

Config
Globals
BEGIN
Variables

```
void main ( void )  
{
```

```
// This is a sample program that can be used as the basis for your robot  
  
// It assumes that the field control receiver is plugged into digital inputs 9 and 10  
  
// The code will sense the field settings and run your blocks shown below as appropriate  
  
// You should modify the code as indicated in the comments to insert your robot specific functions
```

