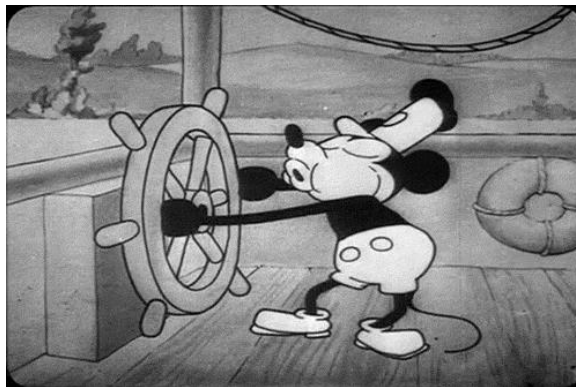


WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

STRESS ANALYSIS ES-2502, B'2025

We will get started soon...



17 November 2025



WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

STRESS ANALYSIS ES-2502, D'2020

Lecture 16:
Unit 12: Torsion of shafts:
circular cross-section: *torsion formula*

17 November 2025



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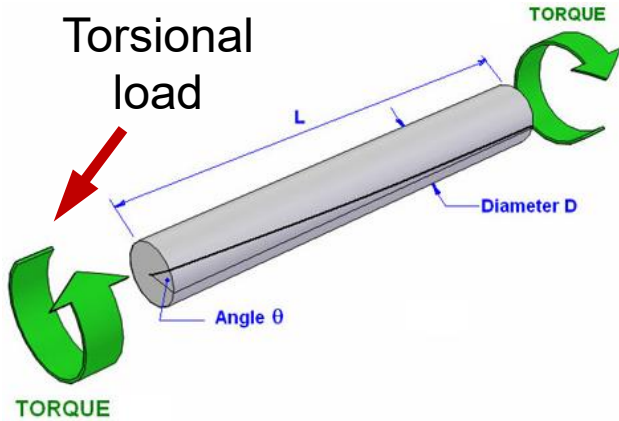
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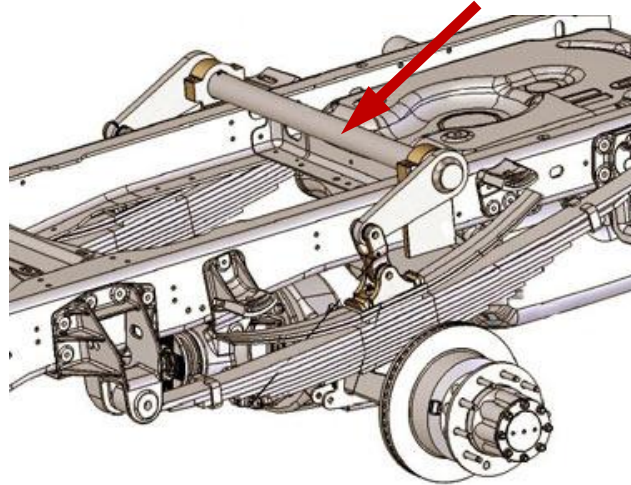


