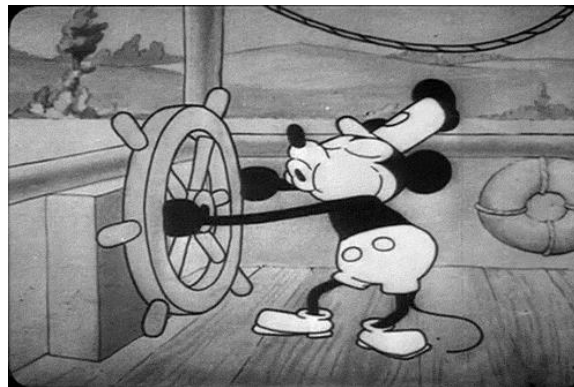


# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

## STRESS ANALYSIS ES-2502, B'2025

**We will get started soon...**



**18 November 2025**



# WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

## STRESS ANALYSIS ES-2502, B'2025

Lecture 17:  
Unit 12: Torsion of shafts:  
circular cross-section: *power transmission*

18 November 2025



# General information

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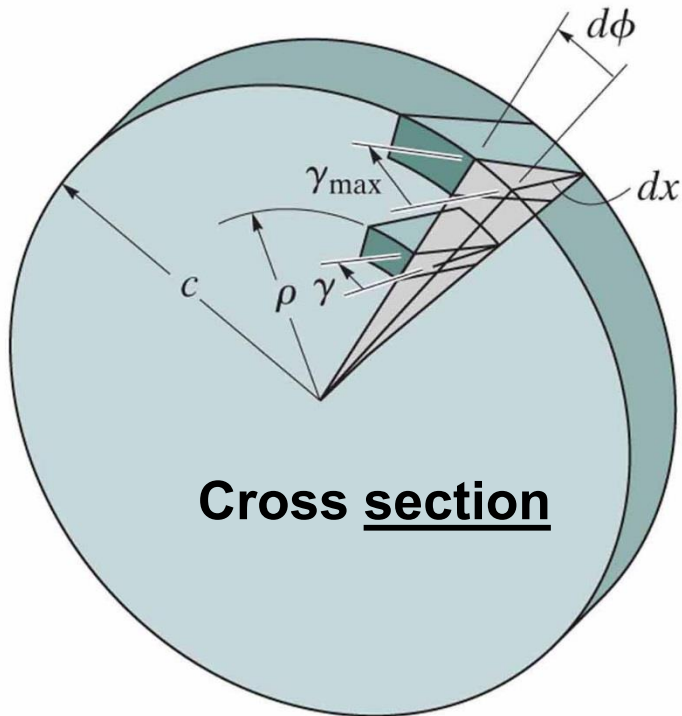
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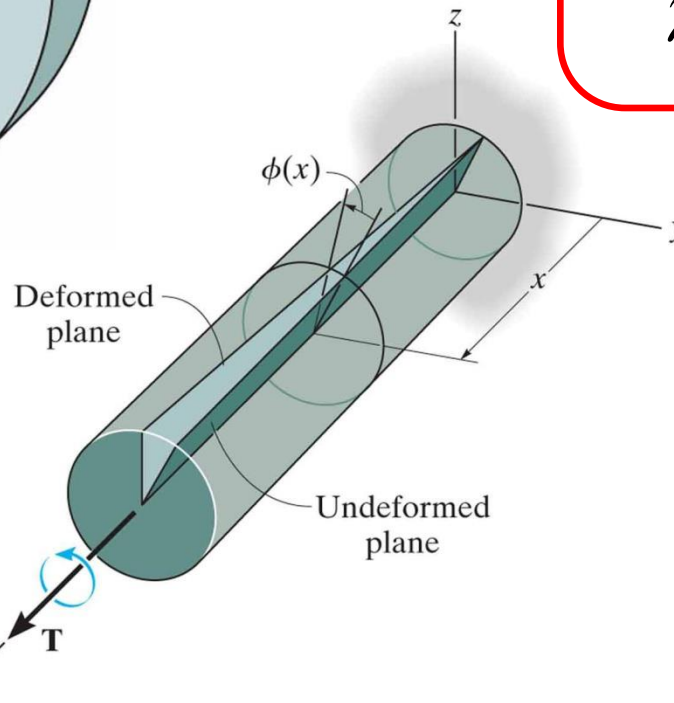
# Torsion: shear strains



$$\frac{\gamma}{\rho} = \frac{\gamma_{\max}}{c}$$

**Shear strains vary linearly within a section:**

$$\gamma = \gamma(\rho) = \rho \frac{\gamma_{\max}}{c}$$



The angle of twist  $\phi(x)$  increases as  $x$  increases.

# Torsion formula

**Shear stresses** also **vary linearly within a section:**

*According to Hook's law  
(linear elasticity):*

$$(\tau = G \cdot \gamma)$$

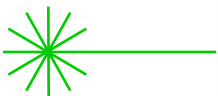
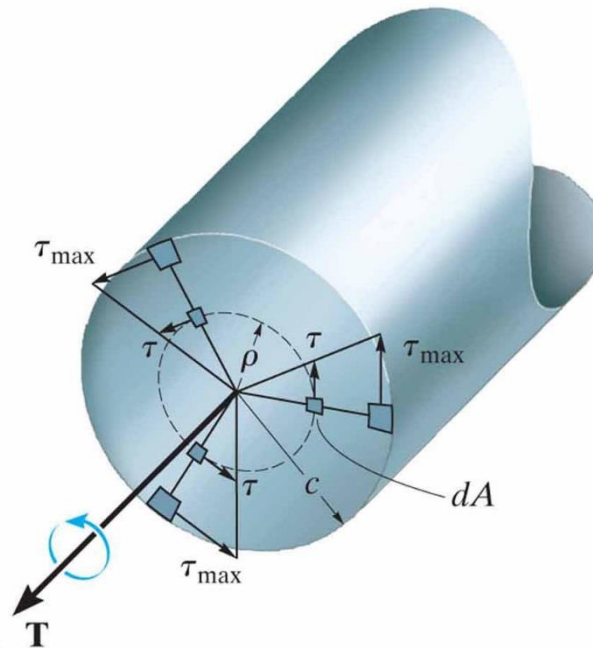
$$\tau = \tau(\rho) = \rho \frac{\tau_{\max}}{c}$$

