

### Sample Solutions – Assignment 5

1.) Problem #11 on p97.

The problem, in Martin's notation is:

Let  $V$  be a vector space and let  $T : V \rightarrow V$  be linear. Then  $T \circ T = T_0$  (the zero function which sends every vector to the zero vector) if and only if the image of  $T$  is a subset of the null space of  $T$ :  $\text{im } T \subseteq \text{nullsp } T$ .

**Proof:** ( $\Rightarrow$ ) Assume  $T \circ T = T_0$ . Let  $w \in \text{im } T$ . Then there is some  $v \in V$  for which  $T(v) = w$ . But then

$$T(w) = T(T(v)) = (T \circ T)(v) = T_0(v) = 0$$

by hypothesis. So  $T(w) = 0$  and  $w \in \text{nullsp } T$ . Since  $w$  was an arbitrary element of  $\text{im } T$ , this proves  $\text{im } T \subseteq \text{nullsp } T$ .

( $\Leftarrow$ ) Assume  $\text{im } T \subseteq \text{nullsp } T$ . To prove that the two functions  $T \circ T$  and  $T_0$  are equal, we show that they do the same thing to each vector in  $V$ . So let  $u$  be any vector in  $V$ . Then  $T(u)$  is obviously in  $\text{im } T$ . So, by hypothesis,  $T(u)$  also lies in  $\text{nullsp } T$ . That means that  $T(T(u)) = 0$ . So we have, for any  $u$ ,  $(T \circ T)(u) = 0$  which is the same as  $T_0(u)$ . Thus  $T \circ T = T_0$  as desired.

2.) Problem #7 on p107.

(a) We must show that, if  $A^2 = O$ , then  $A$  is not invertible. We will (reluctantly) use the method of proof by contradiction. We will contradict the fact that the zero matrix is not invertible. So let us suppose that  $A^2 = O$  and yet  $A$  is invertible. Then, multiply both sides on the left by  $A^{-1}$ , we find

$$A = IA = (A^{-1}A)A = A^{-1}(AA) = A^{-1}A^2 = A^{-1}O = O.$$

This is a contradiction: we cannot have  $A = O$  when  $A$  is invertible.

(b) We must show that, if  $AB = O$  and  $B$  is not the zero matrix, then  $A$  is not invertible. We will prove this by contrapositive. Suppose that  $A$  is invertible and  $AB = O$ . Then, multiplying both sides on the left by  $A^{-1}$ , we find

$$B = IB = (A^{-1}A)B = A^{-1}(AB) = A^{-1}O = O.$$

So, given that  $A$  is invertible, either  $B = O$  or  $AB \neq O$ .

3.) Let  $T : V \rightarrow V$  be a linear transformation from the real vector space  $V$  to itself. Let  $\lambda$  be a real number and consider the following subset of  $V$ :

$$W_\lambda = \{v \in V \mid T(v) = \lambda v\}.$$

Prove that  $W_\lambda$  is a subspace of  $V$ .

**Proof:** We will apply the Subspace Test. First, since  $T(0) = 0 = \lambda 0$ , we have  $0 \in W_\lambda$ . To show closure under addition, let  $u$  and  $v$  be any vectors in  $W_\lambda$ . Then  $T(u) = \lambda u$  and  $T(v) = \lambda v$ . So

$$T(u + v) = T(u) + T(v) = \lambda u + \lambda v = \lambda(u + v)$$

using the fact that  $T$  is linear, showing that  $u + v \in W_\lambda$ . Finally, we must establish that  $W_\lambda$  is closed under scalar multiplication. Let  $u \in W_\lambda$  and let  $c$  be any real number. Then

$$T(cu) = cT(u) = c(\lambda u) = \lambda(cu).$$

This proves that  $cu$  also lies in the eigenspace  $W_\lambda$ . So, by the Subspace Test, we conclude that  $W_\lambda$  is indeed a subspace of  $V$ .

4.) Parts (b), (d) and (f) of exercise #2 on p256-7.

(b) We are given the linear operator  $T : P_1(\mathbb{R}) \rightarrow P_1(\mathbb{R})$  with the rule

$$T(a + bx) = (6a - 6b) + (12a - 11b)x.$$

The given basis is  $\beta = \{3 + 4x, 2 + 3x\}$ . Let us write  $\beta = \{u_1, u_2\}$ . We compute

$$T(u_1) = T(3 + 4x) = -6 - 8x = (-2)u_1 + 0u_2$$

and

$$T(u_2) = T(2 + 3x) = -6 - 9x = 0u_1 + (-3)u_2.$$

So

$$[T]_\beta = \begin{bmatrix} -2 & 0 \\ 0 & -3 \end{bmatrix}$$

and YES,  $\beta$  is a basis of eigenvectors for  $T$  because this is a diagonal matrix.

