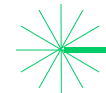


WORCESTER POLYTECHNIC INSTITUTE MECHANICAL ENGINEERING DEPARTMENT

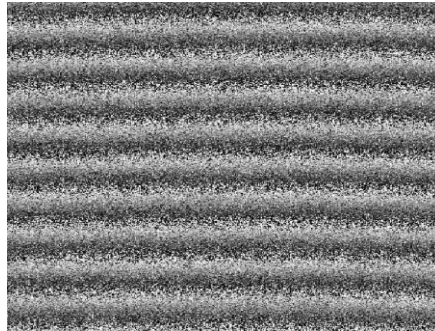
Optical Metrology and NDT
ME-593L, B'2011

Introduction: Phase Unwrapping
30 November 2011



Fringe-locus function $\text{mod}[2\pi]$: actual distributions

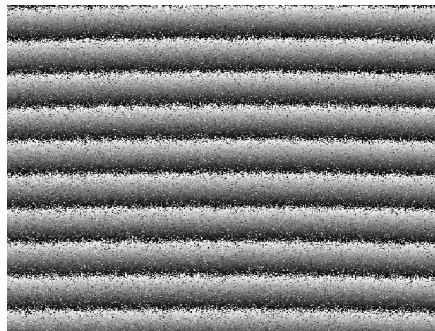
4-frames:



$$\Omega(u, v) = \text{atan} \left[\frac{I_4(u, v) - I_2(u, v)}{I_1(u, v) - I_3(u, v)} \right]$$

(a)

8-frames:



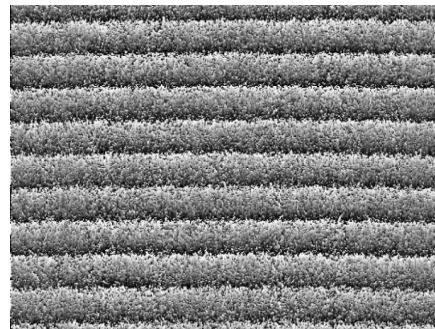
$$\Omega(u, v) = \text{atan} \left[-\frac{N(u, v)}{D(u, v)} \right]$$

$$N(u, v) = (I_1 - I_3)(I_2' - I_4') - (I_2 - I_4)(I_1' - I_3')$$

$$D(u, v) = (I_1 - I_3)(I_1' - I_3') + (I_2 - I_4)(I_2' - I_4')$$

(b)

1-frame,
FFT:



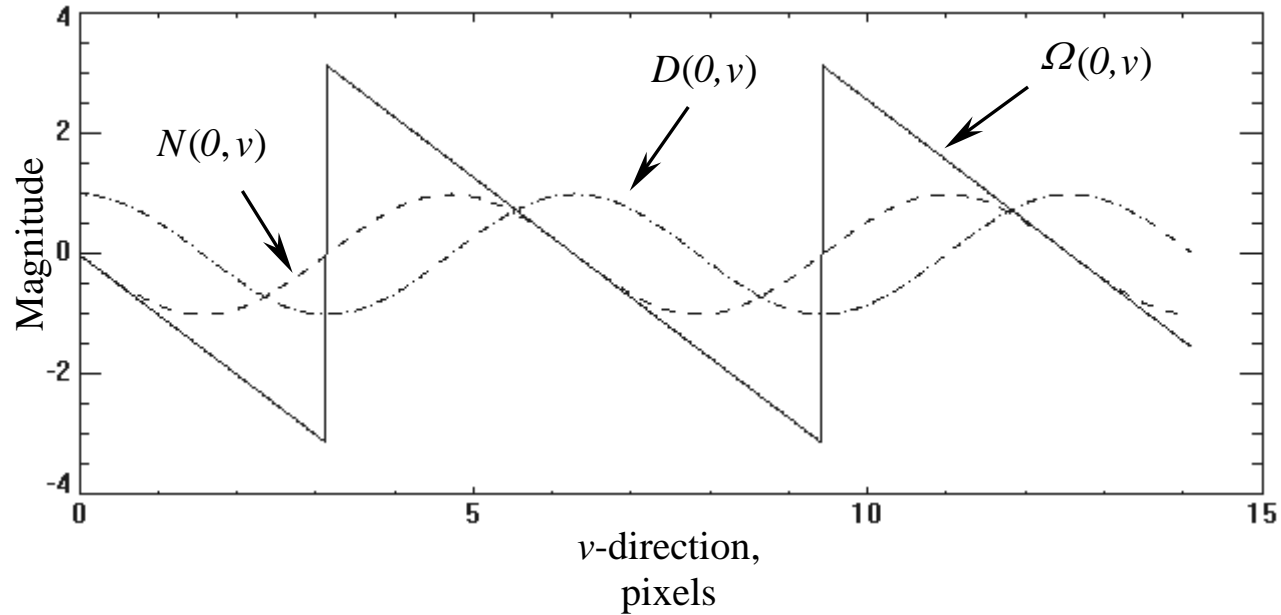
$$\Omega(u, v) = \text{atan} \left\{ \frac{\text{Im}[I_c(u, v)]}{\text{Re}[I_c(u, v)]} \right\}$$

(c)

Recovered optical phase

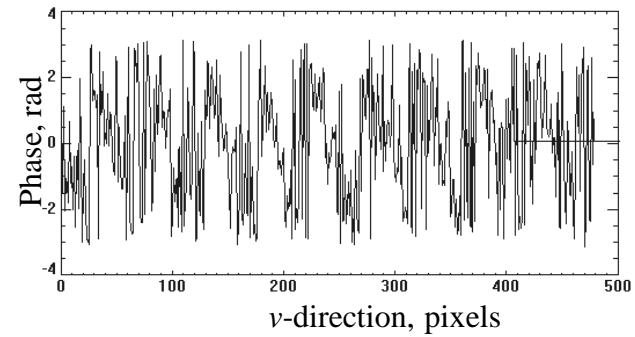
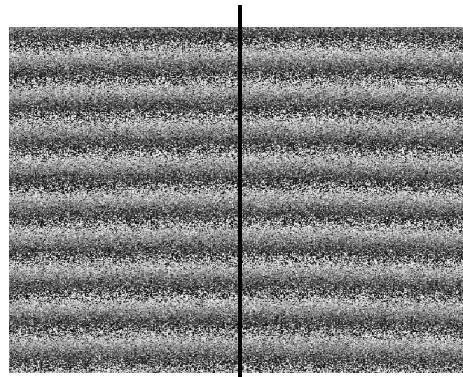
Fringe-locus function $\text{mod}[2\pi]$