**Differential Force:**

$$dF = \tau \cdot dA$$

**Differential Torque:**

$$dT = \rho (\tau \cdot dA)$$



# Torsion formula

Integrating torque: 
$$T = \int_A \rho (\tau \cdot dA) = \int_A \rho \left( \rho \frac{\tau_{\max}}{c} \right) dA$$
$$= \frac{\tau_{\max}}{c} \int_A \rho^2 dA$$

Define: 
$$J = \int_A \rho^2 dA$$
 ← Polar area moment of inertia

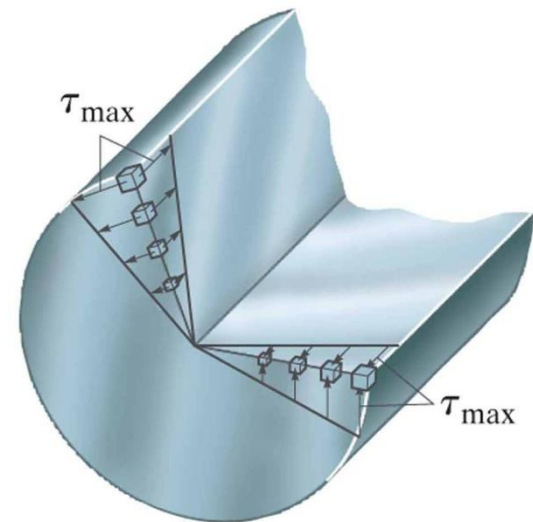
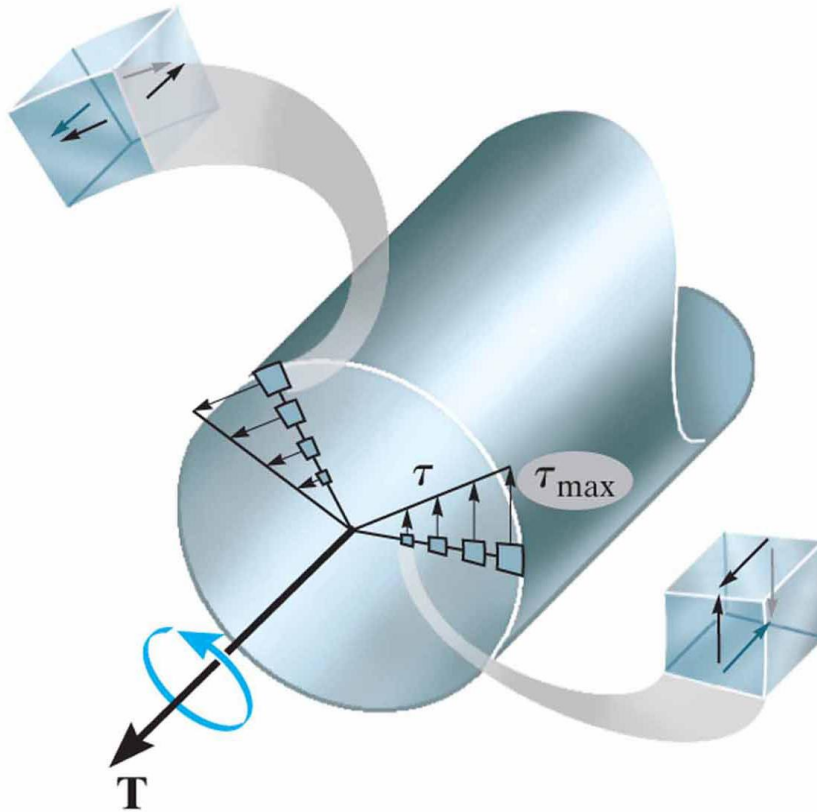
**Torsion formula for stresses:**  
**(linear elastic)**

$$\tau_{\max} = \frac{T c}{J} \quad \text{and} \quad \tau = \tau(\rho) = \frac{T \rho}{J}$$



# Torsion formula: solid circular bar

## Linear variation of shear stress

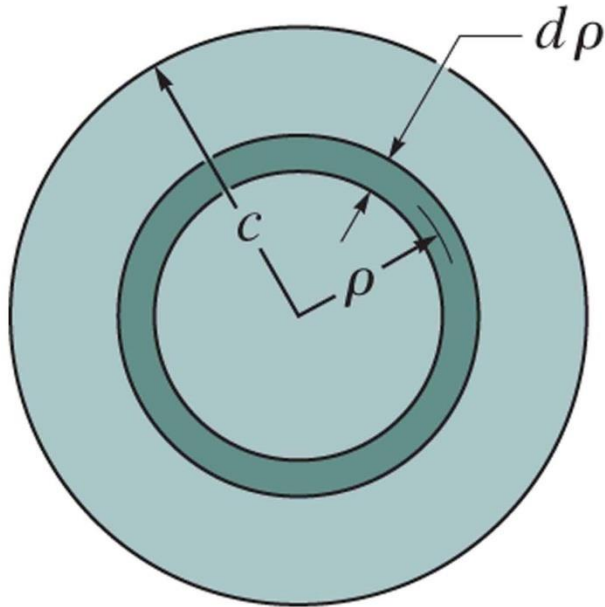


Shear stress varies linearly along each radial line of the cross section.



