

Last time

Taylor's series on equally spaced nodes

Forward difference

$$\frac{d^n U_i}{dx^n} \cong \frac{\Delta^n U_i}{h^n} + O(h)$$

Backward difference

$$\frac{d^n U_i}{dx^n} \cong \frac{\nabla^n U_i}{h^n} + O(h)$$

Centered difference

$$\frac{d^n U_i}{dx^n} \cong \frac{\delta^n U_i}{(1 \text{ or } 2)h^n} + O(h^2)$$

↑ for odd n

Requires $n + 1$ points

and in general $\Delta^n U_i = \Delta(\Delta^{n-1} U_i)$

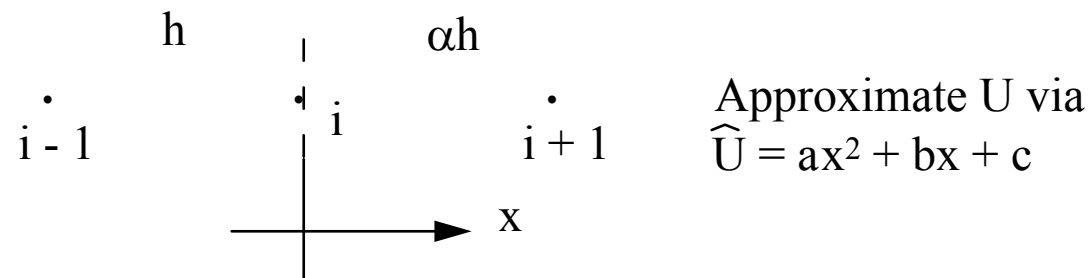
For greater accuracy one must add points

Uncentered: $n + m$ points for $\approx \frac{d^n U_i}{dx^n} \Big|_i + O(h^m)$

Centered: $n+(m-1)$ points for $\approx \frac{d^n U_i}{dx^n} \Big|_i + O(h^m)$
 m must be even

For unequal spacing the centered approximation loses its meaning and accuracy is reduced to uncentered approximations

Alternative to Taylor Series : Polynomial Fit



3 unknowns (a, b, c) require 3 equations

$$\begin{array}{l}
 U_{i-1} = ah^2 + b(-h) + c \\
 U_i = c \\
 U_{i+1} = a(\alpha h)^2 + b(\alpha h) + c
 \end{array}
 \begin{bmatrix}
 h^2 & -h & 1 \\
 0 & 0 & 1 \\
 (\alpha h)^2 & \alpha h & 1
 \end{bmatrix}
 \begin{Bmatrix}
 a \\
 b \\
 c
 \end{Bmatrix}
 =
 \begin{Bmatrix}
 U_{i-1} \\
 U_i \\
 U_{i+1}
 \end{Bmatrix}$$

Solve for a, b, c,

$$\begin{Bmatrix}
 a \\
 b \\
 c
 \end{Bmatrix}
 =
 \begin{Bmatrix}
 \left\{ \alpha[U_{i-1} - U_i] + [U_{i+1} - U_i] \right\} / (\alpha^2 + \alpha)h^2 \\
 \left\{ \alpha^2[U_{i-1} - U_i] + [U_{i+1} - U_i] \right\} / (\alpha^2 + \alpha)h \\
 [U_i]
 \end{Bmatrix}$$

$$\frac{d\widehat{U}}{dx} = 2ax + b \qquad \frac{d^2\widehat{U}}{dx^2} = 2a$$

$$\frac{d^2\widehat{U}}{dx^2} = \frac{2[U_{i+1} - (1 + \alpha)U_i + \alpha U_{i-1}]}{\alpha(\alpha + 1)h^2}$$

i.e. The same as truncated Taylor Series

$$\frac{dU_i}{dx} \cong \frac{-U_{i+2} + 4U_{i+1} - 3U_i}{2h} + O(h^2)$$

i.e. The same as if derived directly from Taylor Series

Difference Formulas for Cross-Derivatives

a.) 2-D Taylor Series :