Recovered wrapped phase

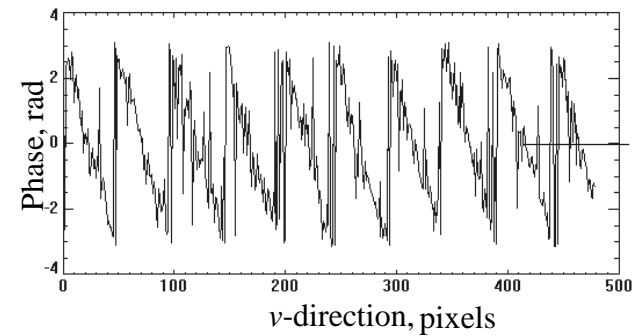
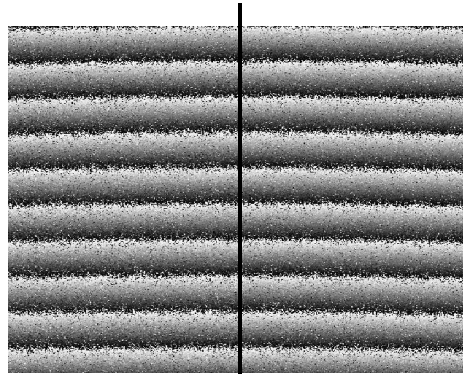


Fringe-locus function mod $[2\pi]$: actual distributions

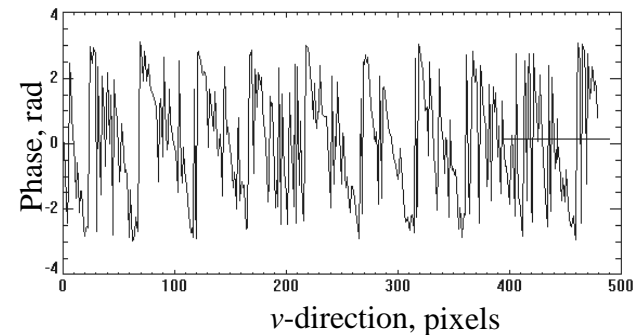
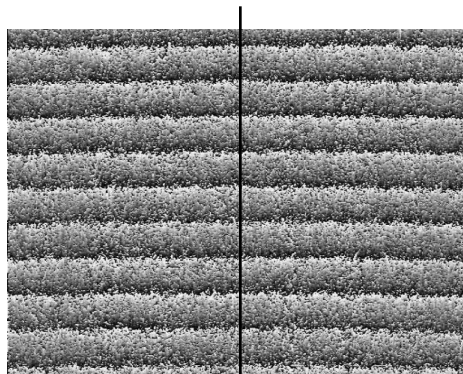
4-frames:



8-frames:



1-frame,
FFT:



Pre-processing: filtering (recommended but not necessary in phase unwrapping)

4-frames:
$$\Omega(u, v) = \text{atan} \left[\frac{I_4(u, v) - I_2(u, v)}{I_1(u, v) - I_3(u, v)} \right]$$

8-frames:
$$\Omega(u, v) = \text{atan} \left[-\frac{N(u, v)}{D(u, v)} \right]$$
$$N(u, v) = (I_1 - I_3)(I_2' - I_4') - (I_2 - I_4)(I_1' - I_3')$$
$$D(u, v) = (I_1 - I_3)(I_1' - I_3') + (I_2 - I_4)(I_2' - I_4')$$

1-frame,
FFT:
$$\Omega(u, v) = \text{atan} \left\{ \frac{\text{Im}[I_c(u, v)]}{\text{Re}[I_c(u, v)]} \right\}$$

Spatial filtering:

- Separate numerator (sine)
- Separate denominator (cosine)
- Filter numerator and denominator separately:
 - Low-pass filter
 - Median filter
 - Adaptive
 - Fourier
 - Other
- Phase re-evaluation

