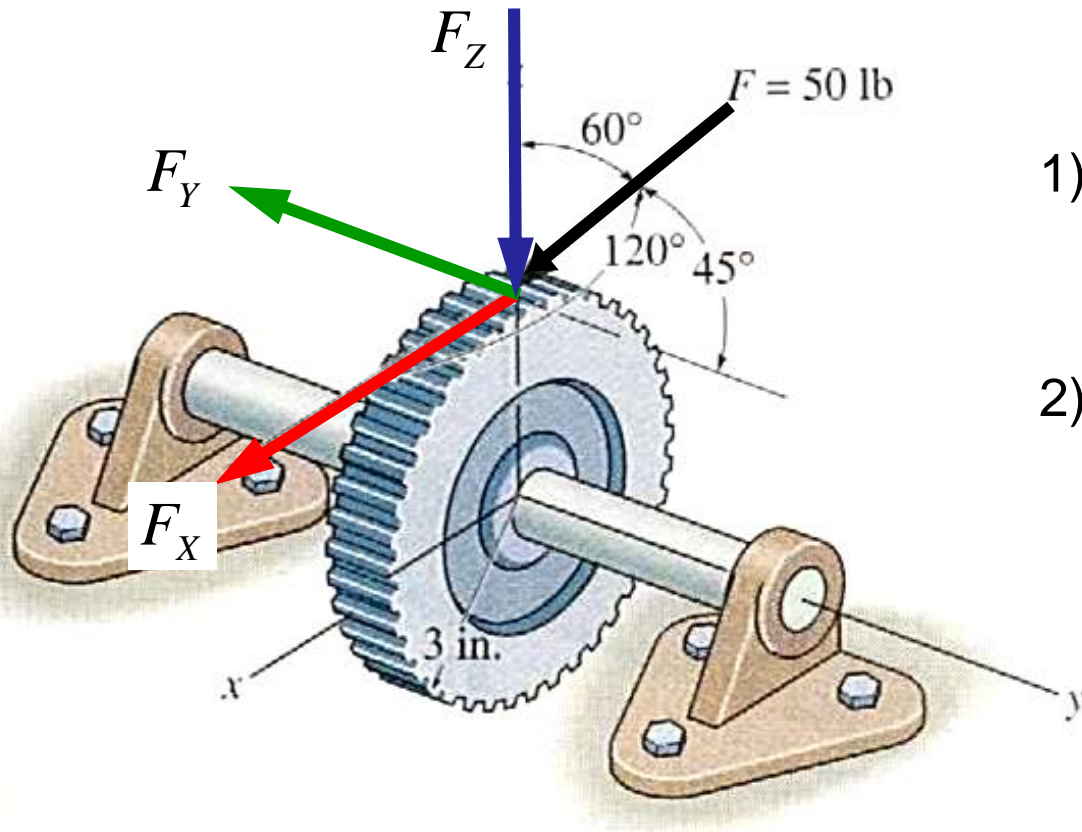
**Magnitude** of moment  
with respect to point O:

$$M_O = 0$$



# Force analysis: example

The 50 lb force acts on the gear in the direction shown. Determine the moment of this force about the  $y$ -axis.



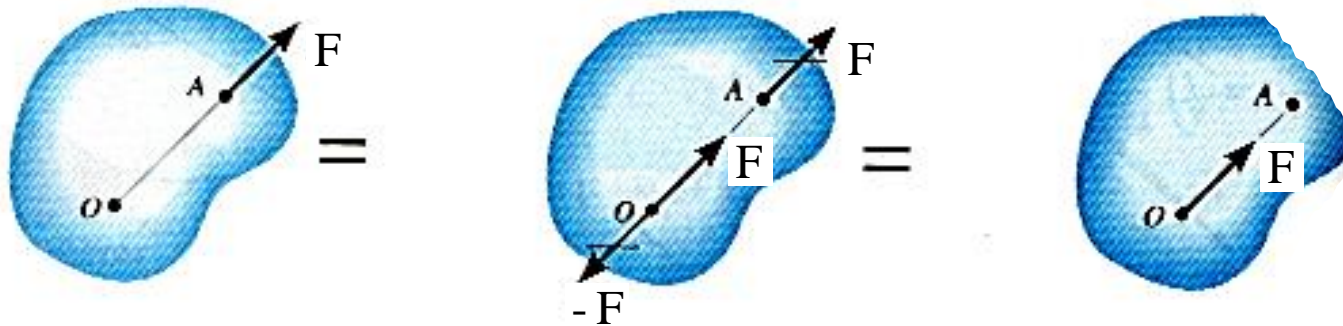
## Approach:

- 1) Determine  $x$ - $y$ - $z$  components of applied force
- 2) Compute moment about  $y$ -axis

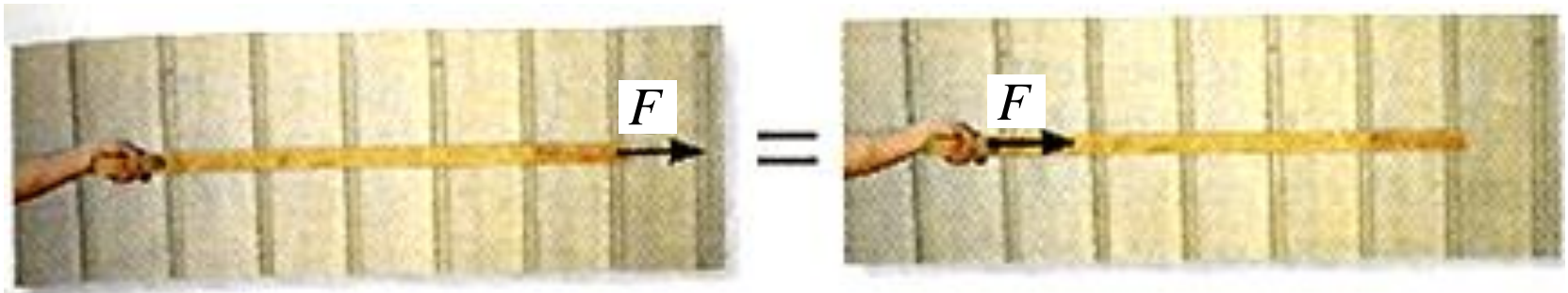


# Equivalent systems: **are they really?**

Force translated along its line of application:



Example:

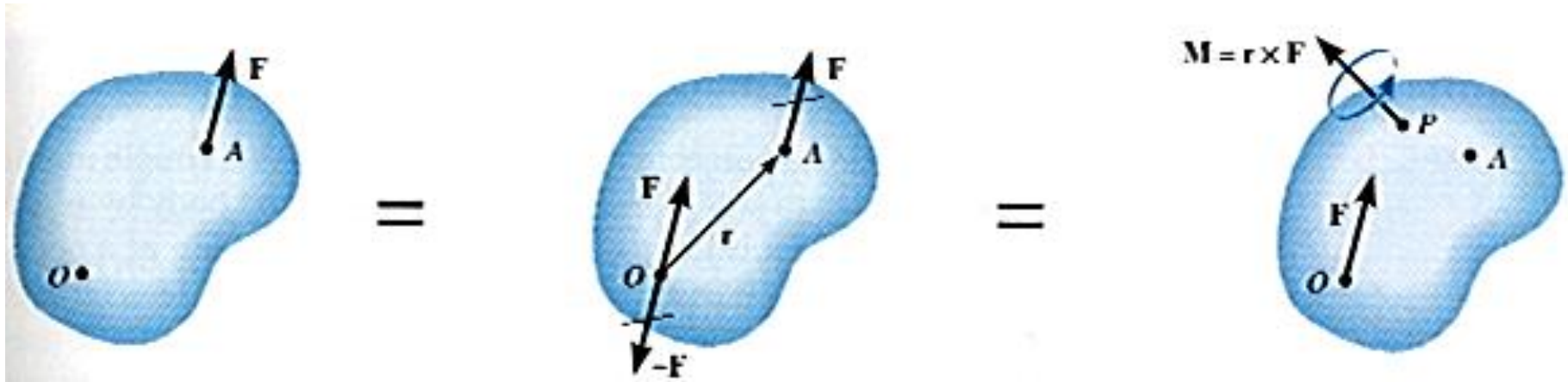


Idealization: similar effects at the support ??

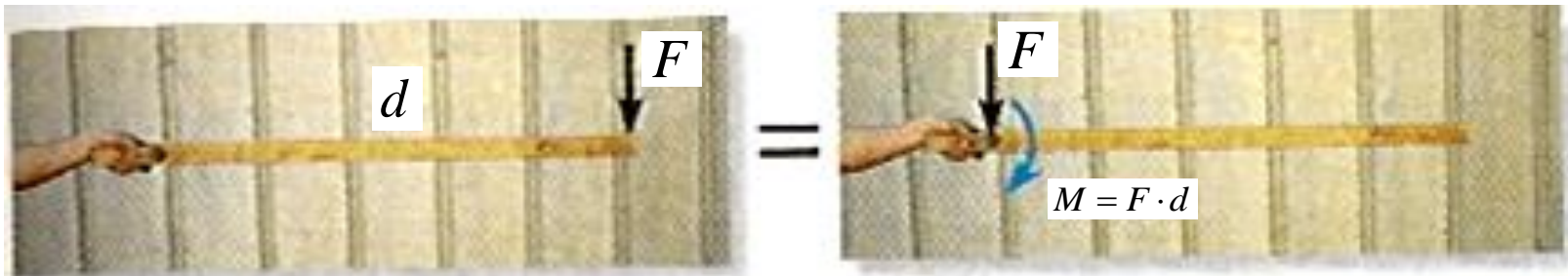


# Equivalent systems: **are they really?**

Equivalent force and couple/moment system:



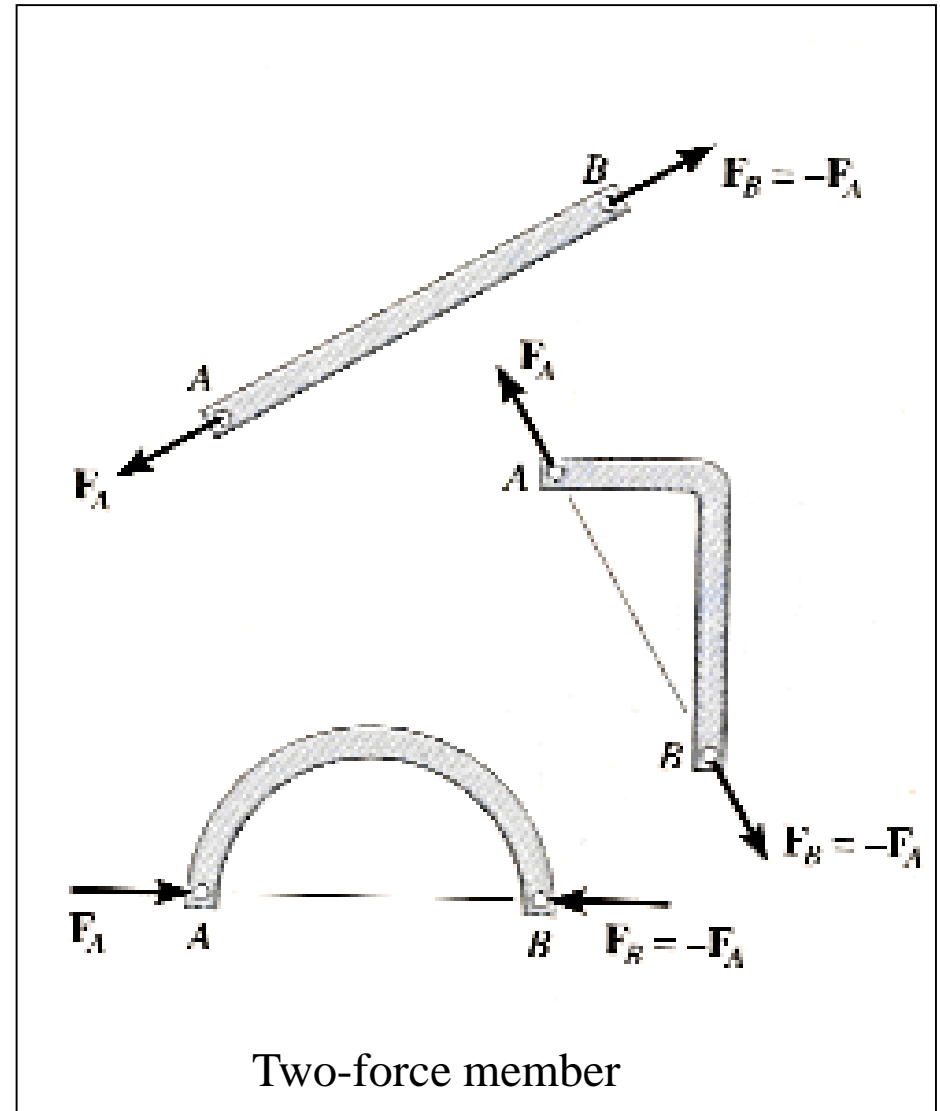
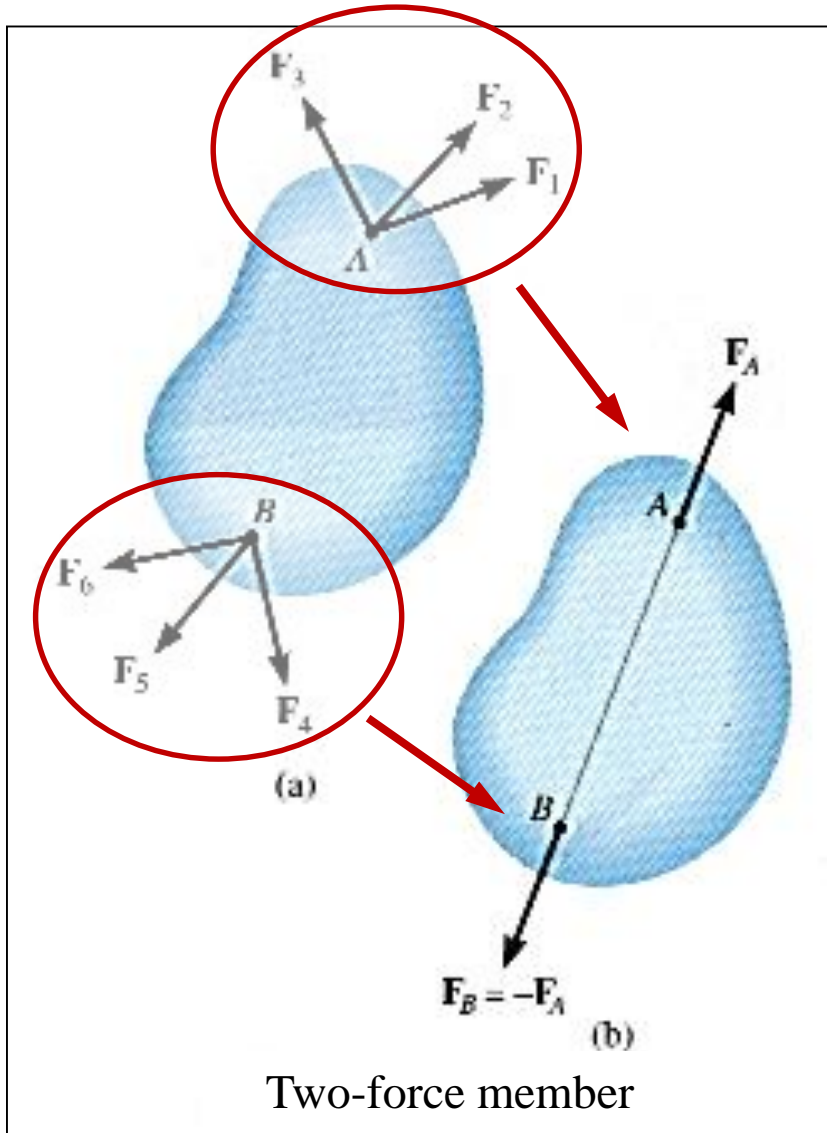
Example:



Idealization: similar effects at the support ??



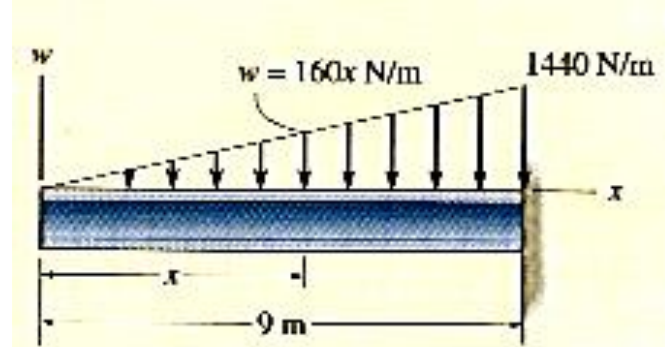
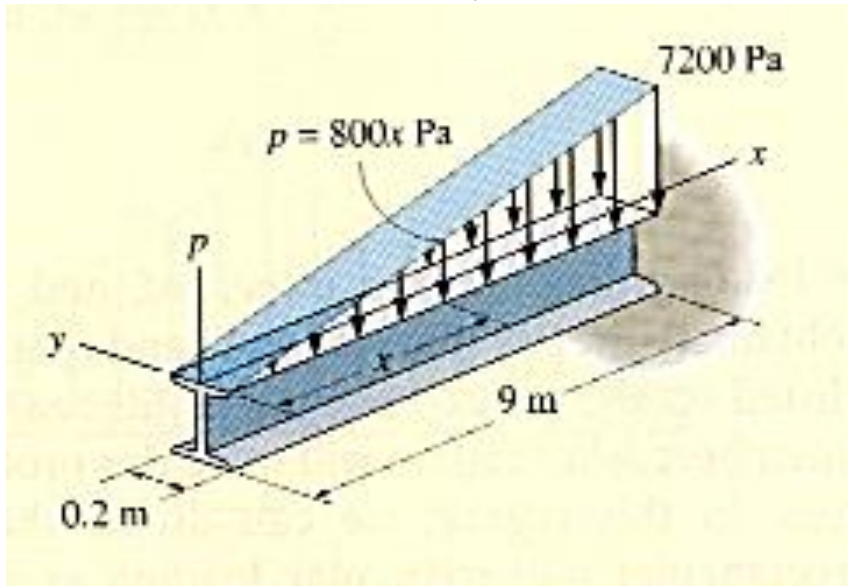
# Equilibrium of rigid bodies: equivalent systems