Torsion

Components subjected to torsional loads: just a few examples



Suspension mechanisms:
torsion bar

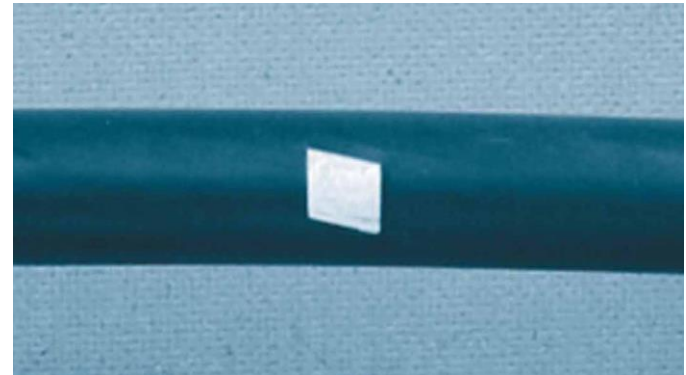
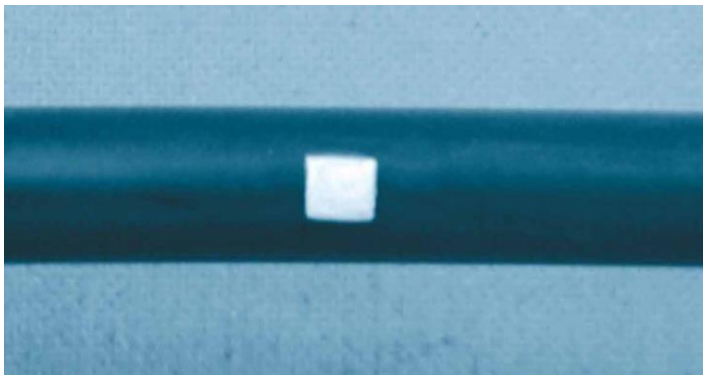
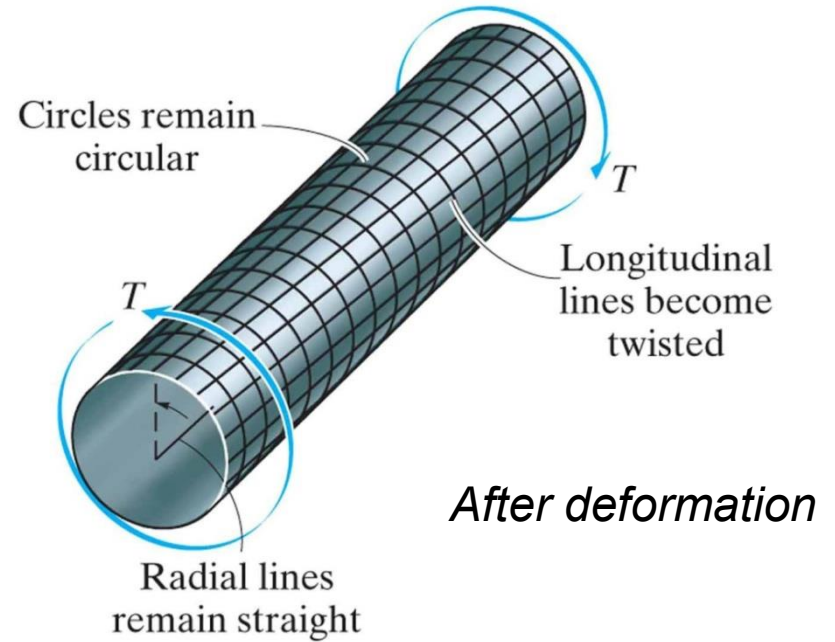
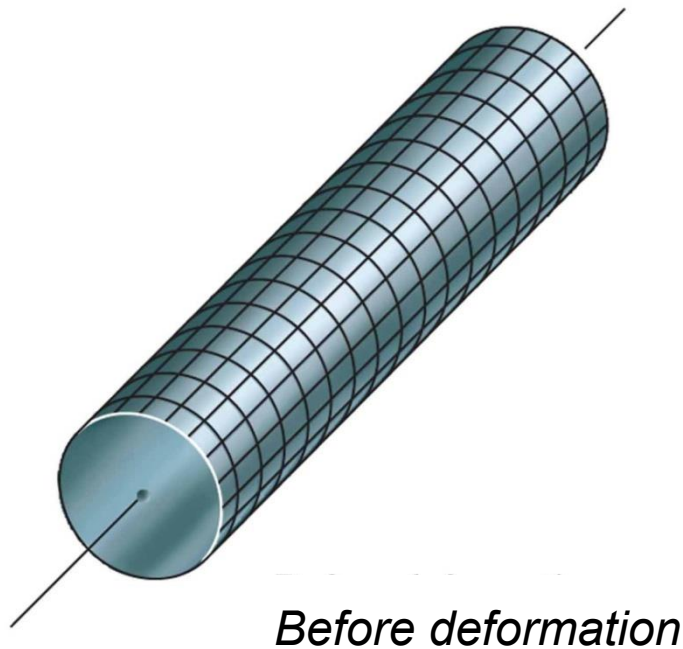