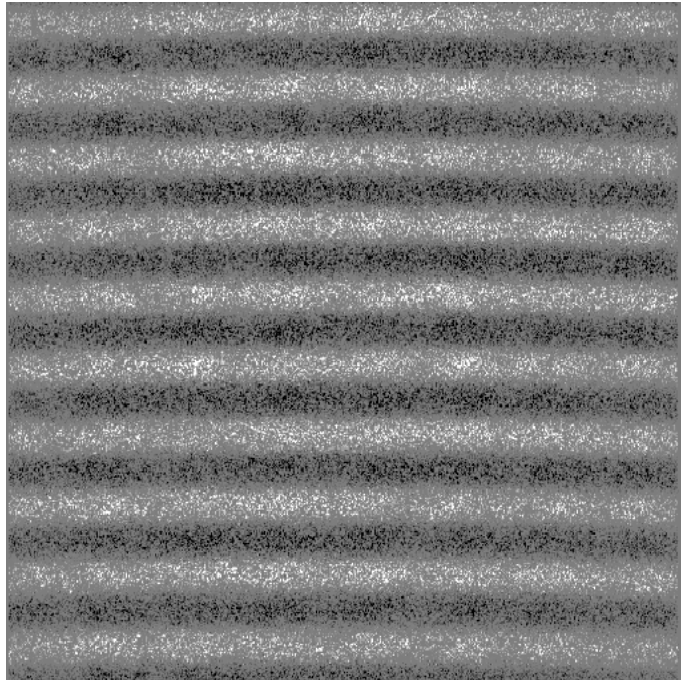
Pre-processing: filtering

Fourier filtering of sine/cosine images

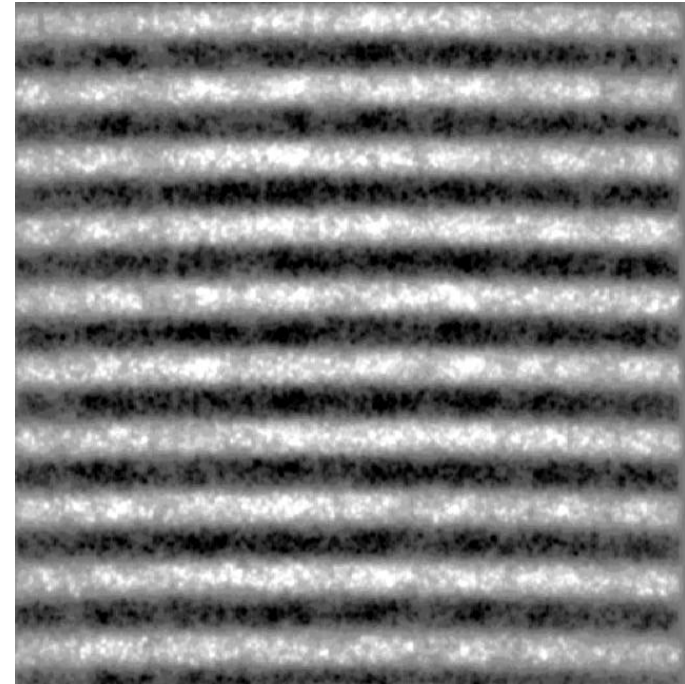
Convolution in the frequency domain: $Q_D^T(f_u, f_v) = Q_D(f_u, f_v) \cdot W_f(f_u, f_v)$

Inverse Fourier transformation: $Q'_D(m, n) = \mathcal{F}^{-1}\{Q_D^T(f_u, f_v)\}$

Original interferogram



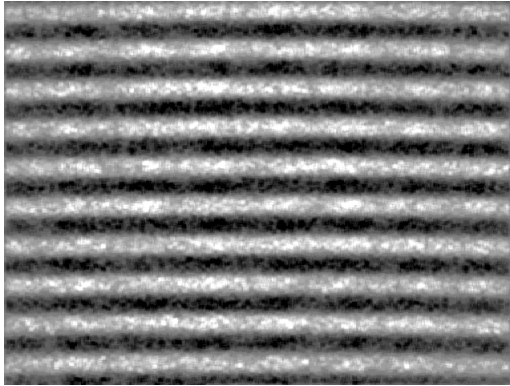
Filtered interferogram



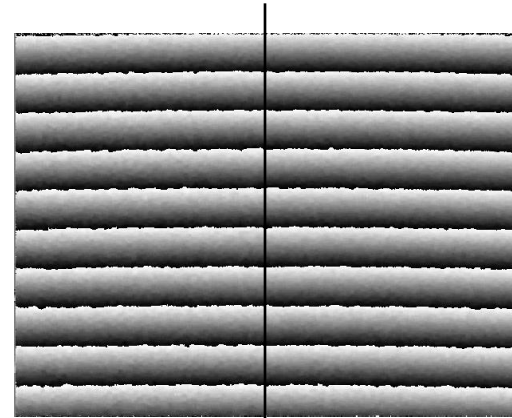
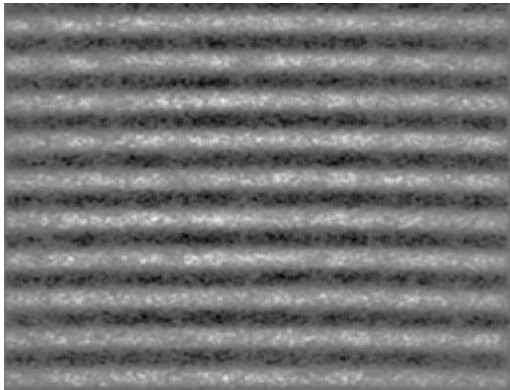
Pre-processing: filtering

Fourier filtering of sine/cosine images

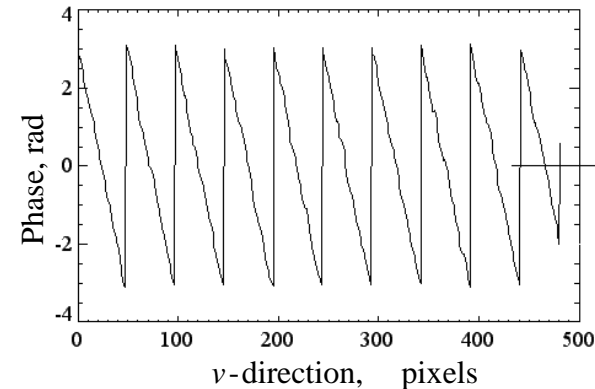
Filtered
sine image:



Filtered
cosine image:



Re-
evaluated
phase



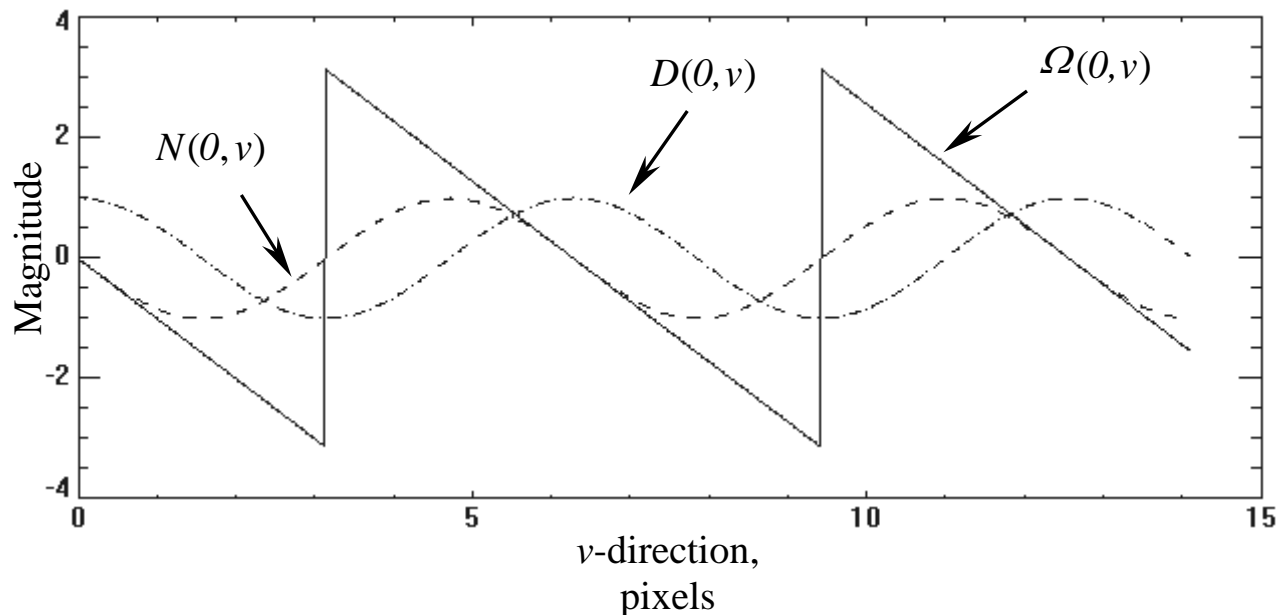
Phase unwrapping of phase mod[2π]