# Torsion formula: polar area moment of inertia

Solid bar



$$J = \int_A \rho^2 dA$$

$$= \int_0^c \rho^2 (2\pi \rho d\rho)$$

$$= 2\pi \int_0^c \rho^3 d\rho = 2\pi \left( \frac{\rho^4}{4} \right)_0^c$$

**Solid, circular,  
section:**

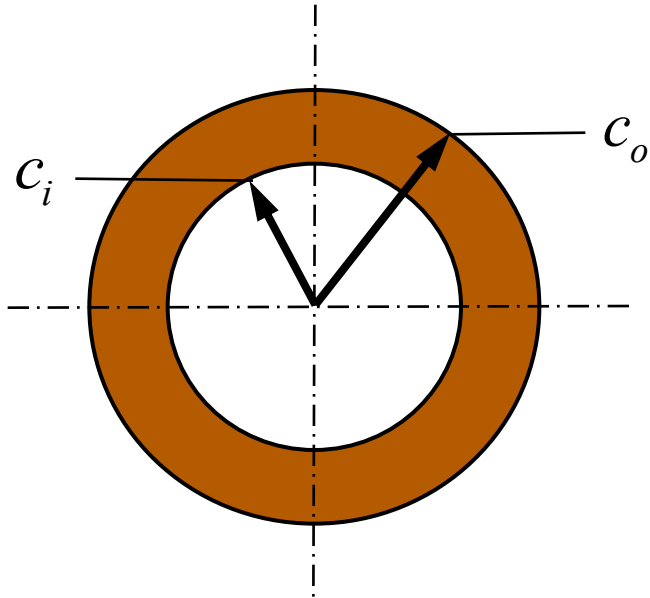
$$J = \frac{\pi}{2} c^4$$





# Torsion formula: polar area moment of inertia

## Tubular bar



$$J = \int_A \rho^2 dA$$

$$= \int_{c_i}^{c_o} \rho^2 (2\pi \rho d\rho)$$

$$= 2\pi \int_{c_i}^{c_o} \rho^3 d\rho = 2\pi \left( \frac{\rho^4}{4} \right)_{c_i}^{c_o}$$

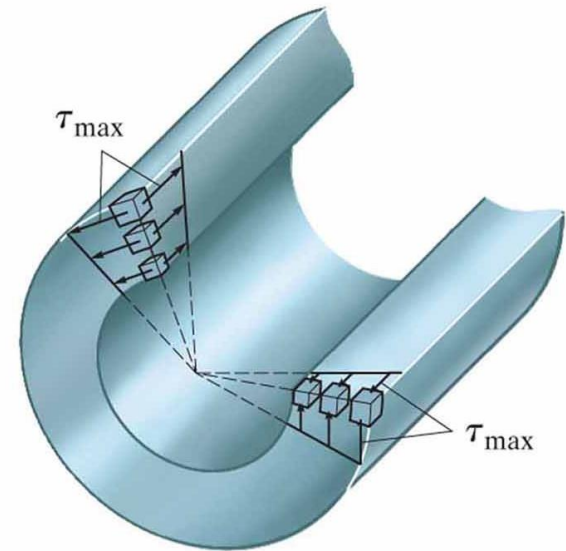
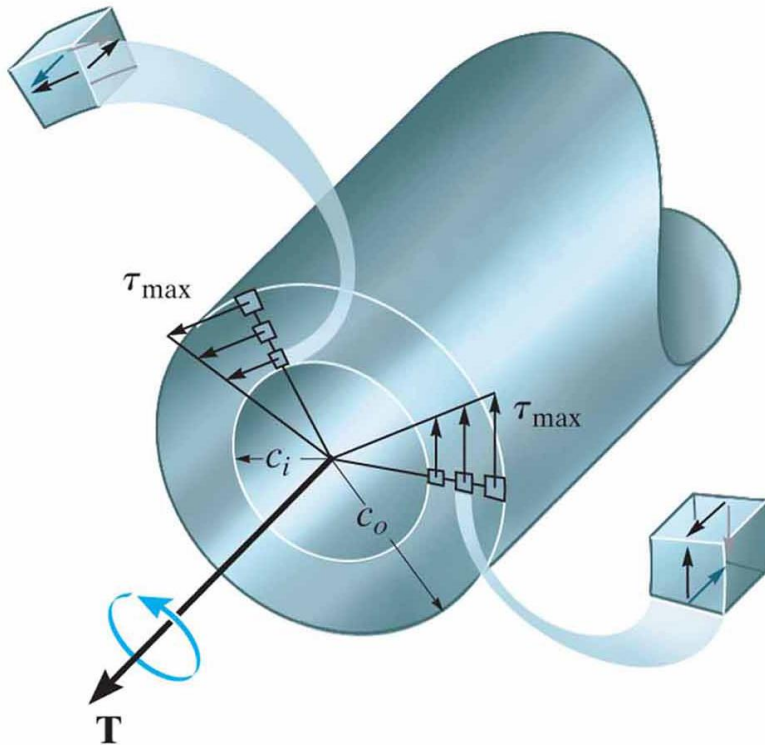
**Tubular  
section:**

$$J = \frac{\pi}{2} (c_o^4 - c_i^4)$$



# Torsion formula: tubular bar

## Linear variation of shear stress



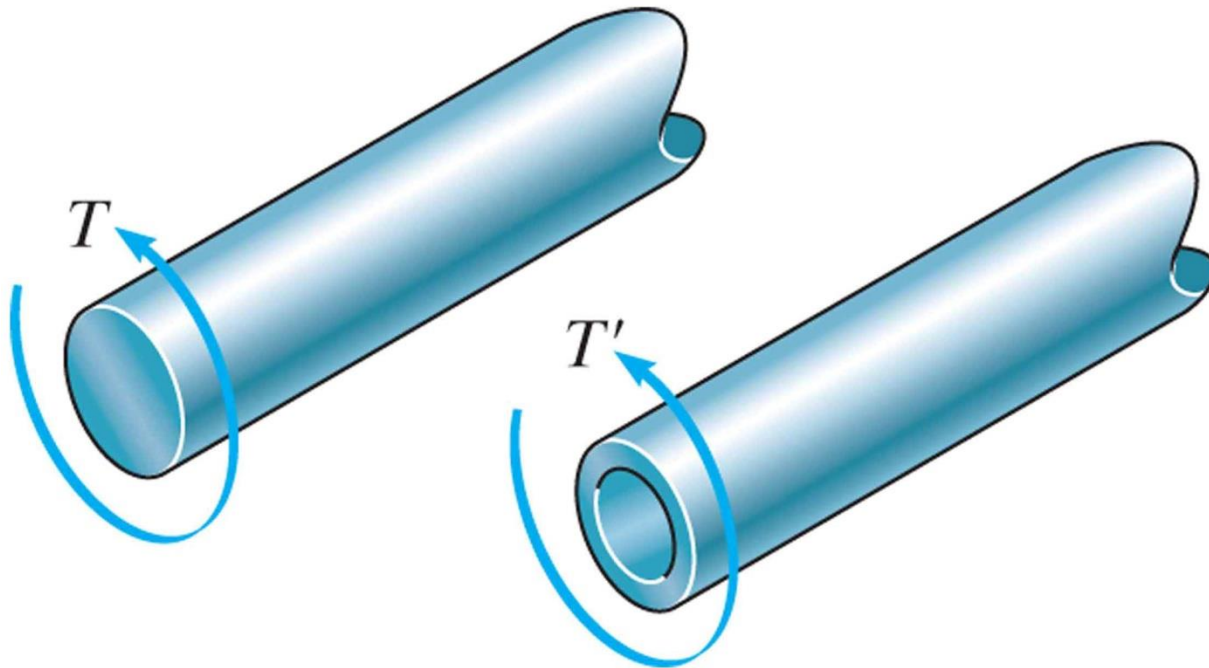
Shear stress varies linearly along each radial line of the cross section.