Pedals of bicycles

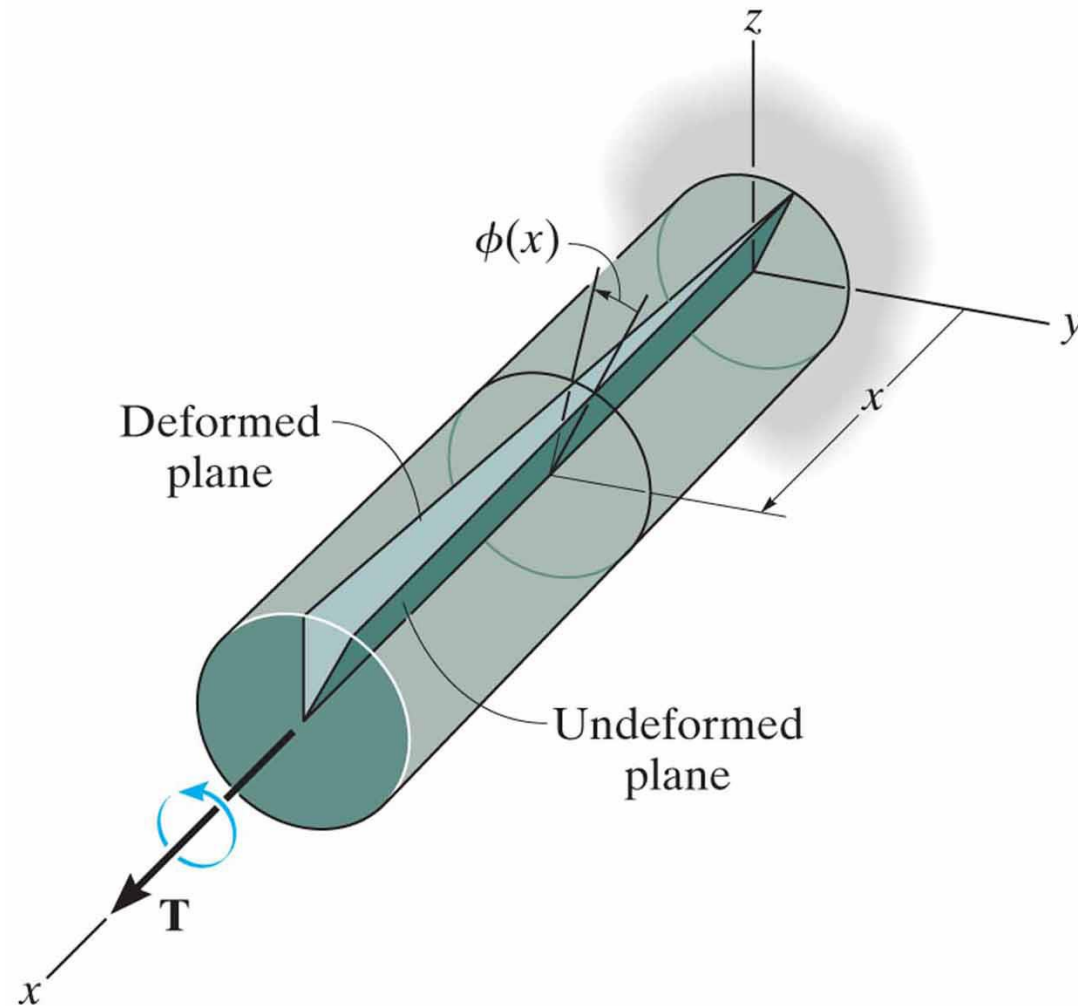


Torsion

Component subjected to torsional load



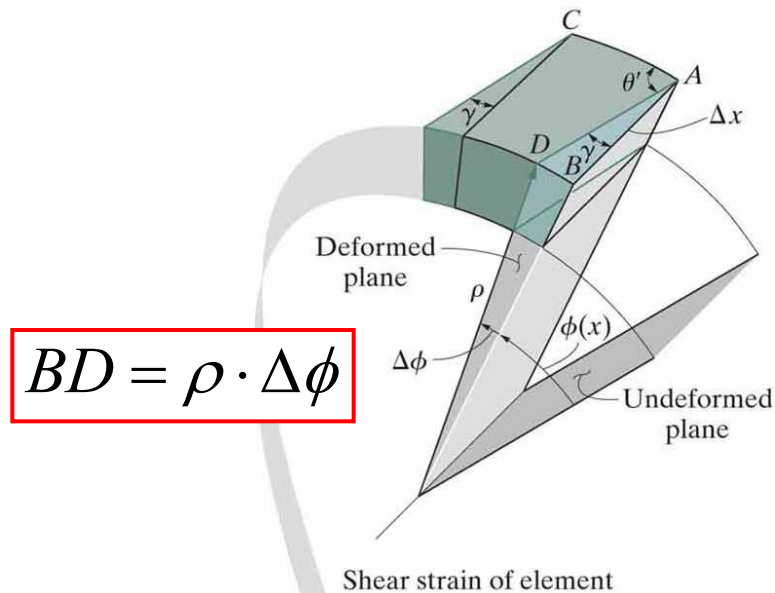
Torsion: angle of twist



The angle of twist $\phi(x)$ increases as x increases.



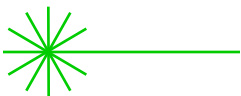
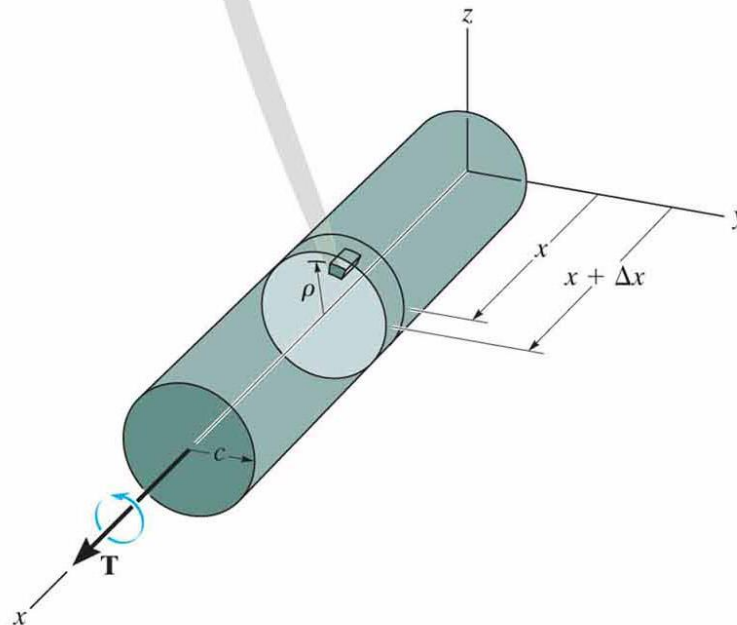
Torsion: shear strains