Wrapped phase: $\Omega = \Omega(u, v)$

→ Unwrapped phase: $U\{\Omega(u, v)\} = \Omega(u, v) + 2\pi N(u, v)$

$N(u, v) = \text{Round}(\text{fringe orders})$

Wrapped phase



Row-by-row / Column-by-column algorithm

Evaluate finite difference $\Delta\ell(u, v)$:

$$\Delta\ell(u, v) = \begin{cases} \Omega(u, v) - \Omega(u-1, v), & \text{row,} \\ \text{or} \\ \Omega(u, v) - \Omega(u, v-1), & \text{column} \end{cases}$$

Line unwrapping:

$$\Omega_c(u, v) = \begin{cases} \Omega(u, v) - C_d \cdot 2\pi & \text{if } \Delta\ell > \kappa \cdot 2\pi \\ \Omega(u, v) + C_d \cdot 2\pi & \text{if } \Delta\ell < -\kappa \cdot 2\pi \end{cases}$$

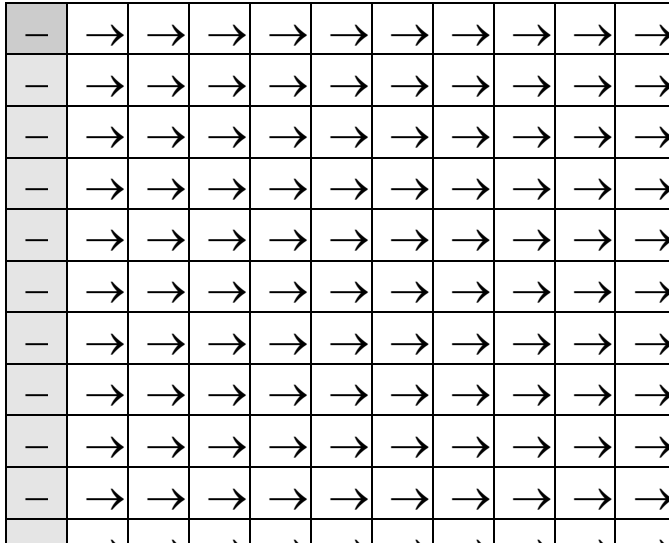
$C_d =$ signed integer

$\kappa < 1$, unwrapping threshold

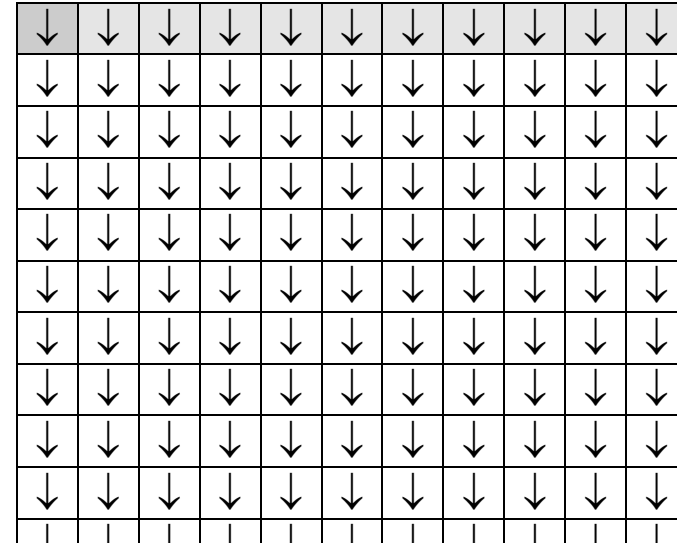


Row-by-row / Column-by-column algorithm

$\Omega(u_0, v_0) = \Omega_0$ (boundary condition)