(d) We are given the linear operator  $T : P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$  with the rule

$$T(a + bx + cx^2) = (-4a + 2b - 2c) + (-7a - 3b - 7c)x + (7a + b + 5c)x^2.$$

The given basis is  $\beta = \{x - x^2, -1 + x^2, -1 - x + x^2\}$ . Again, write  $\beta = \{u_1, u_2, u_3\}$ . We compute

$$T(u_1) = T(x - x^2) = 4 + 4x - 4x^2 = 0u_1 + 0u_2 + (-4)u_3,$$

$$T(u_2) = T(-1 + x^2) = 2 - 2x^2 = 0u_1 + (-2)u_2 + 0u_3$$

and

$$T(u_3) = T(-1 - x + x^2) = 3x - 3x^2 = 3u_1 + 0u_2 + 0u_3.$$

So

$$[T]_\beta = \begin{bmatrix} 0 & 0 & 3 \\ 0 & -2 & 0 \\ -4 & 0 & 0 \end{bmatrix}$$

and NO,  $\beta$  is NOT a basis of eigenvectors for  $T$  because this is not a diagonal matrix.

(f) We are given  $\mathsf{T} : \mathsf{M}_{2 \times 2}(\mathbb{R}) \rightarrow \mathsf{M}_{2 \times 2}(\mathbb{R})$  with the rule

$$\mathsf{T} \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = \begin{bmatrix} (-7a - 4b + 4c - 4d) & b \\ (-8a - 4b + 5c - 4d) & d \end{bmatrix}.$$

The given basis is

$$\beta = \{u_1, \dots\} := \left\{ \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \right\}.$$

Now

$$\mathsf{T}(u_1) = \mathsf{T} \left( \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \right) = \begin{bmatrix} -3 & 0 \\ -3 & 0 \end{bmatrix} = -3u_1,$$

$$\mathsf{T}(u_2) = \mathsf{T} \left( \begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix} \right) = \begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix} = u_2,$$

$$\mathsf{T}(u_3) = \mathsf{T} \left( \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} = u_3,$$

and

$$\mathsf{T}(u_4) = \mathsf{T} \left( \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \right) = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} = u_4.$$

So

$$[\mathsf{T}]_{\beta} = \begin{bmatrix} -3 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

and YES,  $\beta$  is a basis of eigenvectors for  $\mathsf{T}$ .

5.) Complete parts (b) and (d) of exercise #3 on p257.

(b) We first compute the characteristic polynomial

$$\chi_A(t) = \begin{vmatrix} -t & -2 & -3 \\ -1 & 1-t & -1 \\ 2 & 2 & 5-t \end{vmatrix} = -t^3 + 6t^2 - 11t + 6 = (1-t)(2-t)(3-t).$$

So the eigenvalues are 1, 2 and 3. Since the eigenvalues are distinct, we will be successful in finding a basis of eigenvectors (Corollary p261).

(ii) We easily row reduce  $A - \lambda I$  for  $\lambda = 1, 2, 3$  to find eigenspaces

$$\mathsf{W}_1 = \text{nullsp}(A - I) = \{(s, s, -s) \mid s \in \mathbb{R}\},$$

$$\mathsf{W}_2 = \text{nullsp}(A - 2I) = \{(s, -s, 0) \mid s \in \mathbb{R}\},$$

$$\mathsf{W}_3 = \text{nullsp}(A - 3I) = \{(s, 0, -s) \mid s \in \mathbb{R}\}$$

(iii) A basis of eigenvectors is given by the three columns of the matrix

$$Q = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 0 \\ -1 & 0 & -1 \end{bmatrix}.$$

(iv) The above matrix  $Q$  is invertible and  $Q^{-1}AQ$  is the diagonal matrix  $D$  with diagonal 1, 2, 3.

(d) We first compute the characteristic polynomial

$$\chi_A(t) = \begin{vmatrix} 2-t & 0 & -1 \\ 4 & 1-t & -4 \\ 2 & 0 & -1-t \end{vmatrix} = -t^3 + 2t^2 - t = (1-t)(1-t)(-t).$$

So the eigenvalues are 0, 1 and 1.

(ii) We row reduce  $A - \lambda I$  for  $\lambda = 0, 1$  to find eigenspaces

$$W_0 = \text{nullsp}(A) = \text{nullsp} \left( \begin{bmatrix} 1 & 0 & -1/2 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \right) = \{(s, 4s, 2s) \mid s \in \mathbb{R}\}$$

and

$$W_1 = \text{nullsp}(A - I) = \text{nullsp} \left( \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \right) = \{(s, s, s) \mid s \in \mathbb{R}\}.$$

(iii) A basis of eigenvectors does not exist because the second eigenspace is too small. is given by the three columns of the matrix

(iv) There are no such matrices  $Q$  and  $D$ .