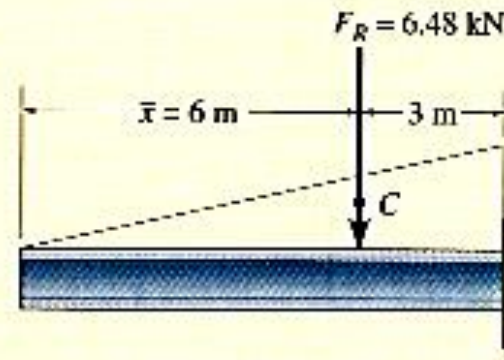


# Distributed loads: equivalent systems

Original 3D problem



2D projection

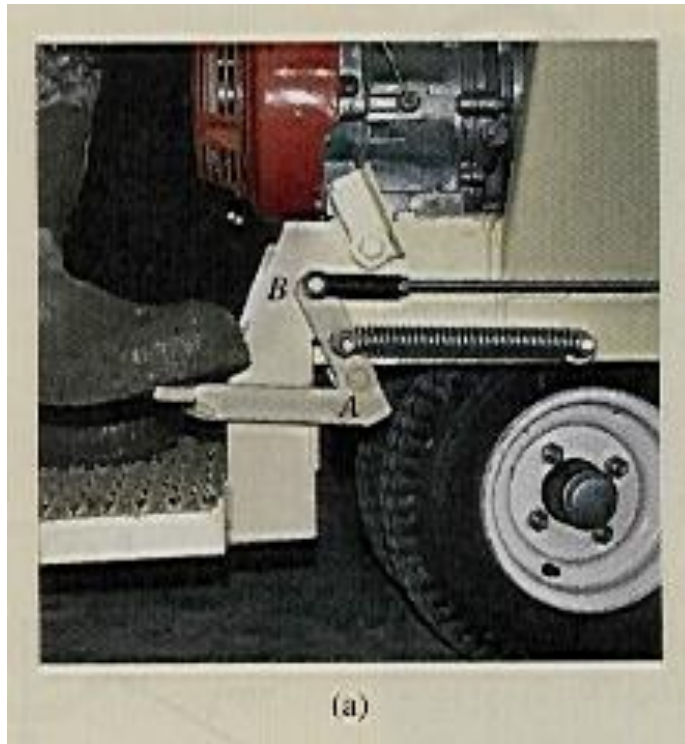


Equivalent system



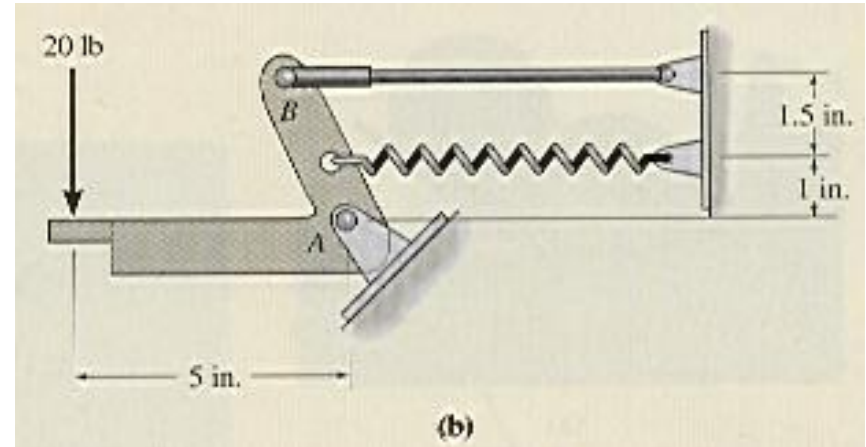
# Free-body diagrams

Operator applies 20-lb to pedal stretching spring by 1.5 in.

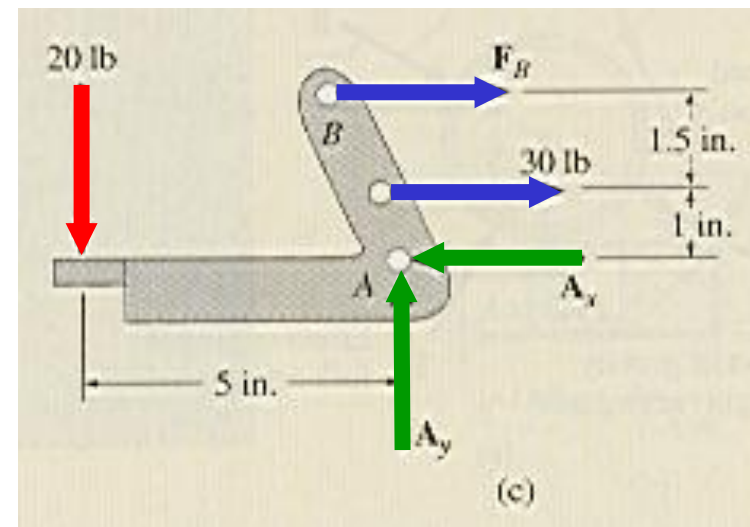


Actual mechanism

Schematic representation:



Free-body diagram:



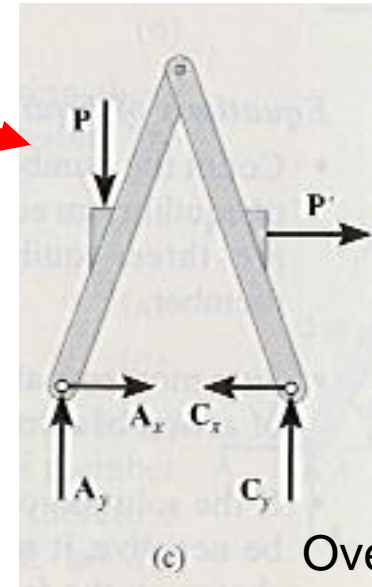
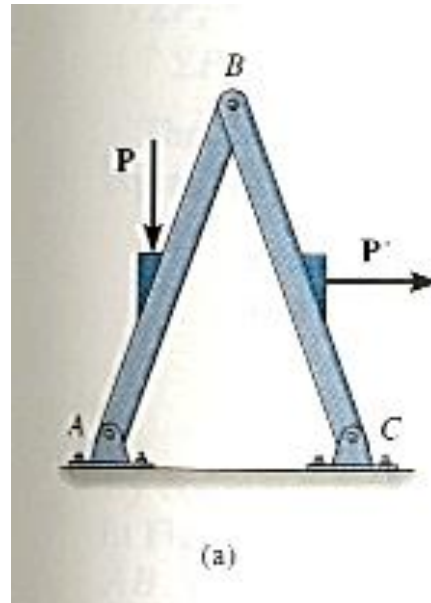


# Force analysis. Free-body diagrams

Number of unknowns ?