## Torsion: example A

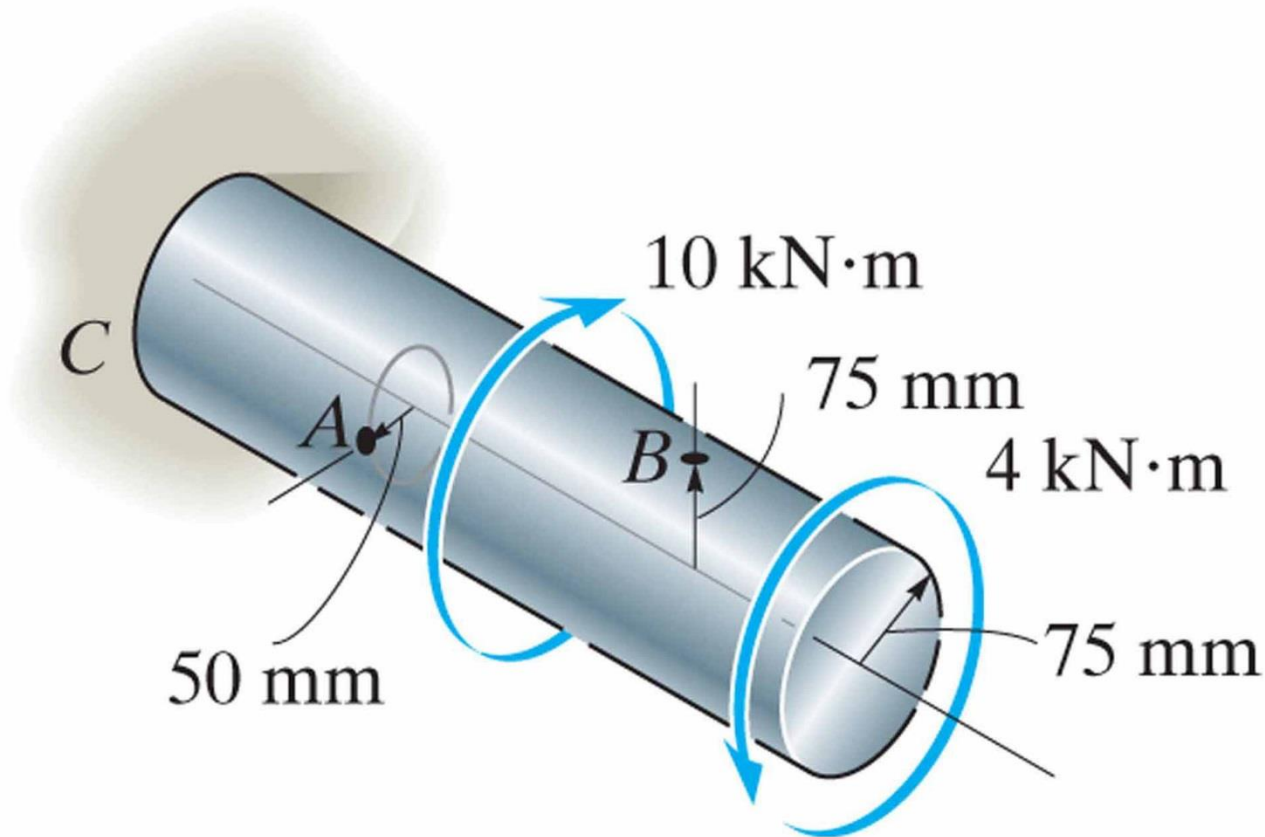
A shaft is made of a steel alloy having an allowable shear stress of  $\tau_{\text{allow}} = 12 \text{ ksi}$ . If the diameter of the shaft is 1.5 in., determine the maximum torque  $T$  that can be transmitted.

What would be the maximum torque  $T'$  if a 1-in. diameter hole is bored through the shaft? Sketch the shear-stress distribution *along a radial line* in each case.