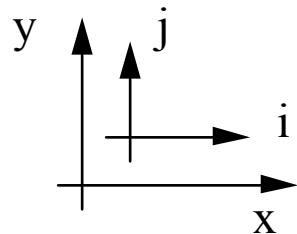
$$U(x + \Delta x, y + \Delta y) = U_{x,y} + \left(\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y} \right) U_{x,y} + \frac{1}{2!} \left(\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y} \right)^2 U_{x,y} \\ + \frac{1}{3!} \left(\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y} \right)^3 U_{x,y} + \dots + h.o.t.$$

Where $\left(\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y} \right)^2 \equiv \Delta x^2 \frac{\partial^2}{\partial x^2} + \Delta y^2 \frac{\partial^2}{\partial y^2} + 2\Delta x \Delta y \frac{\partial^2}{\partial x \partial y}$ etc.

Procedure as in 1-D case: write Taylor series for all points in terms of U , $\frac{\partial U}{\partial x}$, $\frac{\partial U}{\partial y}$, ... at point where $\frac{\partial^2 U}{\partial x \partial y}$ is wanted; mix together to get desired accuracy.

b.) Easier: Operate on 1-D formulas.

$$\frac{\partial^2 U}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial U}{\partial y} \right) \cong \frac{\partial}{\partial x} \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y} \right) \cong \frac{\left(\frac{U_{j+1} - U_{j-1}}{2\Delta y} \right)_{i+1} - \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y} \right)_{i-1}}{2\Delta x}$$



Intuitive ; What is leading error?

From 1-D: $\left(\frac{\partial U}{\partial y}\right) \cong \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right) - \frac{(\Delta y)^2}{6} \frac{\partial^3 U}{\partial y^3} + \dots$

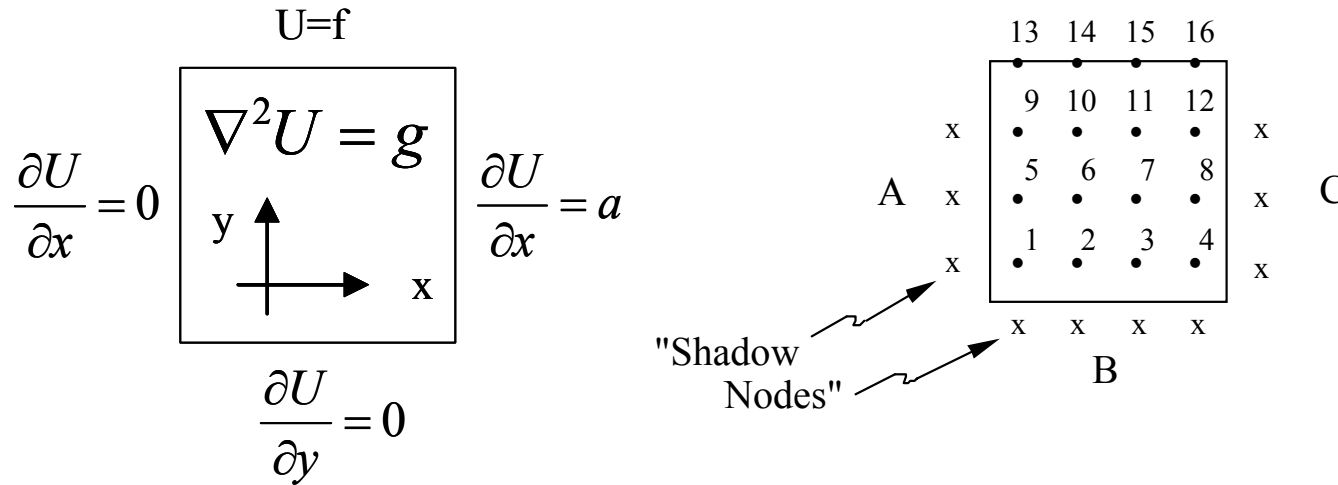
$$\frac{\partial}{\partial x} \left(\frac{\partial U}{\partial y}\right) \cong \frac{\partial}{\partial x} \left(\left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right) - \frac{(\Delta y)^2}{6} \frac{\partial^3 U}{\partial y^3} + \dots \right) \cong \left(\frac{\partial}{\partial x} \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right) - \frac{(\Delta y)^2}{6} \frac{\partial^4 U}{\partial x \partial y^3} + \dots \right)$$