Equilib. Equations ?

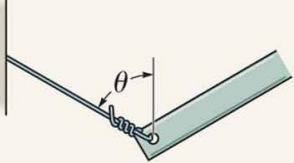
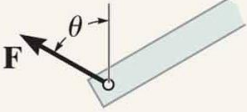








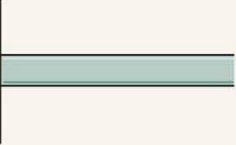
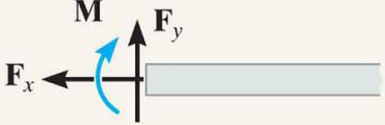
Is this a statically indetermined case ?



Overall FBD



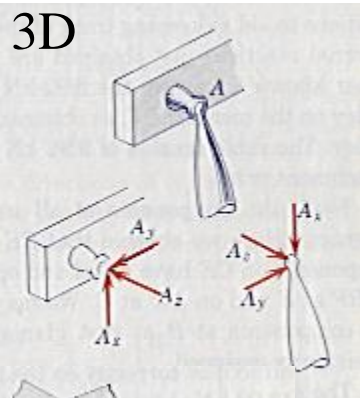
# Force analysis. Free-body diagrams

Type of connection	Reaction	Type of connection	Reaction
 <p>Cable</p>	 <p>One unknown: <math>F</math></p>	 <p>External pin</p>	 <p>Two unknowns: <math>F_x, F_y</math></p>
 <p>Roller</p>	 <p>One unknown: <math>F</math></p>	 <p>Internal pin</p>	 <p>Two unknowns: <math>F_x, F_y</math></p>
 <p>Smooth support</p>	 <p>One unknown: <math>F</math></p>	 <p>Fixed support</p>	 <p>Three unknowns: <math>F_x, F_y, M</math></p>

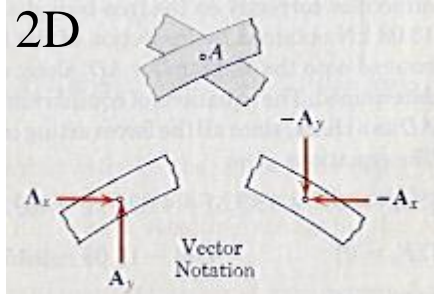


# Force analysis. Free-body diagrams

3D

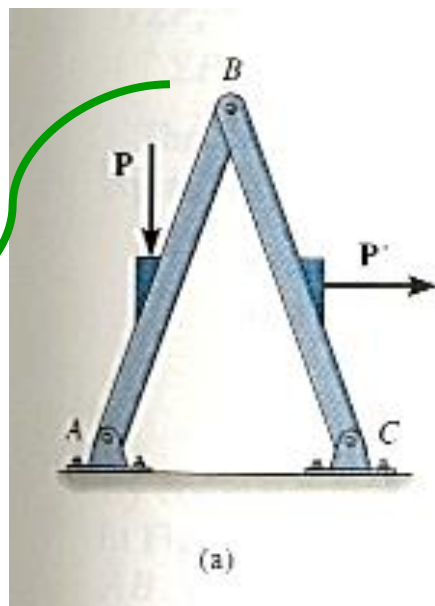


2D



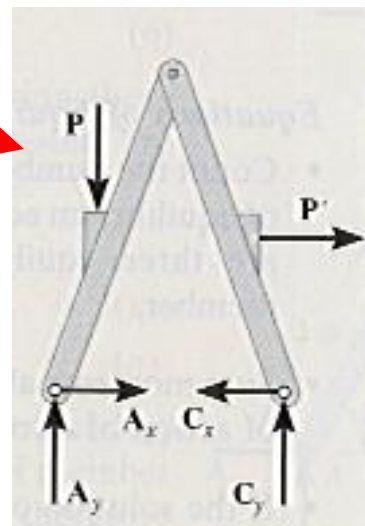
Number of unknowns ?

Equilib. Equations ?



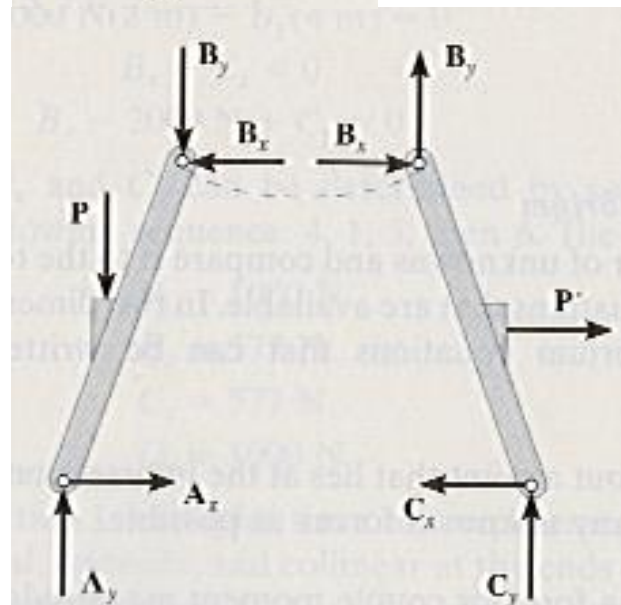
(a)

Individual FBD's



(c)

Overall FBD

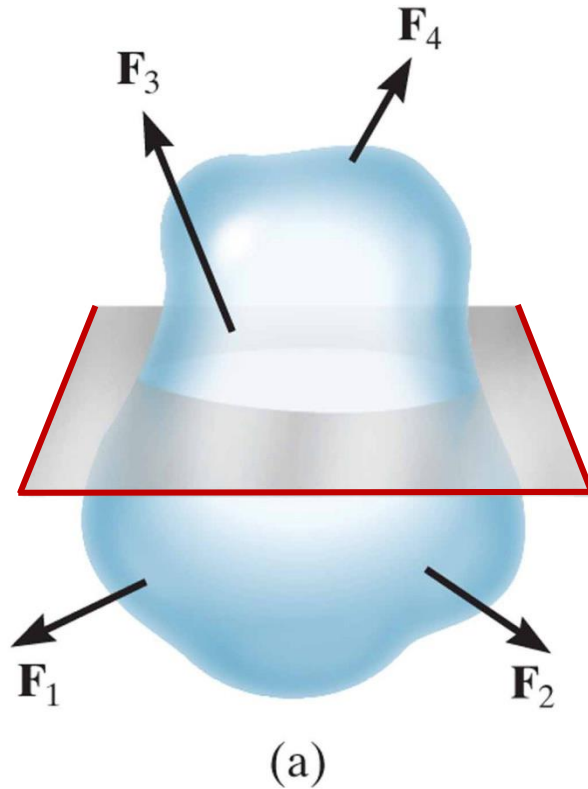


(b)