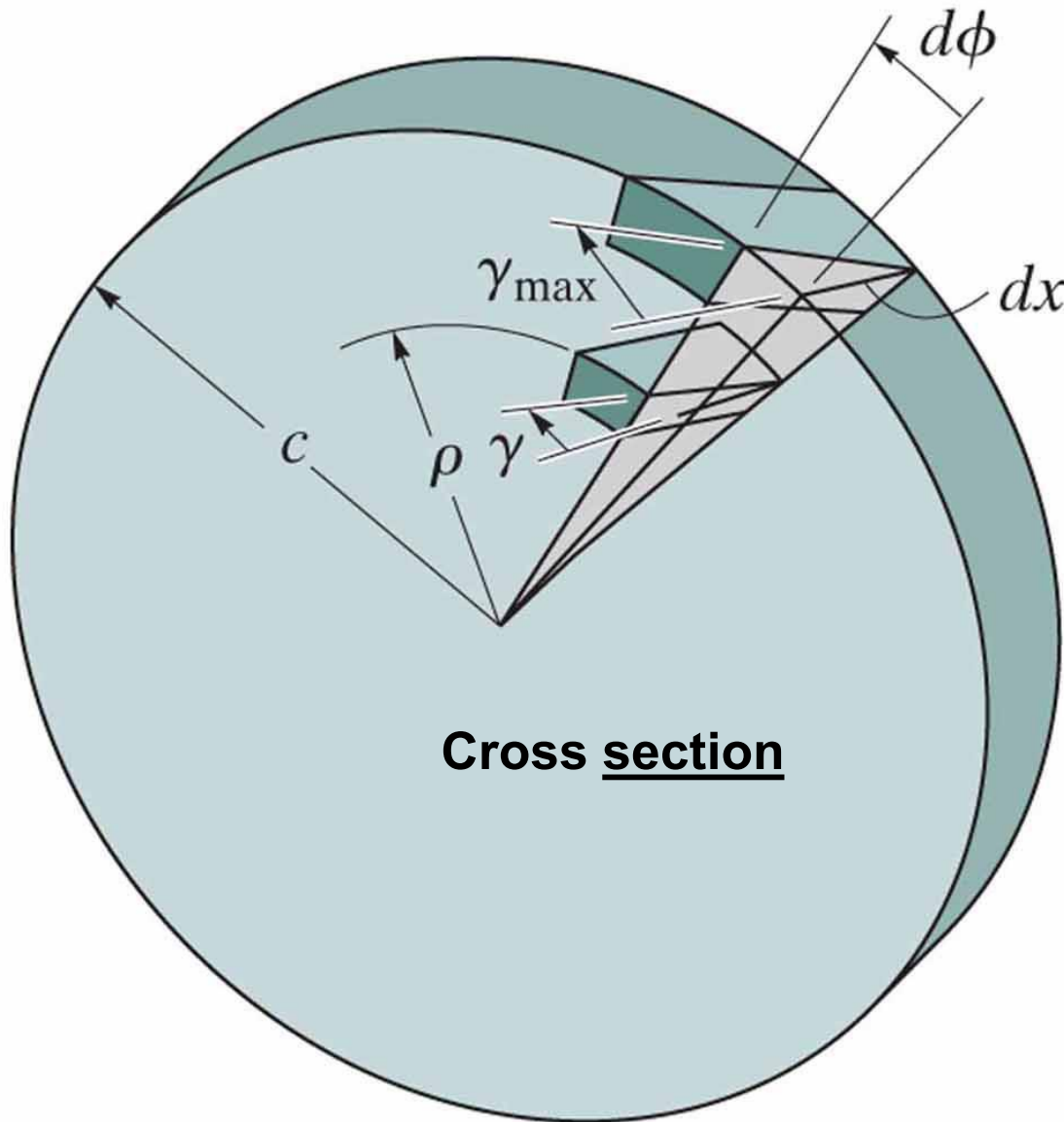
$$BD = \gamma \cdot \Delta x$$

$$BD = \rho \cdot \Delta\phi$$

Shear strain: $\gamma = \rho \frac{d\phi}{dx}$



Torsion: shear strains



$$\frac{\gamma}{\rho} = \frac{\gamma_{\max}}{c}$$

Shear strains vary linearly within a section:

$$\gamma = \gamma(\rho) = \rho \frac{\gamma_{\max}}{c}$$

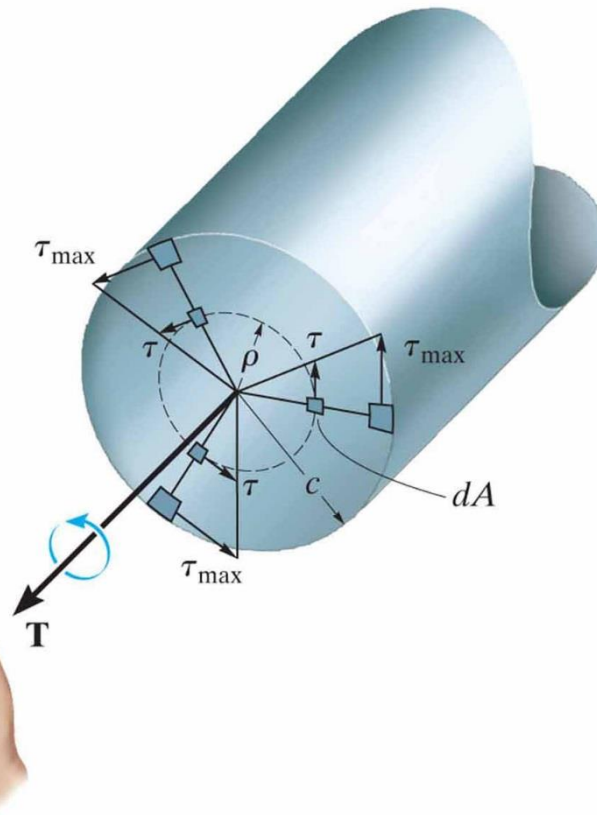
Torsion formula

Shear stresses also vary linearly within a section:

*According to Hook's law
(linear elasticity):*

$$(\tau = G \cdot \gamma)$$

$$\tau = \tau(\rho) = \rho \frac{\tau_{\max}}{c}$$



Differential Force:

$$dF = \tau \cdot dA$$

Differential Torque:

$$dT = \rho (\tau \cdot dA)$$



Torsion formula

Integrating torque:
$$T = \int_A \rho (\tau \cdot dA) = \int_A \rho \left(\rho \frac{\tau_{\max}}{c} \right) dA$$
$$= \frac{\tau_{\max}}{c} \int_A \rho^2 dA$$