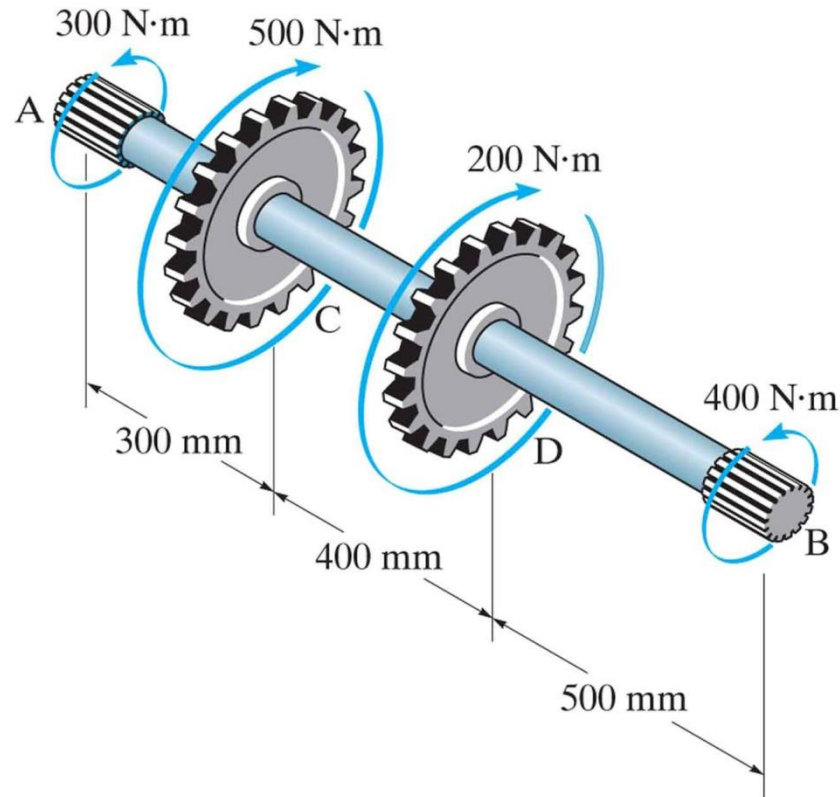
## Torsion: example B

The solid shaft is fixed to the support at  $C$  and subjected to the torsional loadings shown. Determine the shear stress at points  $A$  and  $B$  and sketch the shear stress on volume (stress) elements located at these points.



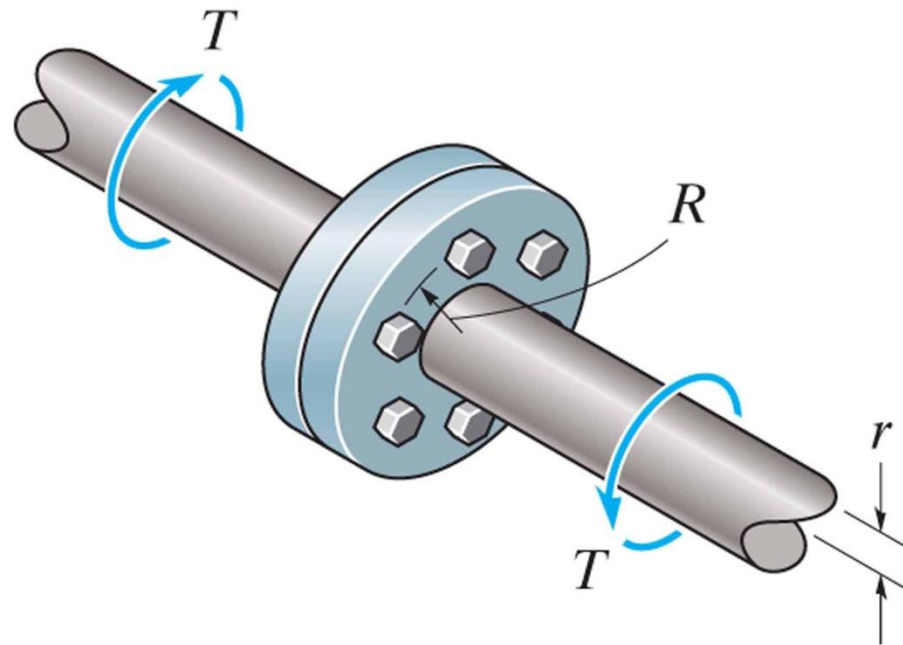
## Torsion: example C

The solid 30 mm diameter shaft is used to transmit the torques applied to the gears. Determine the absolute maximum shear stress on the shaft.

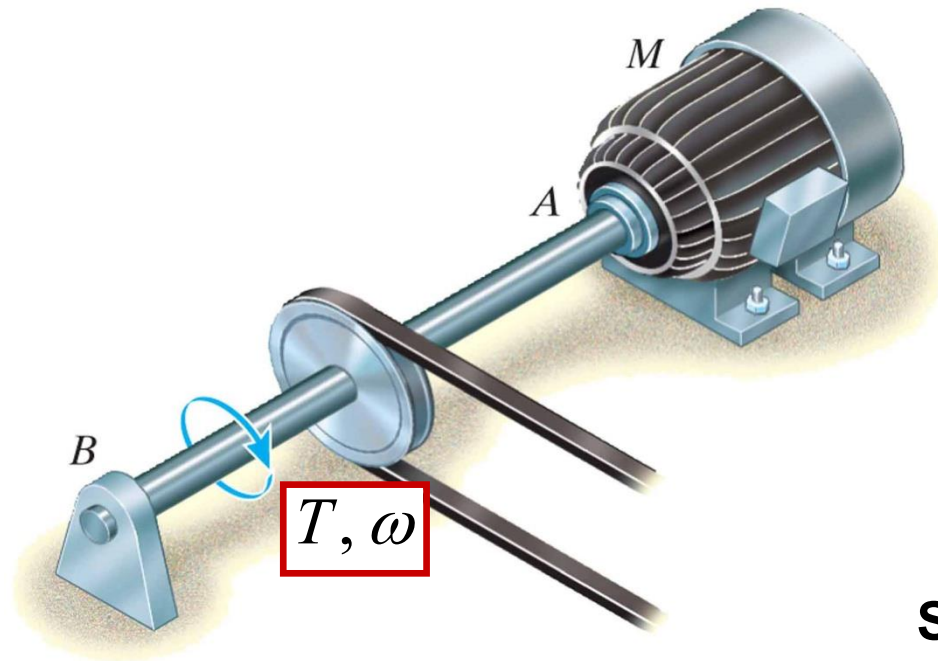


## Torsion: example D

The coupling is used to connect the two shafts together. Assuming that the shear stress in the bolts is *uniform*, determine the number of bolts necessary to make the maximum shear stress in the shaft equal to the shear stress in the bolts. Each bolt has a diameter  $d$ .