# Internal resultant loading

Arbitrary component  
under load

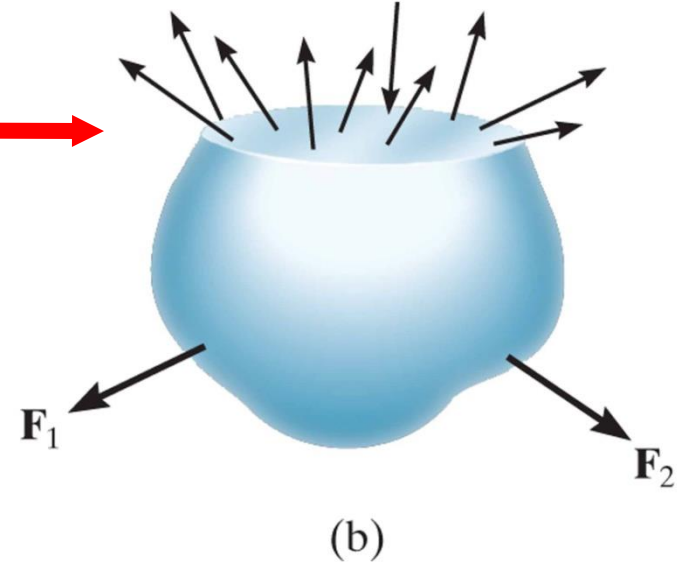


Component is in equilibrium

Virtual  
section

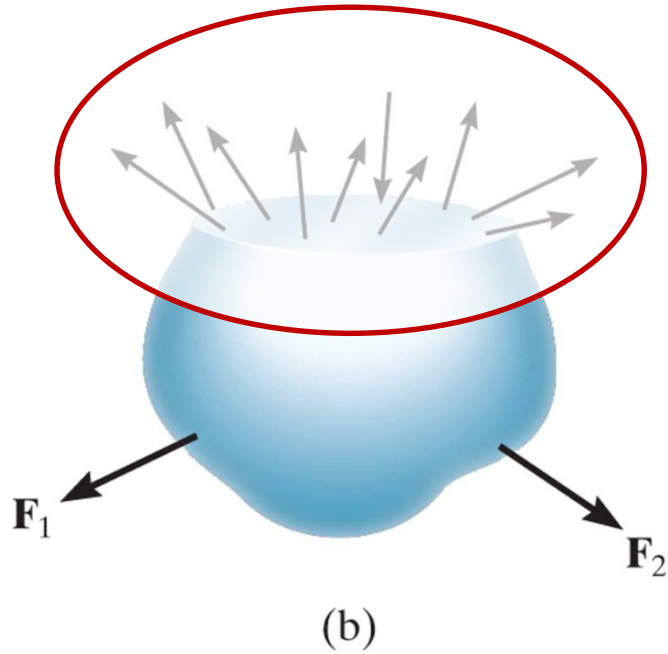


Internal forces  
maintaining equilibrium

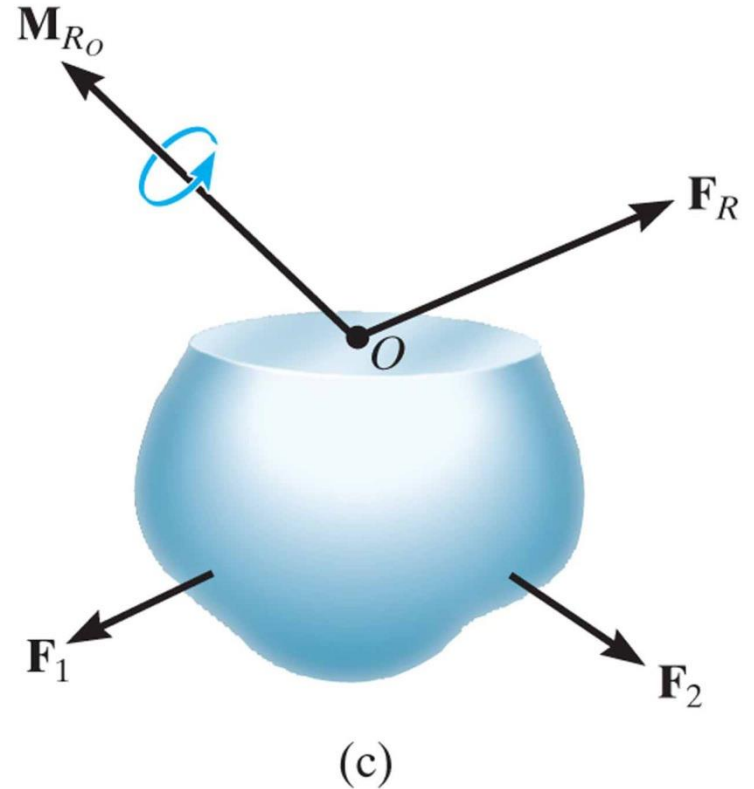


# Internal resultant loading

Internal forces  