$$\frac{\partial}{\partial x} \left(\frac{\partial U}{\partial y}\right) \cong \left(\frac{\left(\left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right)_{i+1} - \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right)_{i-1} \right)}{2\Delta x} - \frac{(\Delta x)^2}{6} \frac{\partial^3}{\partial x^3} \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right) - \frac{(\Delta y)^2}{6} \frac{\partial^4 U}{\partial x \partial y^3} + \dots \right)$$

$$\frac{\partial}{\partial x} \left(\frac{\partial U}{\partial y}\right) \cong \left(\frac{\left(\left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right)_{i+1} - \left(\frac{U_{j+1} - U_{j-1}}{2\Delta y}\right)_{i-1} \right)}{2\Delta x} - \frac{(\Delta x)^2}{6} \frac{\partial^4 U}{\partial x^3 \partial y} - \frac{(\Delta y)^2}{6} \frac{\partial^4 U}{\partial x \partial y^3} + \dots \right)$$

So the leading error terms are symmetrical.

Consider an Elliptic PDE (Poisson's Eqn.)

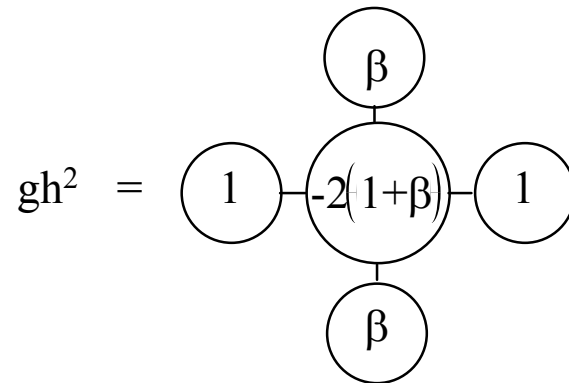


$$\text{PDE: } \frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} = g \cong \frac{U_{i+1,j} - 2U_{i,j} + U_{i-1,j}}{h^2} + \frac{U_{i,j+1} - 2U_{i,j} + U_{i,j-1}}{k^2}$$

$$\left(\frac{1}{h^2}\right) \left(\frac{-2}{h^2}\right) \left(\frac{1}{h^2}\right) + \left(\frac{1}{k^2}\right) \left(\frac{-2}{k^2}\right) \left(\frac{1}{k^2}\right) = g$$


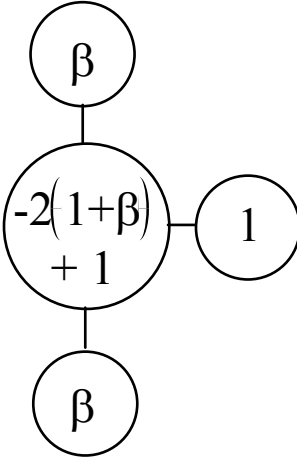

Define $\beta = \frac{h^2}{k^2}$

“Computational Molecule”



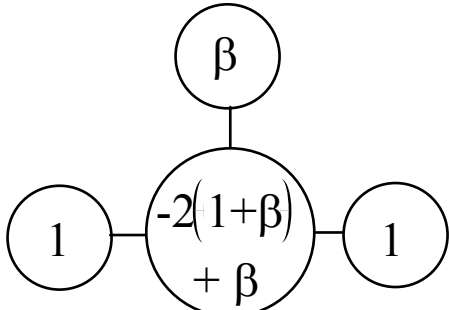
Valid at all interior nodes

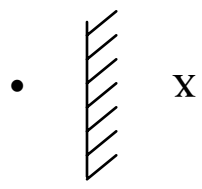
Boundary A : $\frac{\partial U}{\partial x} = 0$