# Power transmission



$$P = T \omega$$

with:

$$\omega = 2\pi \cdot f$$

$$\omega \left[ \frac{\text{rad}}{\text{sec}} \right]$$

$$f [\text{Hz}]$$

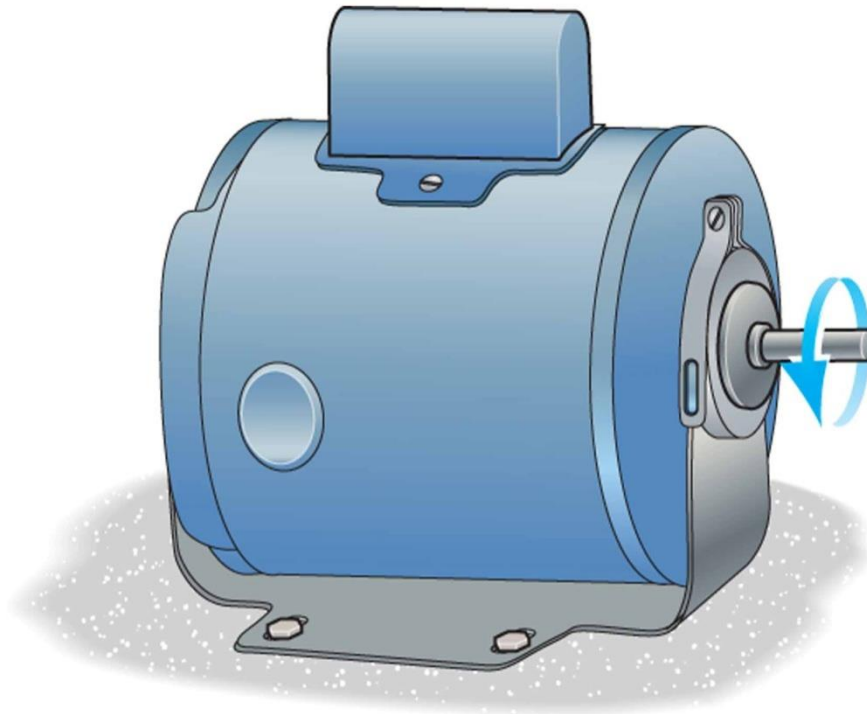
$$\text{SI: } 1W = 1N \cdot \frac{m}{s}$$

$$\text{FPS: } 1hp = 550 \text{ ft} \cdot \frac{lb}{s}$$



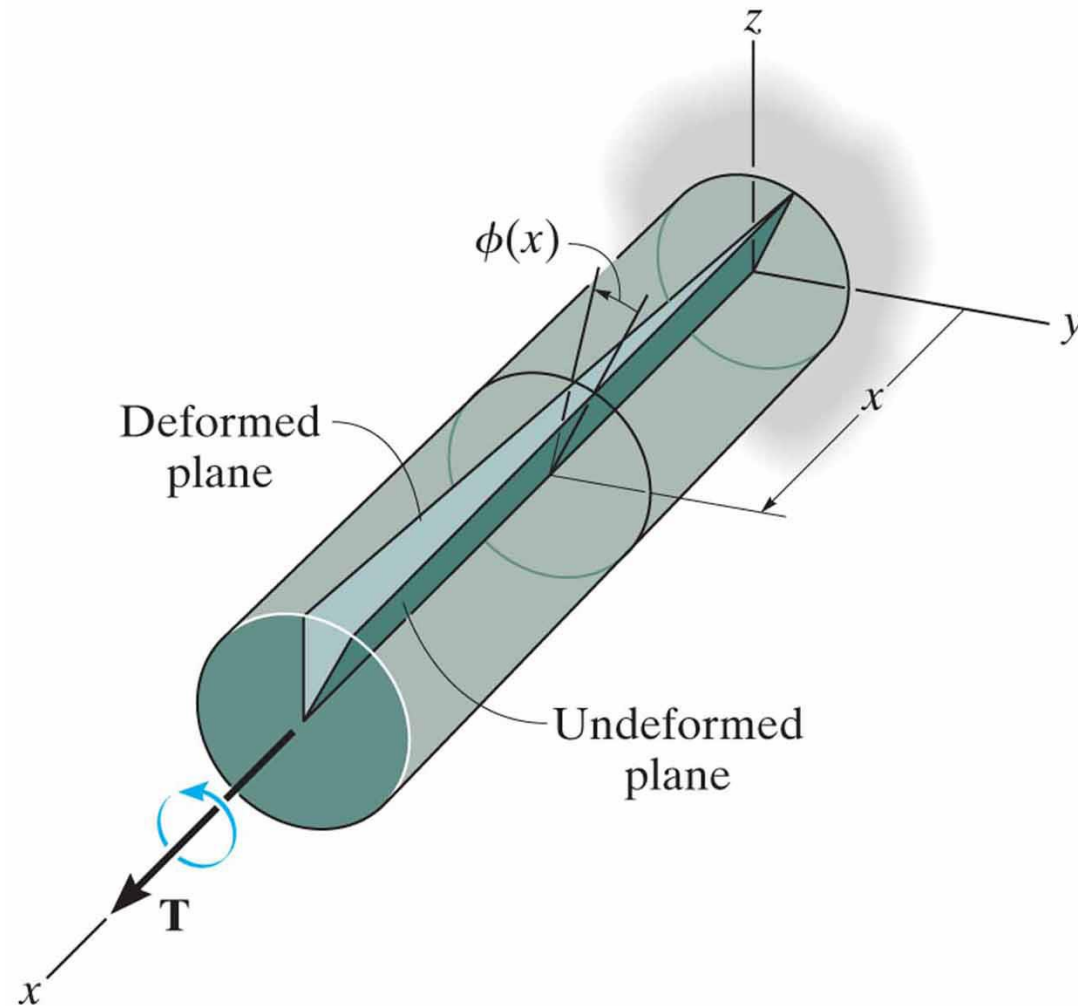
## Torsion: example E

The 25 mm diameter shaft on the motor is made of a material having an allowable shear stress of  $\tau_{\text{allow}} = 75 \text{ MPa}$ . If the motor is operating at its maximum power of 5 kW, determine the minimum allowable rotation of the shaft.





# Torsion: angle of twist



The angle of twist  $\phi(x)$  increases as  $x$  increases.