Define:
$$J = \int_A \rho^2 dA$$
 ← Polar area moment of inertia

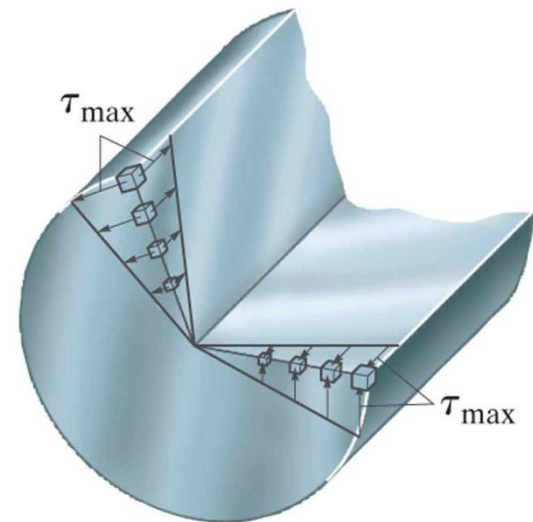
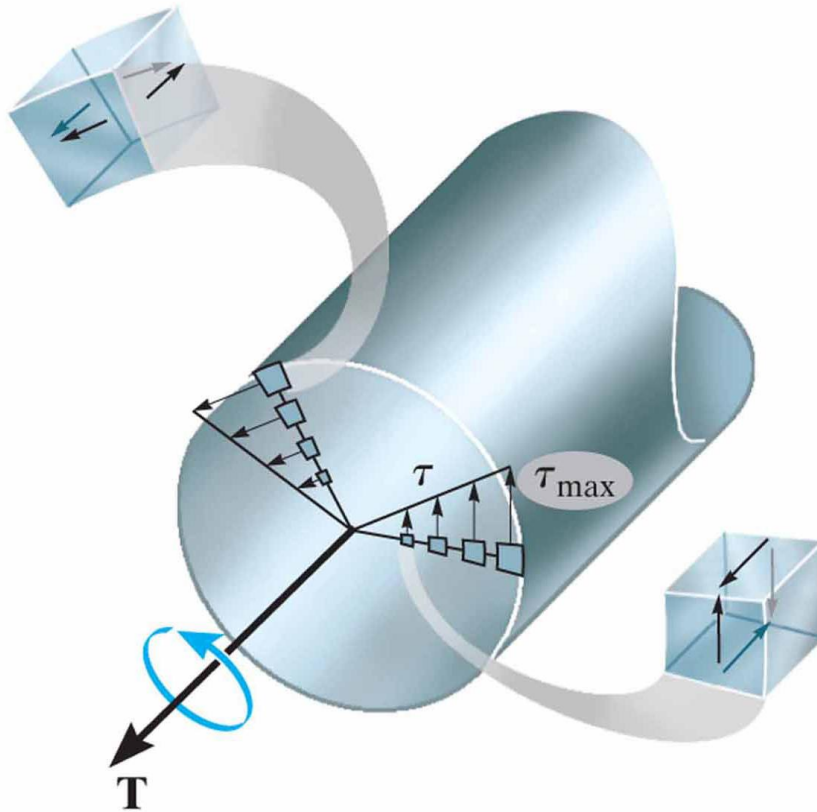
Torsion formula for stresses:
(linear elastic)

$$\tau_{\max} = \frac{T c}{J} \quad \text{and} \quad \tau = \tau(\rho) = \frac{T \rho}{J}$$



Torsion formula: solid circular bar

Linear variation of shear stress

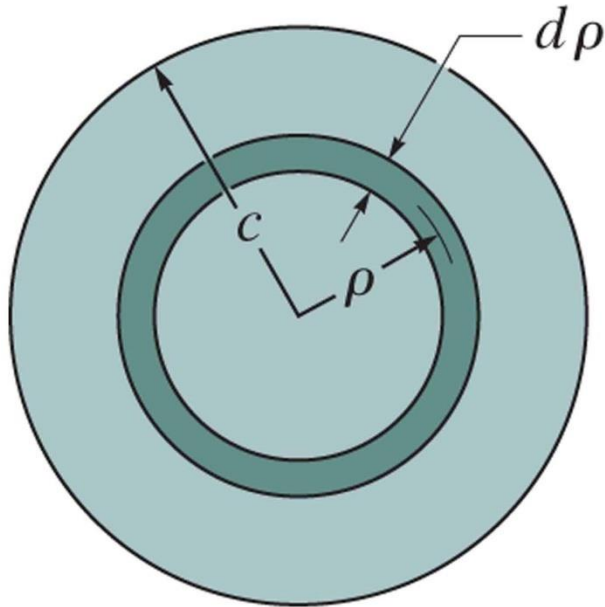


Shear stress varies linearly along each radial line of the cross section.