maintaining equilibrium

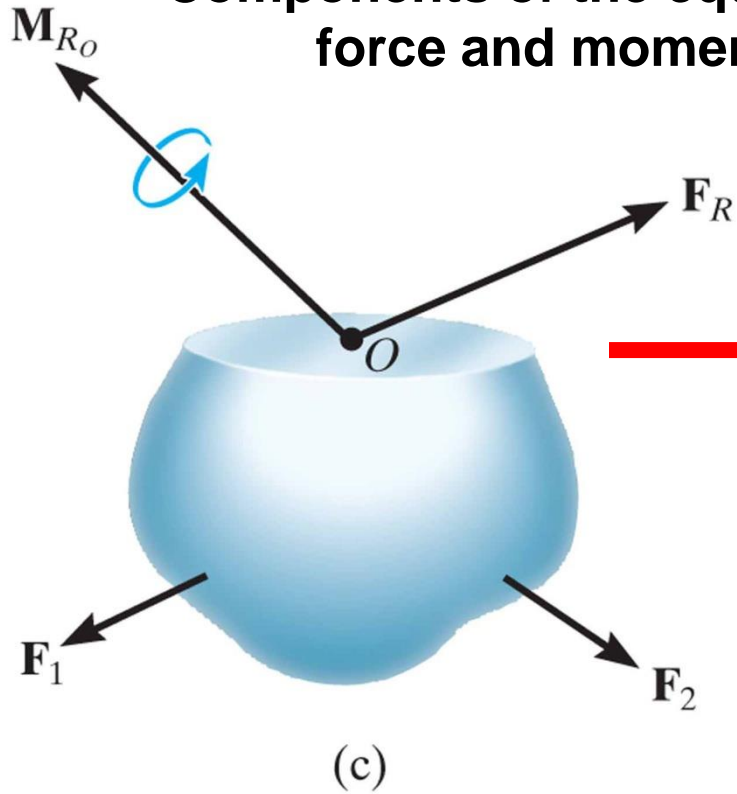


Equivalent  
force and  
moment at  
the section

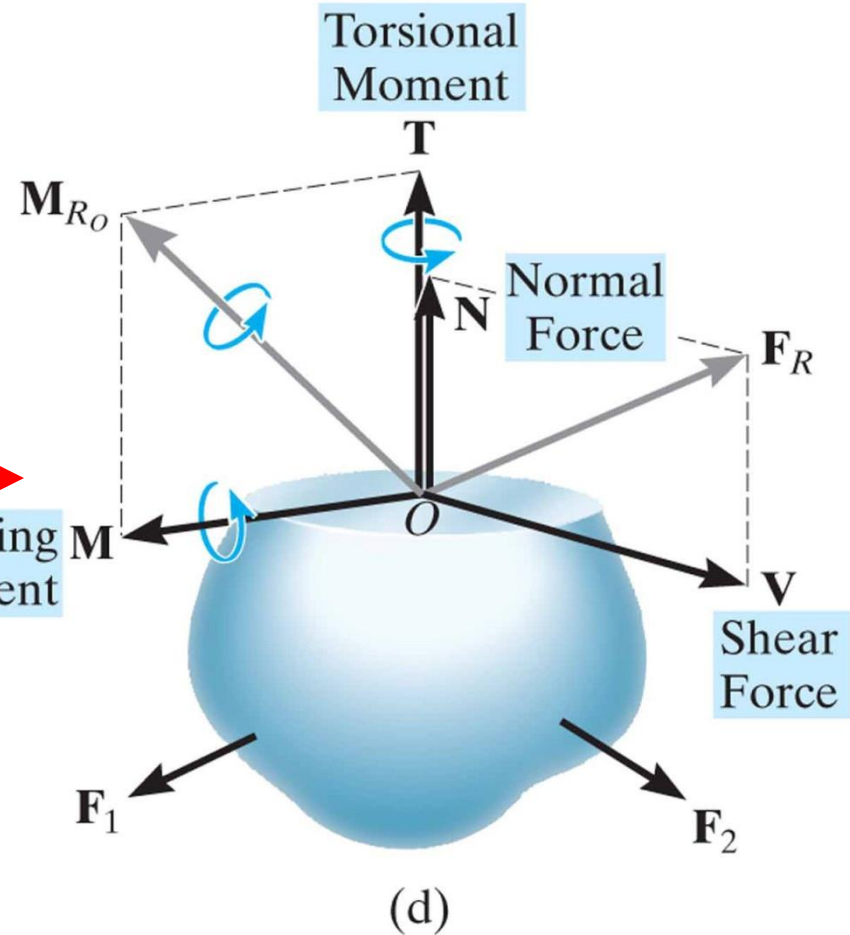


# Internal resultant loading

## Components of the equivalent force and moment



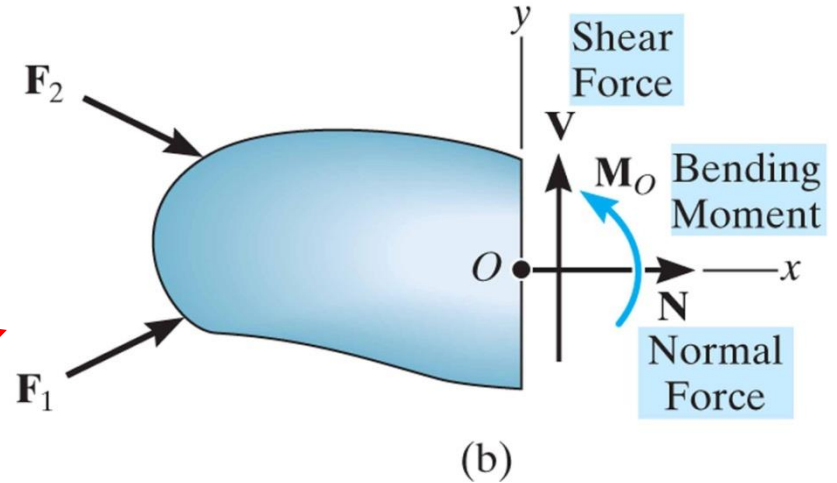
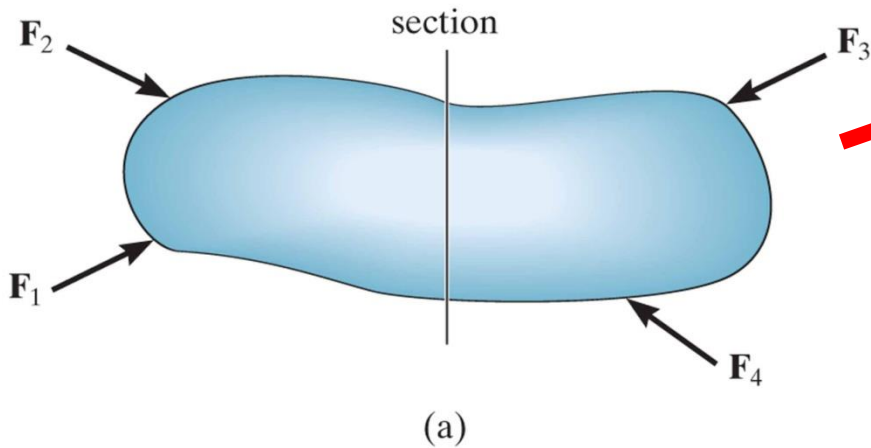
Bending Moment  $M$