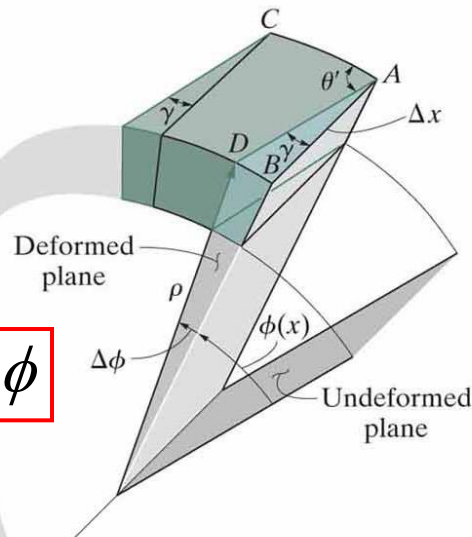
# Torsion: angle of twist $\phi$

$$BD = \gamma \cdot \Delta x$$

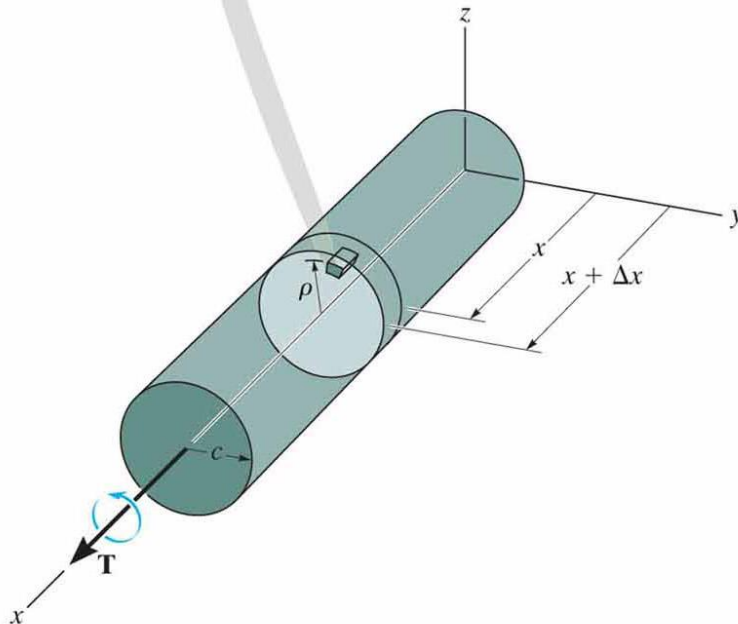
$$BD = \rho \cdot \Delta\phi$$

Shear strain:  $\gamma = \rho \frac{d\phi}{dx}$

Therefore:  $d\phi = \frac{\gamma}{\rho} dx$



Shear strain of element



## Torsion: angle of twist $\phi$

From before: 
$$d\phi = \frac{\gamma}{\rho} dx$$

By Hook's law: 
$$\gamma = \frac{\tau}{G} = \frac{1}{G} \frac{T \rho}{J}$$

$$\gamma(x, \rho) = \frac{1}{G} \frac{T(x) \rho}{J(x)}$$

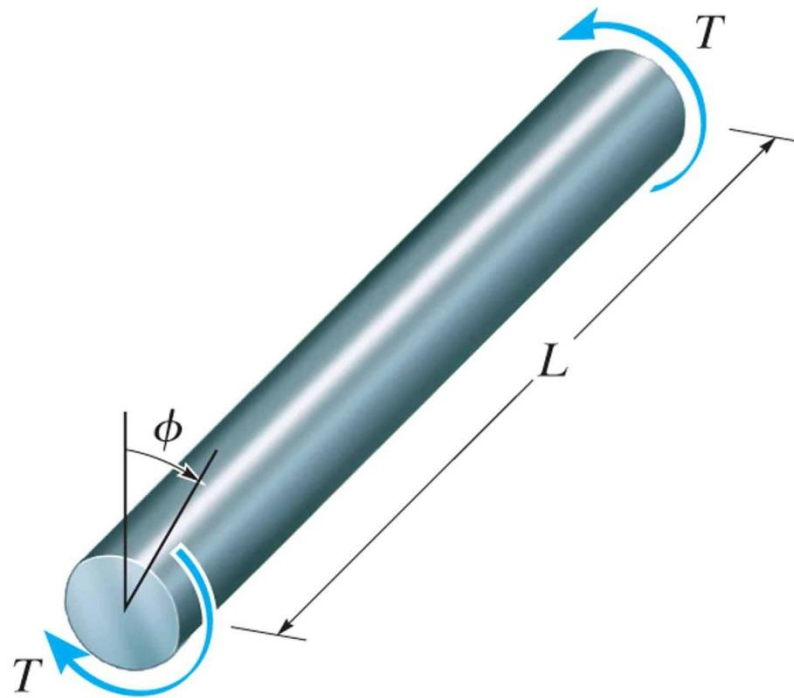
Angle of twist: 
$$\phi(x) = \int_0^L \frac{1}{G} \frac{T(x)}{J(x)} dx$$



# **Torsion: angle of twist $\phi$**

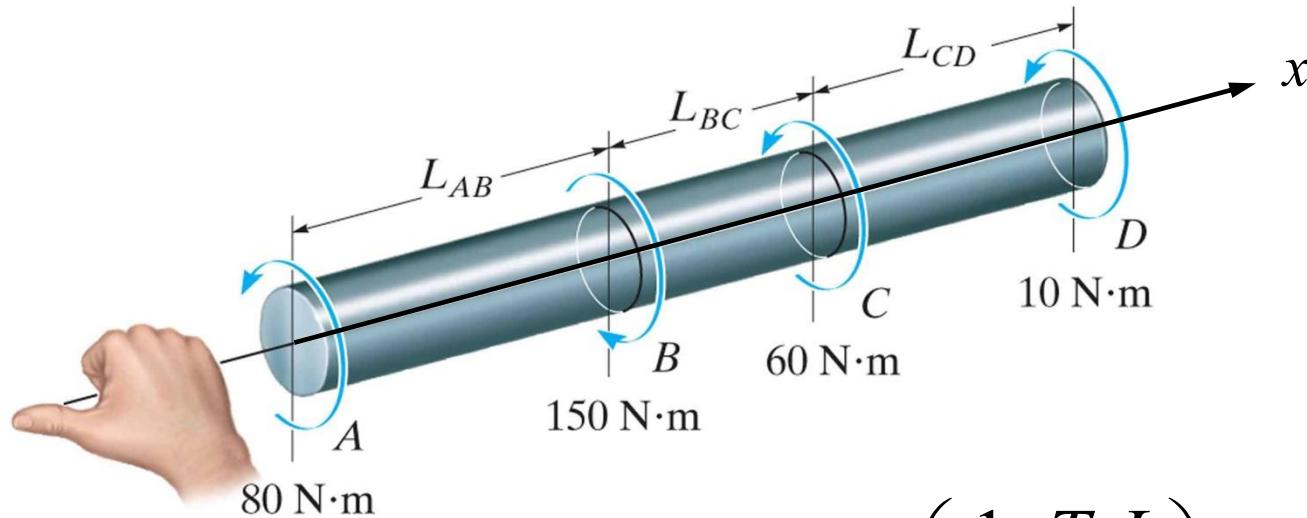
Constant torque and cross sectional area