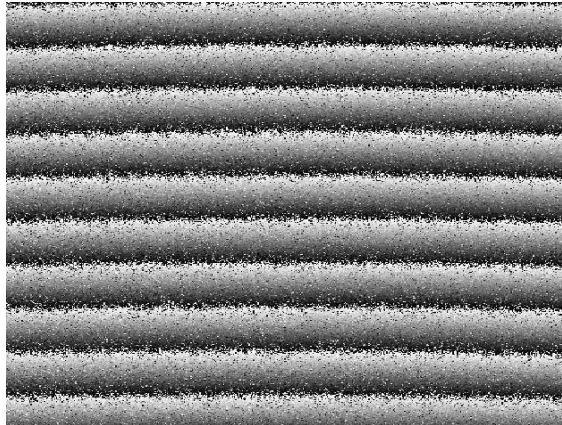
Row-by-row



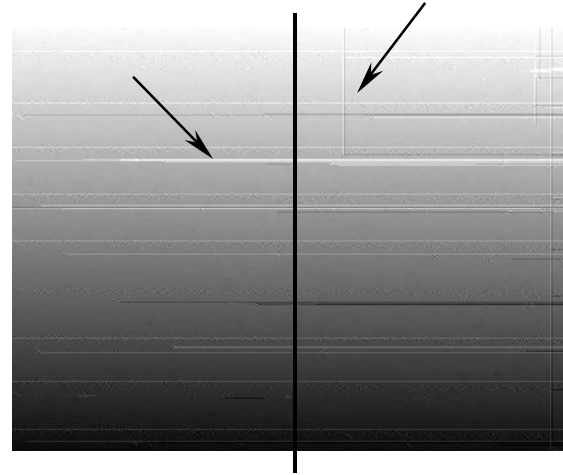
Column-by-column

Row-Column algorithm

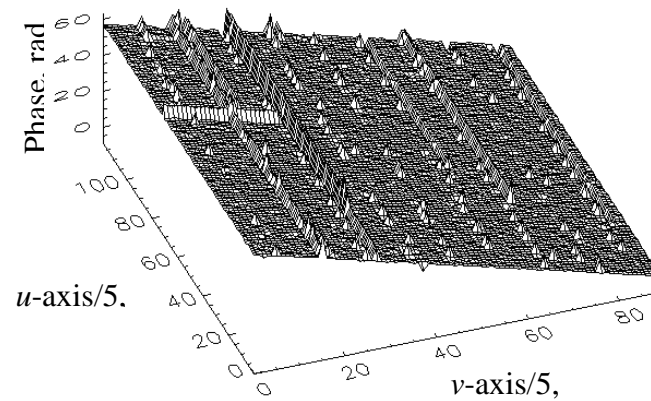
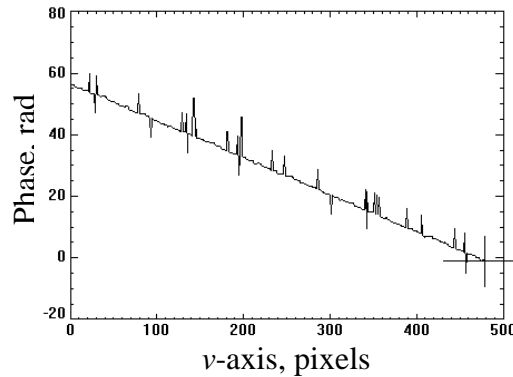
Unfiltered wrapped phase



Unwrapped phase

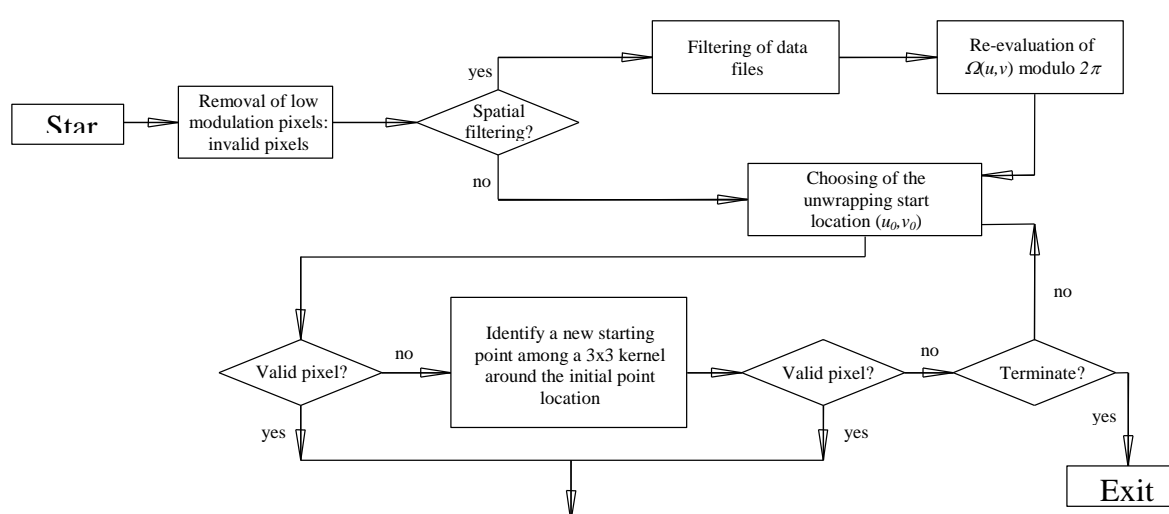


Phase discontinuities still present

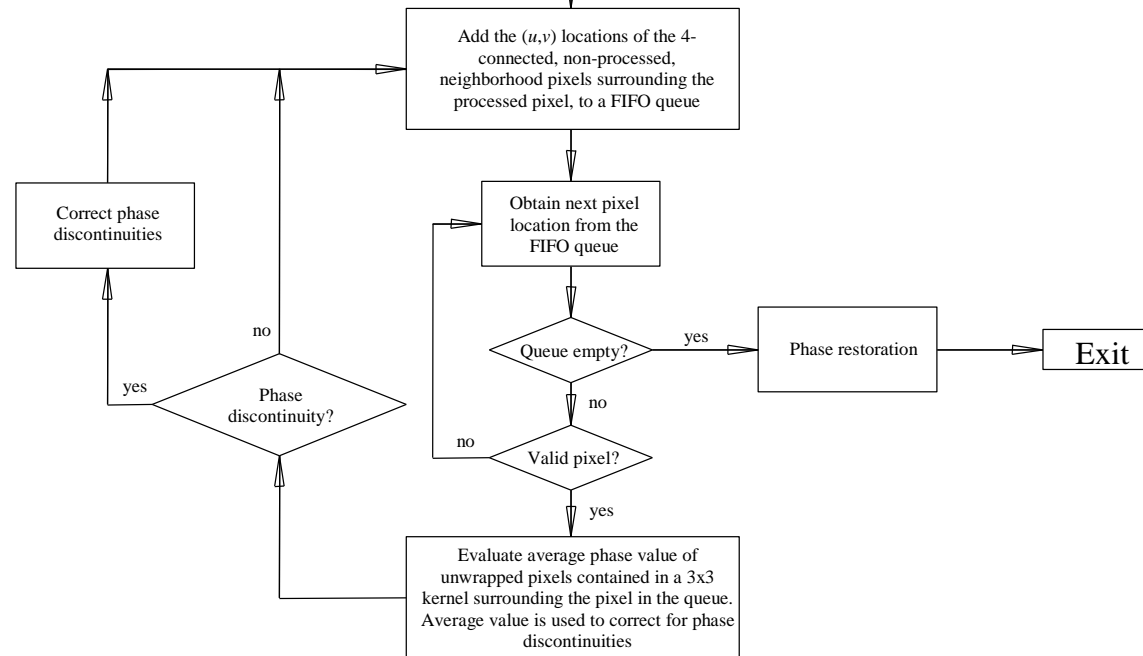


Edge following algorithm

Part I:

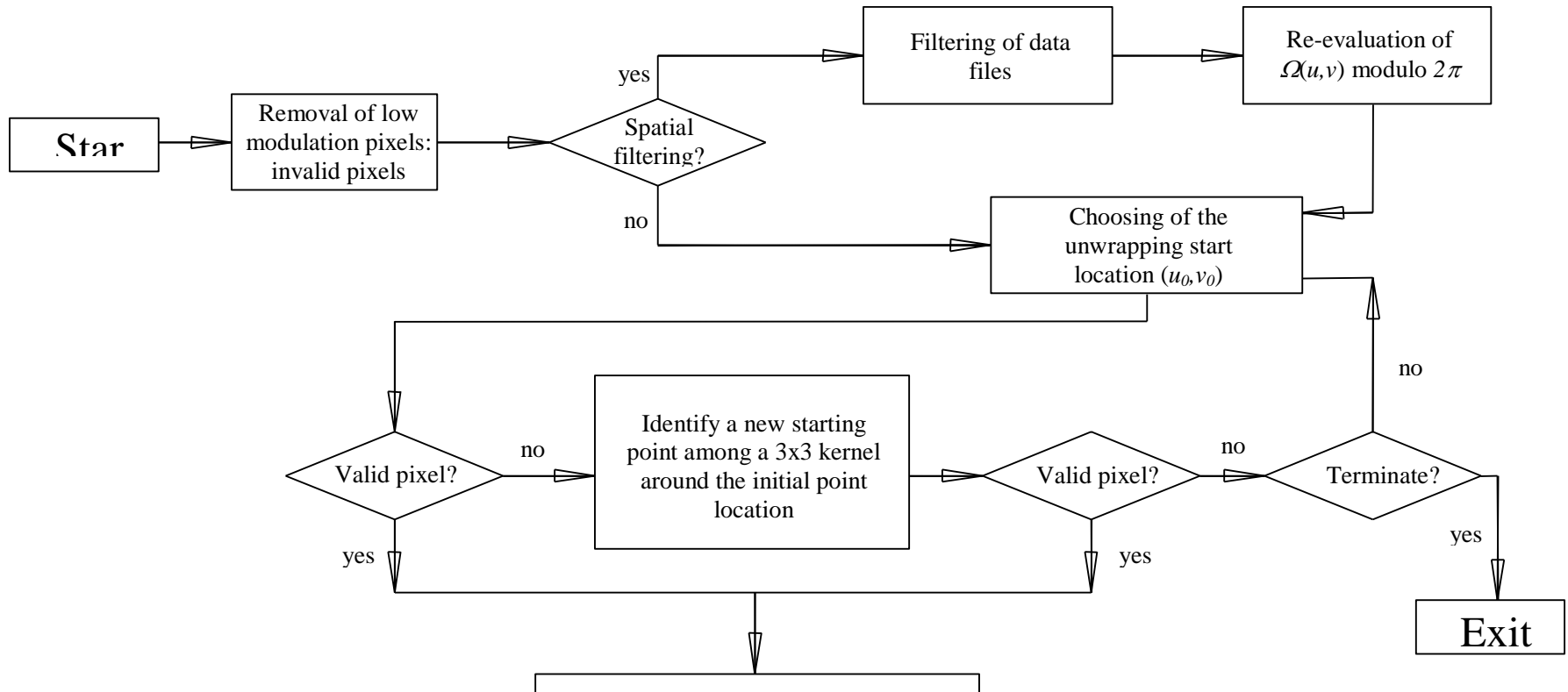


Part II:



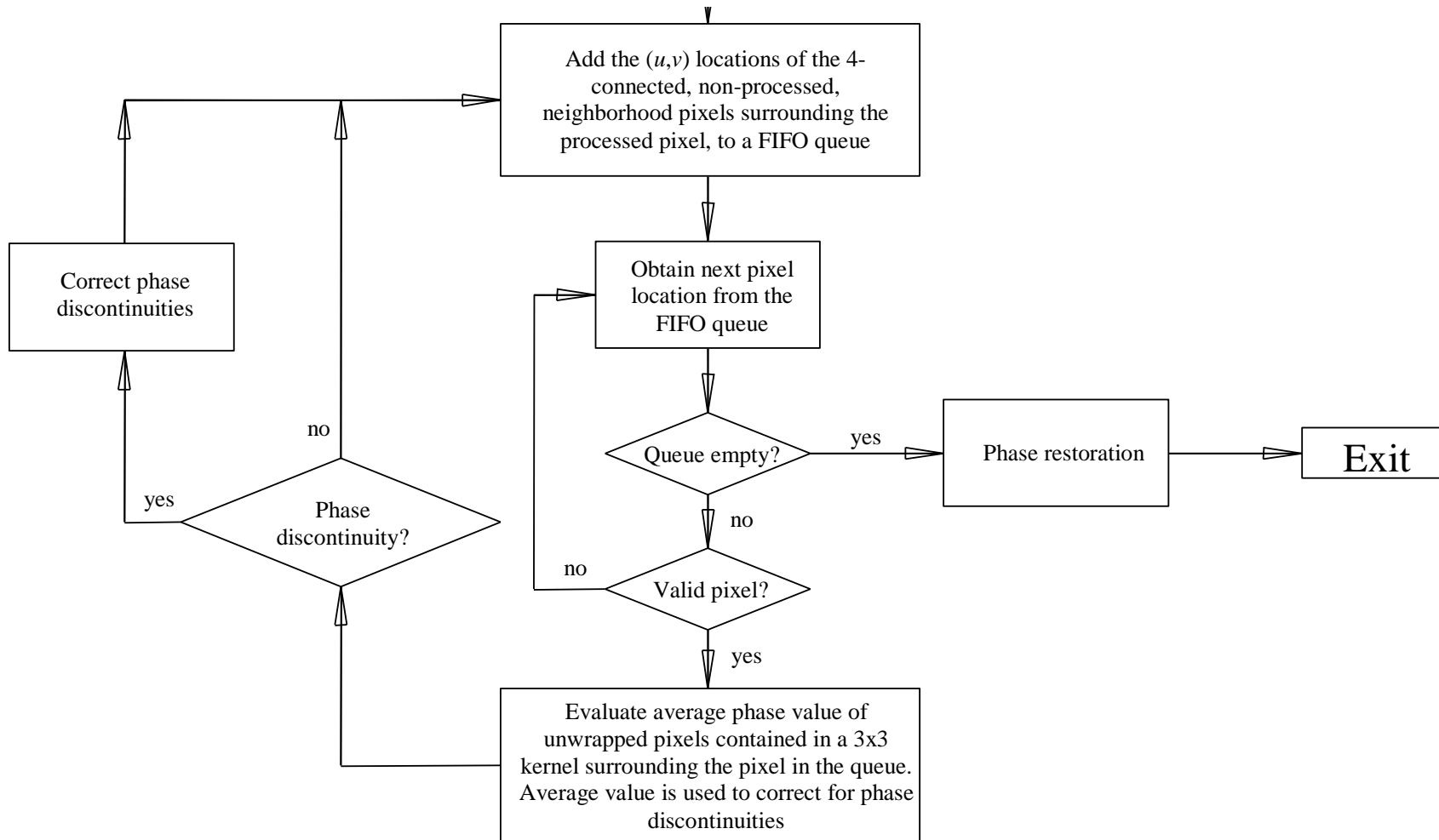
Edge following algorithm

Part I



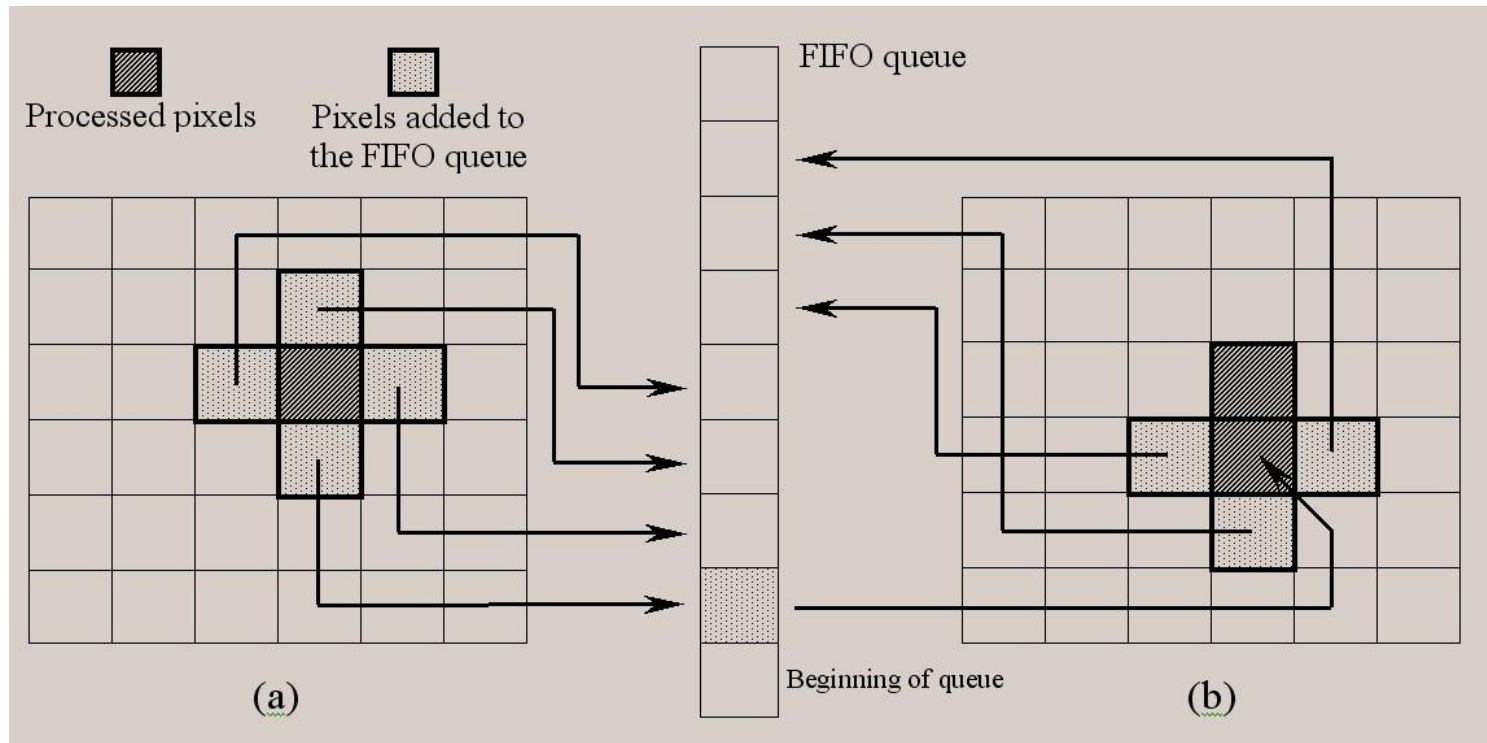
Edge following algorithm

Part II



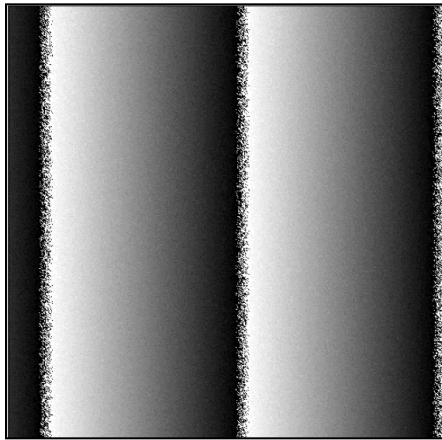
Edge following algorithm: FIFO queue

(a) 4 connected pixels to processed pixel are added to the queue, (b) the next pixel to be processed is taken from the queue and after processing, the unprocessed pixels contained in the 4 connected pixels surrounding the processed pixel are added to the queue.