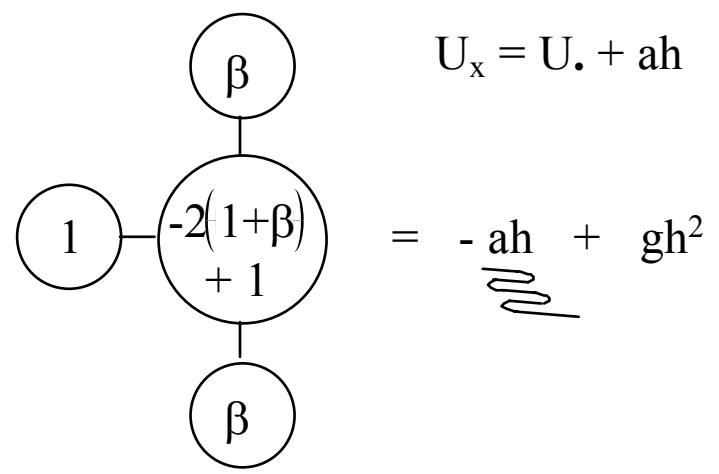

 $\cdot \frac{U. - U_x}{h} = 0 \Rightarrow$

 $=$


i.e. $U_x = U.$

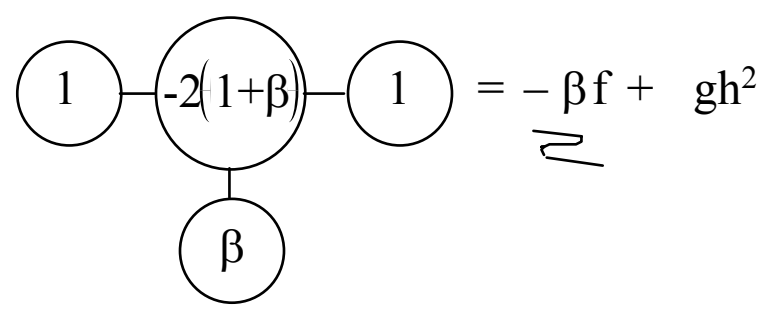
Boundary B :


 $= gh^2$

Boundary C :  $\frac{U_x - U.}{h} = a$



Top Row (nodes 9-12)



Corners : ex. node 4

$$\begin{array}{c} \textcircled{\beta} \\ | \\ \textcircled{-2(1+\beta)} \\ | \\ \textcircled{1} \end{array} \quad \begin{array}{c} \textcircled{1} \\ | \\ \textcircled{-2(1+\beta)} \\ | \\ \textcircled{1+\beta} \end{array} = -ah + gh^2$$

Basic Rule :

Type I Boundary : Do not use the PDE

Type II, III : Use PDE plus BC, together

The node spacing adjacent to the Type II boundaries are spaced at a $\Delta x/2$ format. This is NOT required. It IS accurate, however, the unknown values (u) on the boundary are not calculated. This may be a disadvantage. Similarly, if the geometry does not lend itself to this spacing conveniently - do not use it. The alternate strategy is to place nodes directly on the boundary. If nodes are on the boundary then the shadow node contributions do not usually move to the diagonal.