$$\text{Angle of twist: } \phi(x = L) = \frac{1}{G} \frac{T L}{J}$$

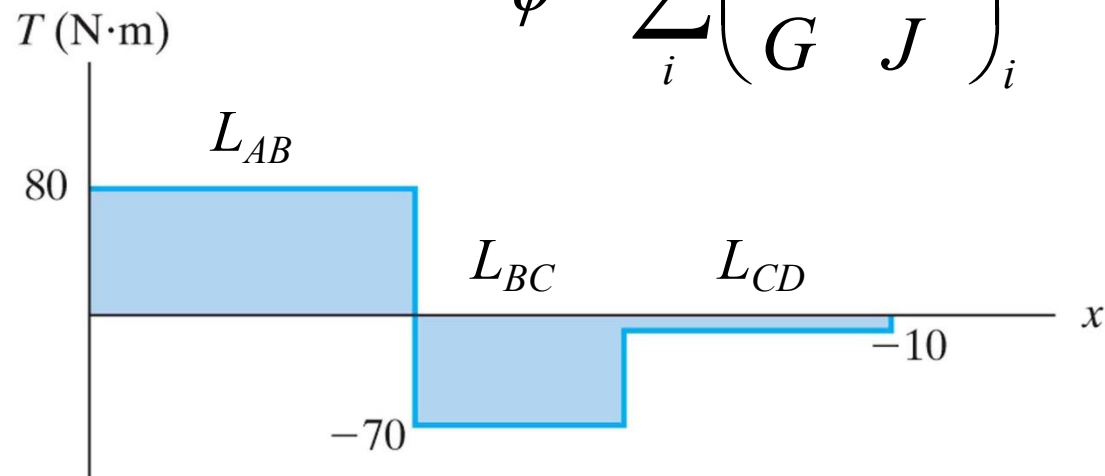


# Torsion: angle of twist $\phi$

## Multiple torques

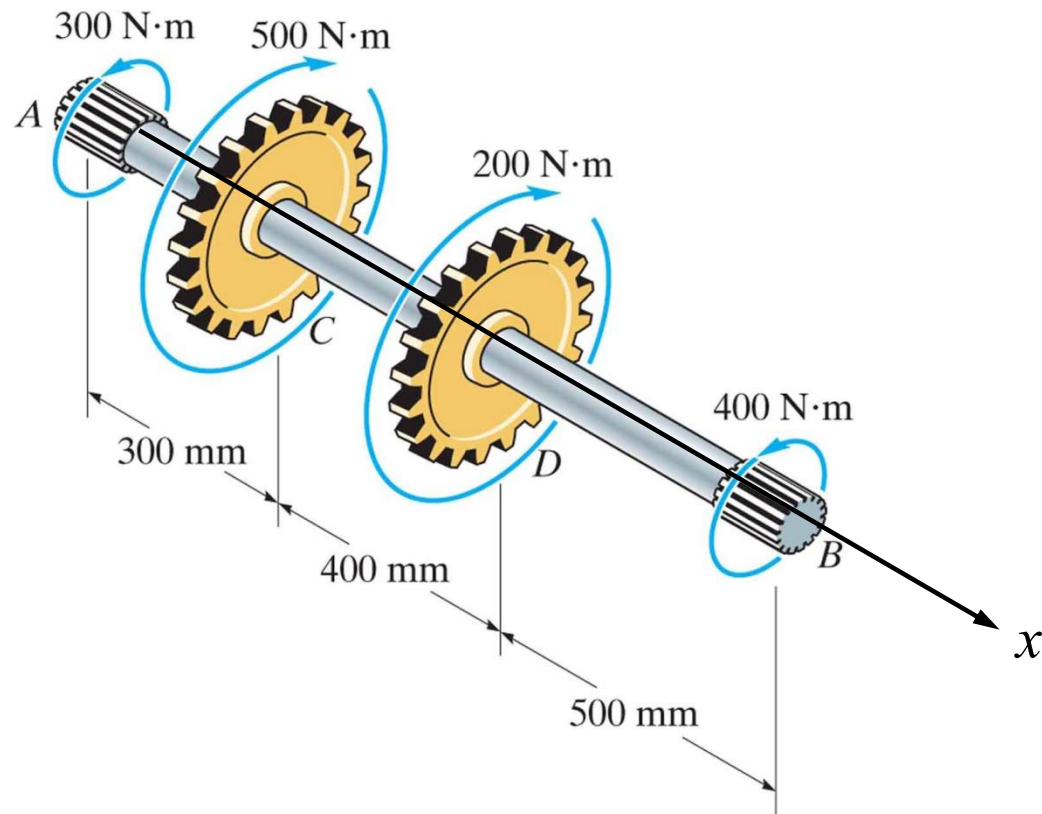


$$\phi = \sum_i \left( \frac{1}{G} \frac{T L}{J} \right)_i$$



## Torsion: example F

The splined ends and gears attached to the A-36 steel shaft are subjected to the torques shown. Determine the angle of twist of end  $B$  with respect to end  $A$ . The shaft has a diameter of 40 mm.



# Reading assignment

- Chapter 5 of textbook
- Review notes and text: ES2001, ES2501



# Homework assignment

- As indicated on webpage of our course