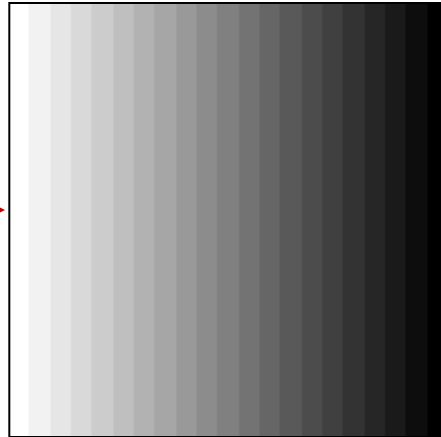


Example: interferogram with open-fringes

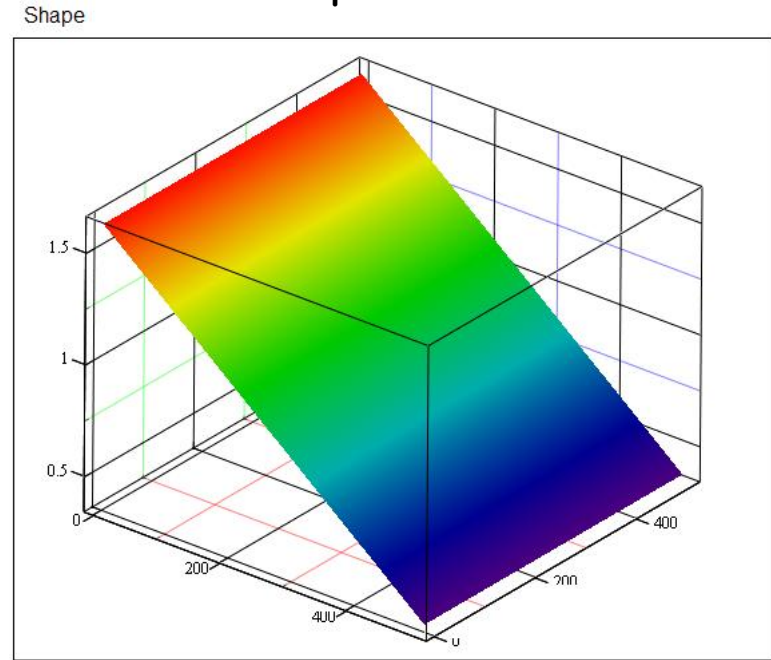
Wrapped phase



Unwrapped phase



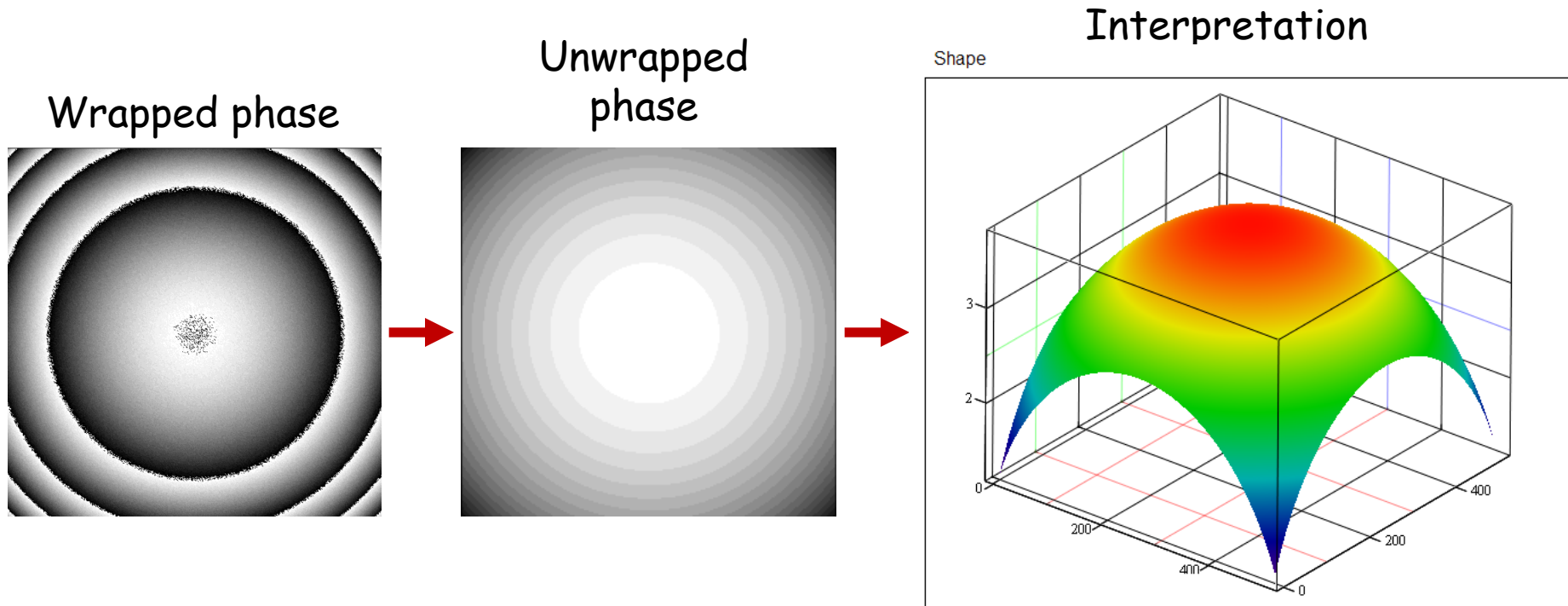
Interpretation



Need:

Camera calibration &
Sensitivity Vector

Example: interferogram with closed-fringes



Need:

Camera calibration &
Sensitivity Vector

Homework

Refer to homework assignment: "high-speed measurements on a canopy."

- 1) Develop software to unwrap phase $\text{mod}[\pi]$ and/or $\text{mod}[2\pi]$;
- 2) Apply phase unwrapper to the results obtained with the Fourier analysis of single images.