# Internal resultant loading

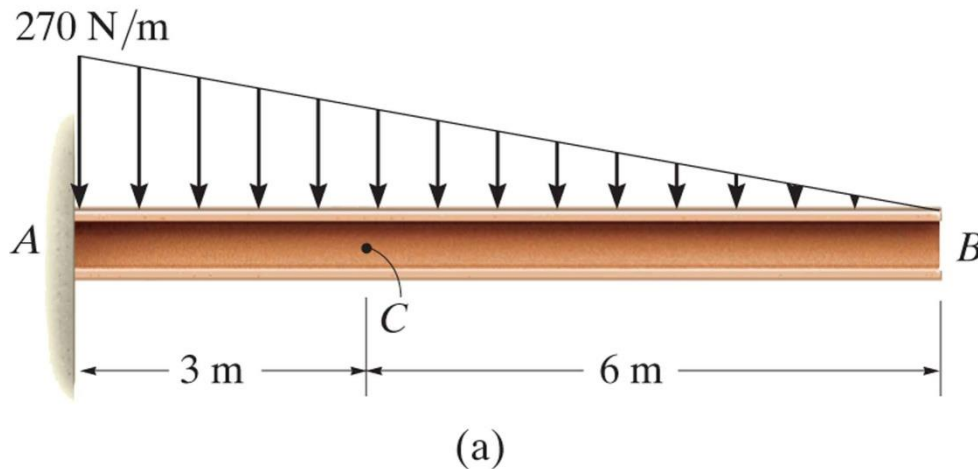
Equivalent forces and moments at the section

Component is in equilibrium



# Internal resultant loading: example

Determine resultant internal loading acting on the cross section at  $C$  of the cantilever shown:



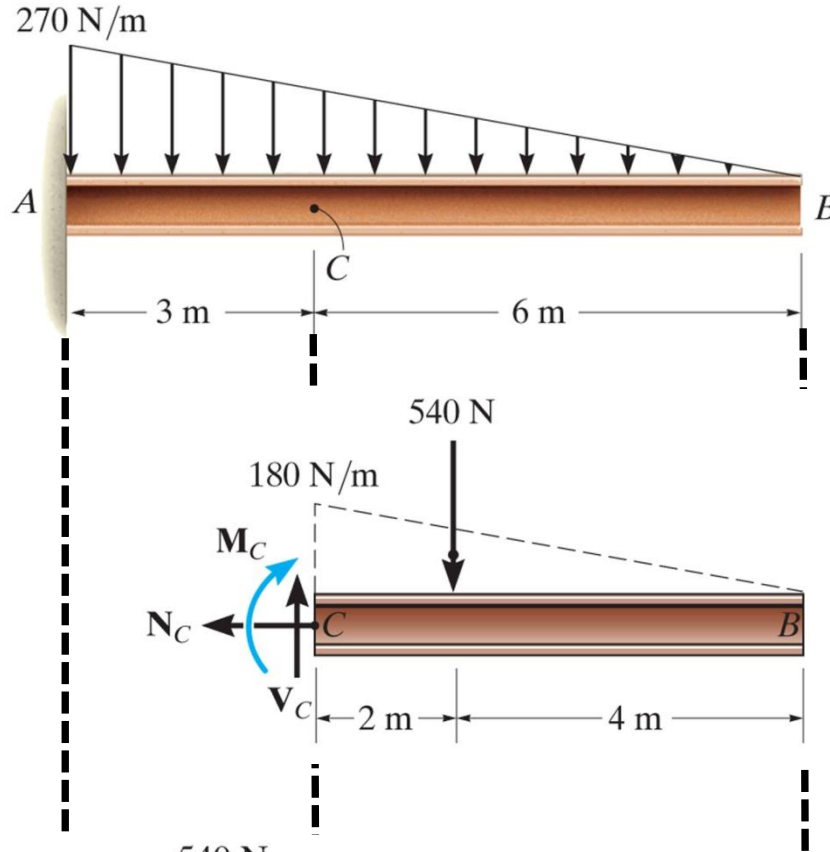
## Approach:

- 1) Define free-body diagrams
- 2) Apply equilibrium equations

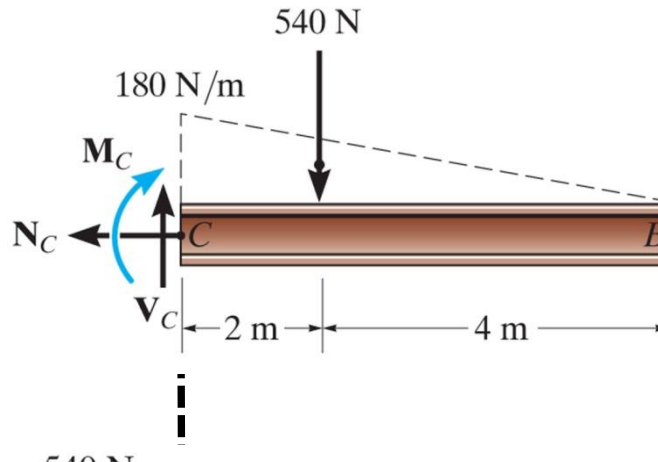




# Internal resultant loading: example

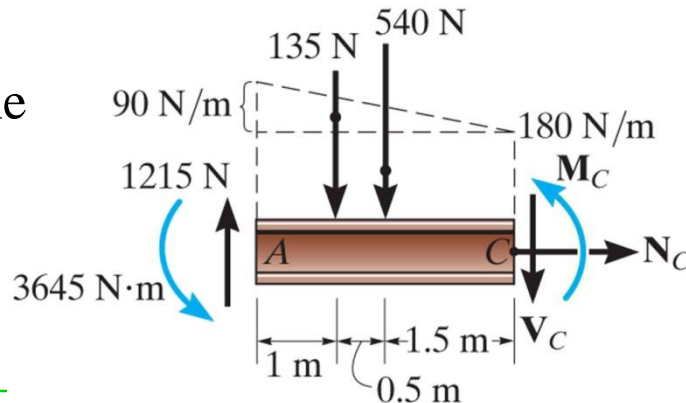


Free-body diagrams (FBDs):



Section to the right of C

Section to the left of C



Use either section to determine internal loadings



# Reading assignment

- Chapter 1 of textbook
- Review notes and text: ES2001, ES2501



# Homework assignment

- As indicated on webpage of our course