Torsion formula: polar area moment of inertia

Solid bar



$$J = \int_A \rho^2 dA$$

$$= \int_0^c \rho^2 (2\pi \rho d\rho)$$

$$= 2\pi \int_0^c \rho^3 d\rho = 2\pi \left(\frac{\rho^4}{4} \right)_0^c$$

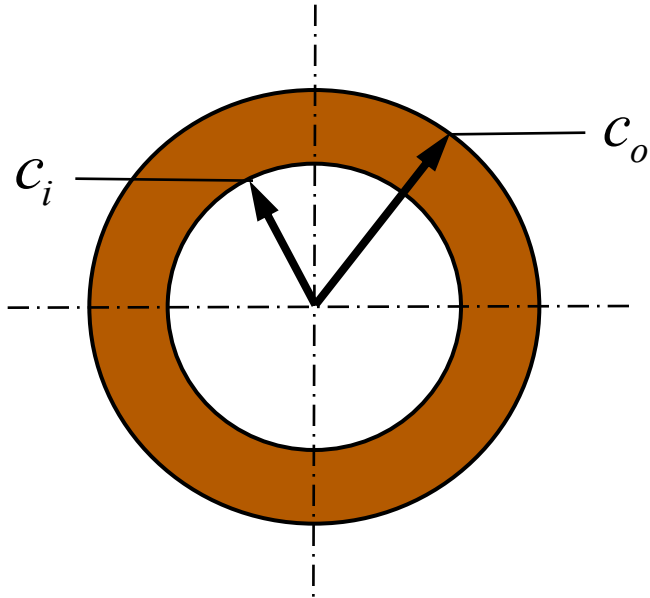
**Solid, circular,
section:**

$$J = \frac{\pi}{2} c^4$$



Torsion formula: polar area moment of inertia

Tubular bar



$$J = \int_A \rho^2 dA$$

$$= \int_{c_i}^{c_o} \rho^2 (2\pi \rho d\rho)$$

$$= 2\pi \int_{c_i}^{c_o} \rho^3 d\rho = 2\pi \left(\frac{\rho^4}{4} \right)_{c_i}^{c_o}$$

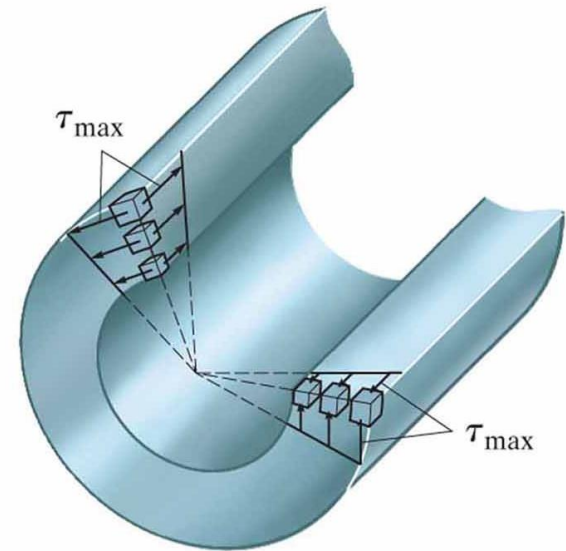
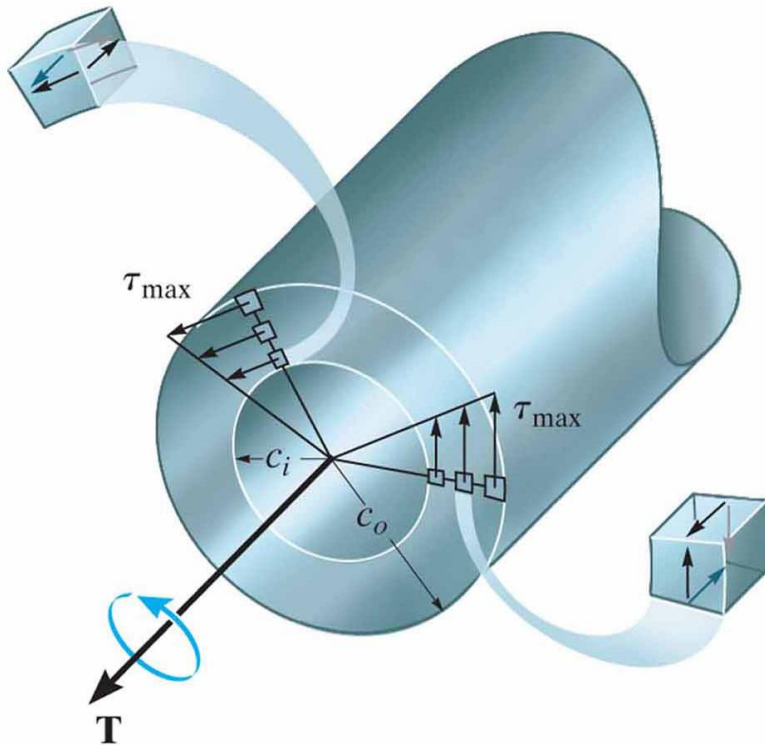
**Tubular
section:**