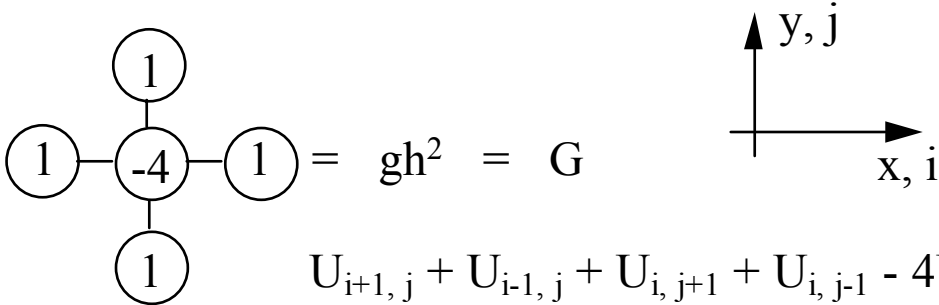
For $\beta = 1$: ($h = k$)

$$\begin{array}{c} \textcircled{1} \\ \textcircled{1} \quad \textcircled{-4} \quad \textcircled{1} = G \\ \textcircled{1} \end{array} \quad \begin{array}{l} \nearrow \\ \text{gh}^2 \end{array}$$

Solution Strategies

- Direct:
- Exact algebraic solution in finite # of steps
 - Non-repetitive
 - Complicated coding
 - Exploit sparse / banded structure
 - Node numbering : dictates the banded structure
 - LU Decomposition popular
 - Preserves bandwidth
 - “Back Substitution” step easy relative to decomposition \therefore numerous solutions to the same matrix can be gotten cheaply.

- Iterative: - Exact algebraic solution only after ∞ # of steps
- Monotonously repetitive
 - Coding simple; proceed directly from molecule
 - Exploit sparseness; banded structure irrelevant
 - Retain double subscripts U_{ij}
 - Node numbering important:
 - Dictates order in which iterations proceed
 - \therefore Can determine convergence properties
 - “Point” versus “Block” or “Line” methods:
Matrix Inversion (usually 3-Diag)



The diagram shows a central node with four adjacent nodes (up, down, left, right), each containing the number 1. The central node contains -4. To the right is a coordinate system with a vertical axis labeled 'y, j' and a horizontal axis labeled 'x, i'.

$$\begin{array}{c}
 \textcircled{1} \\
 | \\
 \textcircled{1} - \textcircled{-4} - \textcircled{1} \\
 | \\
 \textcircled{1}
 \end{array} = gh^2 = G$$

$$U_{i+1,j} + U_{i-1,j} + U_{i,j+1} + U_{i,j-1} - 4U_{i,j} = G$$

Jacobi : “Solve” for $U_{i,j}$

$$U_{i,j}^{n+1} = \frac{1}{4}[U_{i+1,j} + U_{i-1,j} + U_{i,j+1} + U_{i,j-1} - G]^n$$

- Easy
- Need 2 arrays U^n, U^{n+1}
- Iteration independent of node #'s / order of calculation

Gauss - Seidel : Use latest info within Jacobi

$$U_{i,j}^{n+1} = \frac{1}{4}[U_{i+1,j}^n + \underbrace{U_{i-1,j}^{n+1}} + U_{i,j+1}^n + \underbrace{U_{i,j-1}^{n+1}} - G]$$

- Easy
- Only one array
- Ordering makes difference!

S.O.R. : Accelerate / Dampen the Gauss - Seidel :

$\tilde{U}_{i,j}^{n+1} \equiv$ Gauss - Seidel “estimate” for $U_{i,j}^{n+1}$

$$U_{i,j}^{n+1} = \underbrace{\omega \tilde{U}_{i,j}^{n+1} + (1 - \omega) U_{i,j}^n}_{\text{S.O.R.}} = U_{i,j}^n + \omega(\tilde{U}_{i,j}^{n+1} - U_{i,j}^n)$$

$$U_{i,j}^{n+1} = \omega \left[\frac{1}{4} [U_{i+1,j}^n + U_{i-1,j}^{n+1} + U_{i,j+1}^n + U_{i,j-1}^{n+1} - G] \right] + (1 - \omega) U_{i,j}^n$$

where $\boxed{0 < \omega < 2}$