$$J = \frac{\pi}{2} (c_o^4 - c_i^4)$$



Torsion formula: tubular bar

Linear variation of shear stress



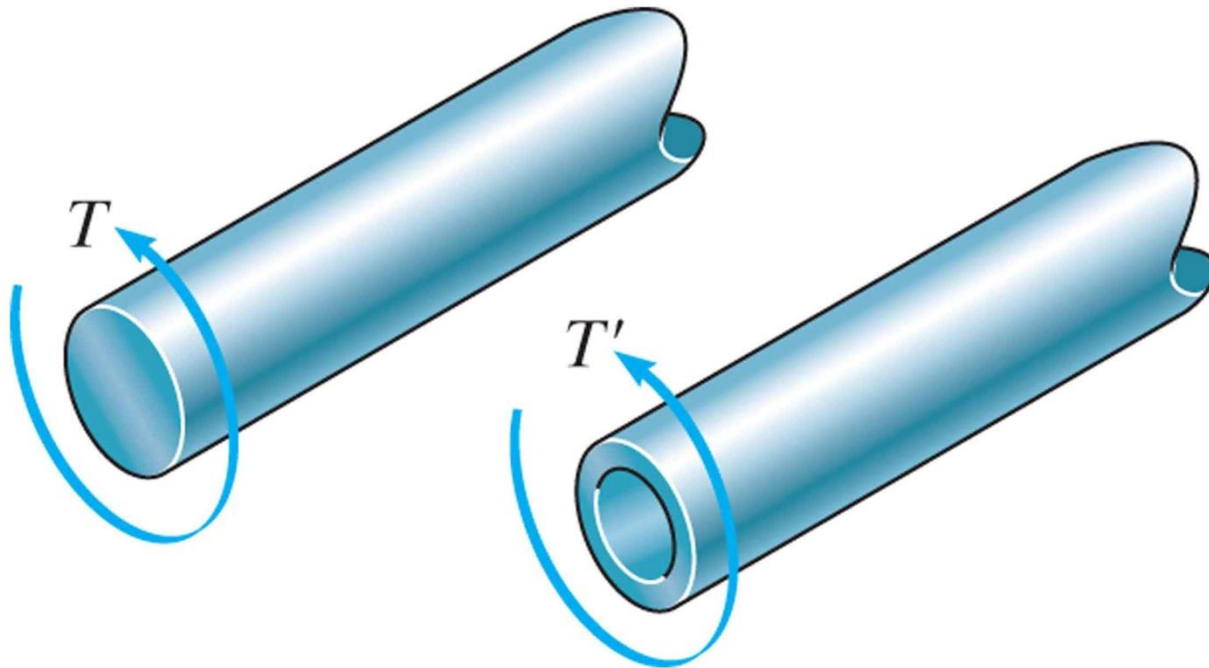
Shear stress varies linearly along each radial line of the cross section.



Torsion: example A

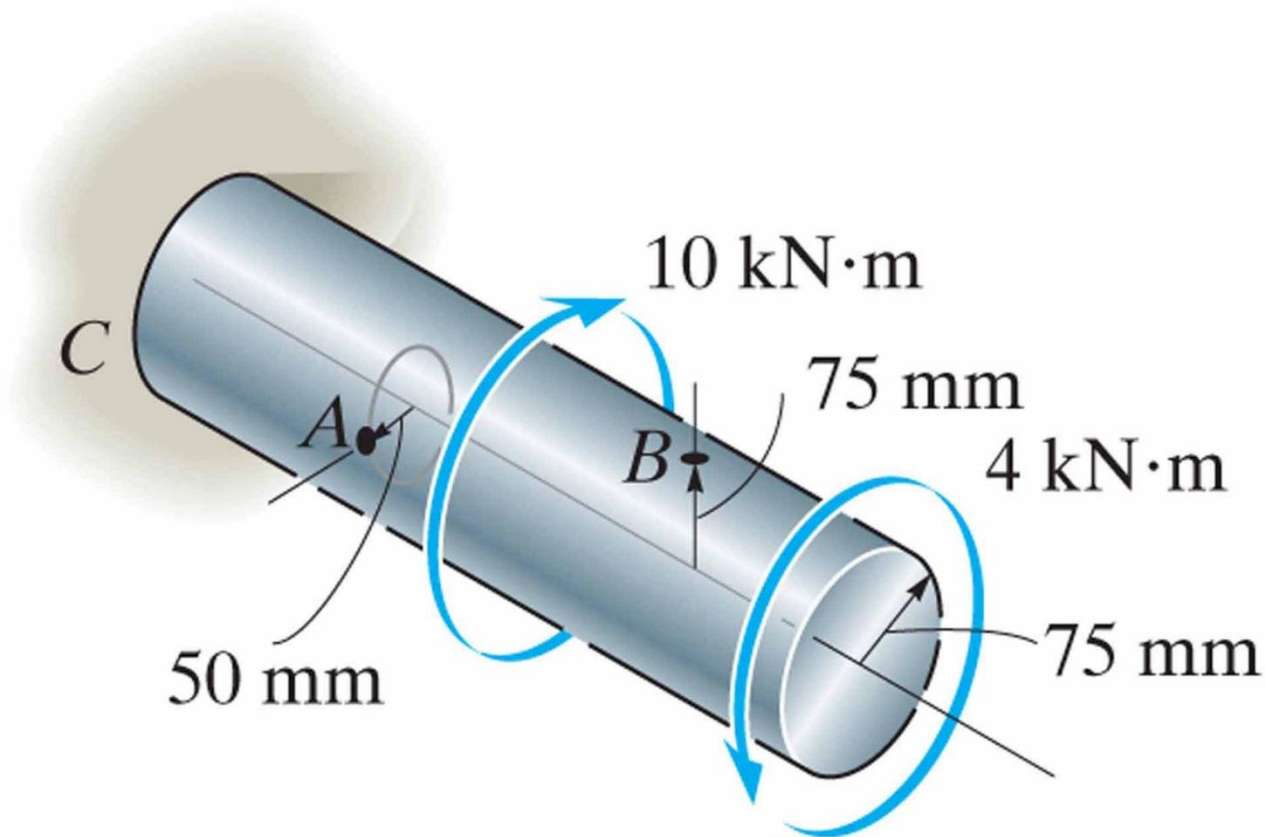
A shaft is made of a steel alloy having an allowable shear stress of $\tau_{\text{allow}} = 12 \text{ ksi}$. If the diameter of the shaft is 1.5 in., determine the maximum torque T that can be transmitted.

What would be the maximum torque T' if a 1-in. diameter hole is bored through the shaft? Sketch the shear-stress distribution *along a radial line* in each case.



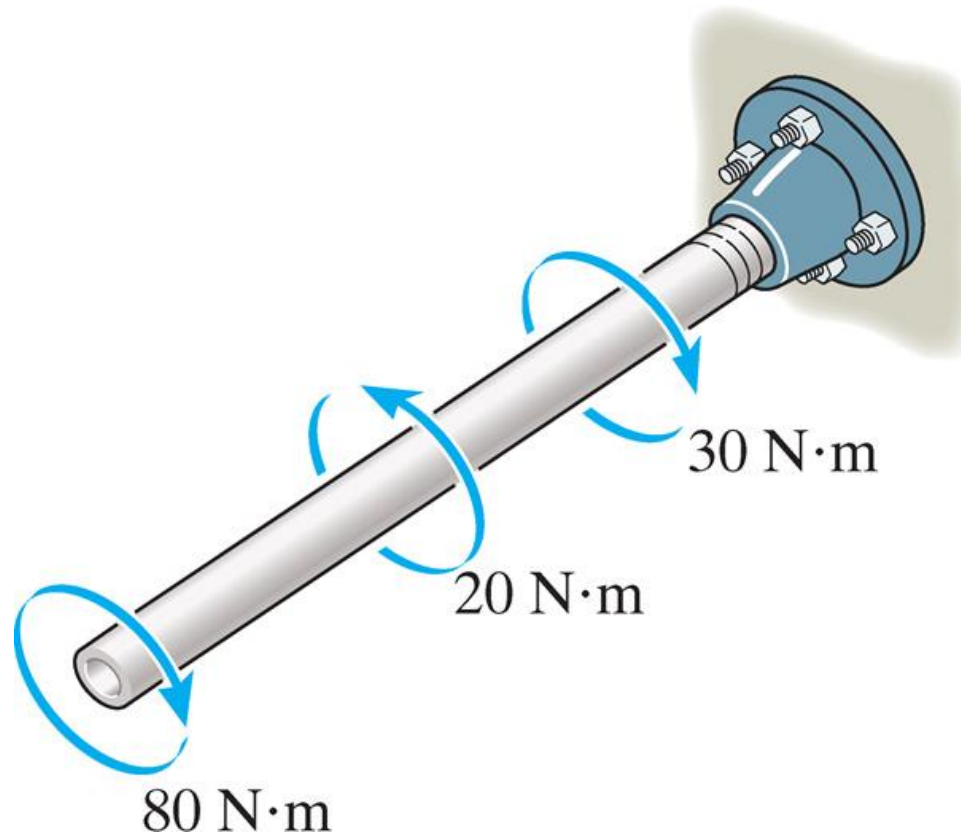
Torsion: example B

The solid shaft is fixed to the support at C and subjected to the torsional loadings shown. Determine the shear stress at points A and B and sketch the shear stress on volume (stress) elements located at these points.

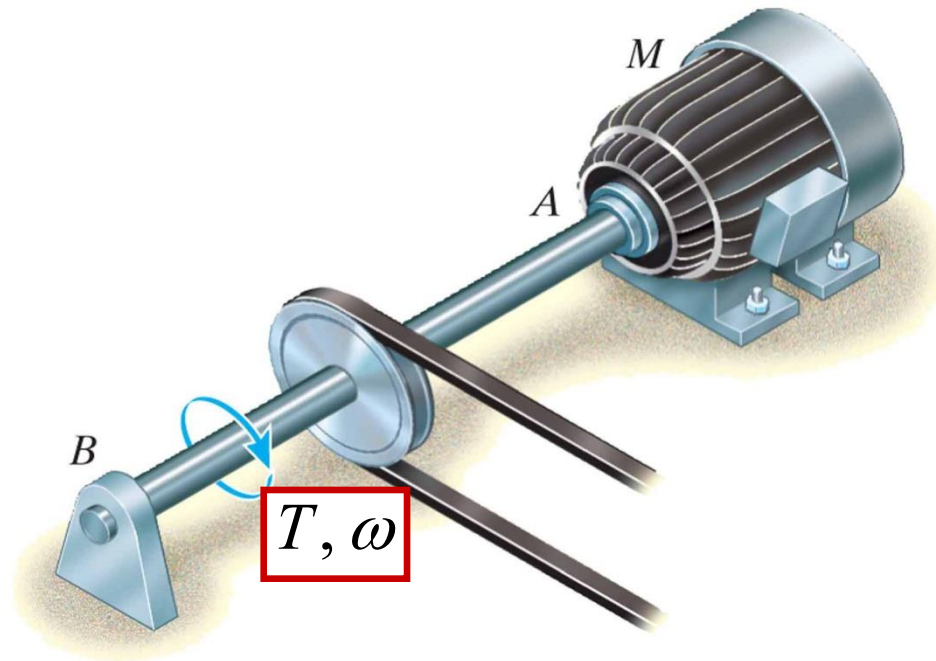


Torsion: example C

The copper pipe has an outer diameter of 40 mm and an inner diameter of 37 mm. If it is tightly secured to the wall and three torques are applied to it, determine the absolute maximum shear stress developed in the pipe.



Power transmission



$$P = T \omega$$

with:

$$\omega = 2\pi \cdot f$$

$$\omega \left[\frac{\text{rad}}{\text{sec}} \right]$$

$$f [\text{Hz}]$$



Reading assignment

- Chapter 5 of textbook
- Review notes and text: ES2001, ES2501



Homework assignment

- As indicated on webpage of our course

